Models 236/237 Source-Measure Units

Applications Manual



Contains Programming Examples



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Model 236 Source-Measure Unit Model 237 High Voltage Source-Measure Unit Applications Manual

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SAFETY PRECAUTIONS

The following safety precautions should be observed before using Model 236/237 Source Measure Units.

The Model 236/237 Source Measure Unit is intended for use by qualified personnel who recognize shock hazards and are familiar with the safety precautions required to avoid possible injury. Read over the operator's manual carefully before using the instrument.

Exercise extreme caution when a shock hazard is present. Lethal voltages may be present on the test fixture or the Source Measure Unit connector jacks. The American National Standards Institute (ANSI) states that a shock hazard exists when voltage levels greater than 30V RMS or 42.4V peak are present. A good safety practice is to expect that hazardous voltage is present in any unknown circuit before measuring.

Inspect the connecting cables, test leads, and jumpers for possible wear, cracks, or breaks before each use.

For maximum safety, do not touch the Source Measure Unit, test fixture, test cables or any other instruments while power is applied to the circuit under test. Turn off all power and discharge any capacitors before connecting or disconnecting cables or jumpers. Also, keep the test fixture lid closed while power is applied to the device under test. Safe operation requires the use of the lid interlock.

Do not touch any object which could provide a current path to the common side of the circuit under test or power line (earth) ground. Always make measurements with dry hands while standing on a dry, insulated surface capable of withstanding the voltage being measured.

Do not exceed the maximum signal levels of the test fixture, as shown on the rear panel and as defined in the specifications and operation section of the instruction manual.

Connect the screw of the test fixture to safety earth ground using #18 AWG or larger wire (supplied accessory).

Instrumentation and accessories should not be connected to humans.

The symbol on a Model 237 indicates that 1000V or more may be present on the terminals. Refer to the Model 236/237 Operator's Manuals for detailed operation information.

When a Model 236/237 is programmed for remote sensing, hazardous voltage may be present on the SENSE and OUT-PUT terminals when the unit is in operate regardless of the programmed voltage or current. To avoid a possible shock hazard, always turn off all power before connecting or disconnecting cables to the Source Measure Unit or the associated test fixture.

PREFACE

This Applications Manual is intended to demonstrate a number of key applications for the Models 236 and 237 Source Measure Units. Typical applications covered in this manual include: diode forward characteristics, common-emitter and common-source characteristics, current gain, threshold tests, and Gummel plots. Additional applications include using Source Measure Units with other instruments such as voltage sources, current source, and electrometers. Finally, several switching system examples are included to demonstrate how to increase the versatility of a Source Measure Unit test system.

Each application includes an example program written in Hewlett-Packard BASIC 4.0 to demonstrate programming principles, and all applications are intended to run on Hewlett-Packard Series 200 and 300 computers. The programs can be converted to run on IBM PC and compatible computers using Microsoft QuickBASIC, as outlined in Appendix A.

Before using these applications, you should become thoroughly familiar with the operation of your Model 236 or 237 Source Measure Unit. Refer to the Model 236/237 Operator's Manual, supplied with the instrument, for detailed information on operation.

PROGRAM SYNOPSIS

A brief description of each example program in this manual is given below. Programs 1, 2, 3, 8, and 23 require only one Model 236 or 237 to operate. The remainder of the programs require two or more Source Measure Units, or one Source Measure Unit and at least one additional instrument such as a voltage source, current source, scanner, or switching matrix.

Program 1: Resistor Voltage Coefficient Test Program. This program requires only one Source Measure Unit, and it is intended to test the voltage coefficient of resistors. User-programmed voltage test values are used, and the current through the resistor under test is measured by the Source Measure Unit. The resistance and values and voltage coefficient are computed by the program. (pp. 2-2 to 2-7)

Program 2: Capacitor Leakage Test Program. Program 2 allows you to test leakage current values of capacitors using a single Source Measure Unit. User-input test voltage and delay values are used, and the program displays both leakage current and leakage resistance. (pp. 2-8 to 2-11)

Program 3: Diode Characterization. Program 3 determines the variability of forward voltage, V_F , as the forward current, I_F , is varied across a certain range. Once test data are compiled, a plot of V_F vs. I_F is generated on the computer CRT. (pp. 2-12 to 2-16)

Program 4: Common-emitter Characteristics. This program performs standard common-emitter characteristic tests of a typical small-signal NPN bipolar transistor. Two Model 236 or 237 Source Measure Units are required to run the program, with one unit sweeping I_B , and the second unit sweeping V_{CE} and measuring I_C . A total of five I_B values are used, and, at the conclusion of the test, a plot of all five I_C vs. V_{CE} curves is generated. (pp. 3-3 to 3-7)

Program 5: Gummel Plot. Program 5 provides a Gummel plot of an NPN bipolar transistor with $log(I_B, I_C)$ plotted vs. V_{BE} . Two Model 236 or 237 Source Measure Units are required; the first unit sweeps V_{BE} and measures I_B , and the second unit sources V_{CE} and measures I_C . (pp. 3-8 to 3-12)

Programs 6A and 6B: Dc Current Gain. Programs 6A and 6B allows dc current gain testing of an NPN transistor using two Model 236 or 237 Source Measure Units. One Source Measure Unit provides the base current, I_B, and the second unit sources V_{CE} and measures I_C. Program 6A automatically sets the base current to the correct value based on user-input target I_C. Program 6B demonstrates a high-speed current gain test method using special characteristics of the Models 236 and 237. (pp. 3-13 to 3-20)

Program 7: Differential Current Gain. This program allows you to enter two incremental base current values to determine the differential current gain of NPN bipolar transistors. The result approximates the ac current gain of the devices. One unit supplies the base current, and the second unit sources V_{CE} and measures I_C at each base current value. (pp. 3-21 to 3-23)

Program 8: Transistor Leakage Current. Using one Source Measure Unit, Program 8 measures the leakage current, I_{CEO}, as the reverse bias voltage, V_{CEO} is varied. The program generates an I_{CEO} vs. V_{CEO} plot after data are collected. (pp. 3-24 to 3-28)

Program 9: Common-Source Characteristics. This program uses two Source Measure Units to generate FET common-source characteristics. The first Source Measure Unit is used to sweep V_{GS} , and the second unit is used to sweep V_{DS} and measure I_D . Curves at five different V_{GS} values are generated by the program. (pp. 4-2 to 4-7)

Program 10: Transconductance vs. Gate Voltage. Program 10 generates a plot of g_{fs} vs. V_{GS} for a typical FET. Transconductance is computed from small, incremental changes in V_{GS} and the resulting changes in I_D . Two Model 236 or 237 Source Measure Units are required to use this program. (pp. 4-8 to 4-12)

Program 11: Transconductance vs. Drain Current. This program generates a plot of V_{GS} vs. I_D for an FET. Again, g_{fs} is computed from incremental V_{GS} and I_D values, and two Source Measure Units are required. (pp. 4-13 to 4-16)

Programs 12A and 12B: Threshold Voltage. Program 12A allows you to determine the threshold voltage of a typical FET at a specified drain current value. Two Source Measure Units are required for the program which includes an iterative search for target I_D . Program 12B demonstrates the self-bias threshold test, which is much faster, and showcases some special capabilities of the Models 236 and 237. (pp. 4-17 to 4-24)

Program 13: Substrate Current vs. Gate Voltage. Three Source Measure Units are required for Program 12, which generates a plot of substrate current, I_{SB} , vs. gate voltage, V_{GS} . One unit sweeps V_{GS} , the second unit sources V_{DS} , and the third unit sources V_{SB} and measures I_{SB} . (pp. 5-4 to 5-8)

Program 14: Common-source Characteristics with Source Measure Unit Substrate Bias. Program 14 adds substrate-bias programming for a third Source Measure Unit to a common-source characteristic test program. The program generates a plot of I_D vs. V_{DS} at five V_{GS} values. (pp. 5-9 to 5-14)

Program 15: Common-source Characteristics with Voltage Source Substrate Bias. Program 15 uses a Model 230 Voltage Source to provide substrate bias for the device under test. Two Model 236 or 237 Source Measure Units are also required to run the program, which generates I_D vs. V_{DS} curves at five different V_{GS} values. (pp. 5-15 to 5-19)

Program 16: Common-emitter Characteristics with Voltage Source Substrate Bias. Program 16 uses a Model 230 Voltage Source to provide substrate bias when measuring common-emitter characteristics. Two Source Measure Units are required in addition to the voltage source to run this program, which generates I_C vs. V_{CE} curves at five I_B values. (pp. 5-20 to 5-24)

Program 17: Common-emitter Characteristics using Current Source. Program 17 is one of several programs that demonstrate techniques for using a Source Measure Unit with other instruments. In this instance, a Model 220 Current Source is used to sweep the base current under program control, while a Model 236 or 237 Source Measure Unit is required to sweep V_{CE} and measure I_c. The program generates I_c vs. V_{CE} curves at five different I_B values. (pp. 6-1 to 6-6)

Program 18: Common-source Characteristics using Electrometer. This program utilizes a Model 617 Electrometer to sweep V_{DS} under program control and to measure I_D . A Source Measure Unit is necessary to sweep V_{CS} , and the program generates I_D vs. V_{DS} curves at five V_{CS} values. (pp. 6-7 to 6-12)

Program 19: Power Transistor Testing. Program 19 demonstrates using a Model 228A Voltage/Current Source in conjunction with a Source Measure Unit to test power transistor current gain. The Source Measure Unit is used to provide base current, while the Model 228A Voltage/Current Source is used to source V_{CE} and to measure I_c. (pp. 6-13 to 6-18)

Program 20: Dc Current Gain with Scanning. Program 20 demonstrates using a Model 705 Scanner to test a number of DUTs with one test system. Two Model 7058 Low Current Scanner Cards and two Source Measure Units are also required for the program, which can test the current gain of up to ten transistors. (pp. 7-1 to 7-7)

Program 21: Resistivity Test Program. Program 21 demonstrates techniques for determining the resistivity of devices. In addition to a Model 236 or 237 Source Measure Unit, the program also requires a Model 705 Scanner equipped with a Model 7152 Low Current Matrix Card. Following measurement, the program automatically calculates and displays resistivity values. (pp. 7-7 to 7-14)

Program 22: Using a Switching Matrix to Test Transconductance. This program uses a Model 707 Switching Matrix and a Model 7072 Semiconductor Matrix Card to demonstrate programming principles associated with matrix operation. In addition to the switching matrix, two Model 236 or 237 Source Measure Units are required for the program, which tests for and calculates the transconductance of one of three selected DUTs. (pp. 7-14 to 7-23)

Program 23: Binary Transfer Diode Characterization Program. Program 23 tests the forward characteristics of typical diodes using one Model 236 or 237 Source Measure Unit. The program demonstrates how to optimize measurement speed by using the binary data format to speed up IEEE-488 bus data transmission. Once data are taken, the program generates a V_F vs. I_F plot on the computer CRT. (pp. 8-3 to 8-9)

Program 24: Binary Transfer Common-emitter Program. This program shows binary transfer methods as applied to common-emitter characteristic testing. Two Model 236 or 237 Source Measure Units are required by the program, with one unit sweeping I_B , and the second unit sweeping V_{CE} and measuring I_C . The program generates I_C vs. V_{CE} plots for five I_B values after device testing is complete. (pp. 8-10 to 8-15)

Program 25: Self-bias Threshold Tests with Plotting and Binary Transfer. This program demonstrates techniques for plotting V_T vs. I_D using the self-bias method for threshold measurement. (pp. 8-16 to 8-22)

Program 26: Log Sweep Threshold Test with Plotting: Program 26 performs essentially the same type of test as Program 25 with modifications to generate and plot a log sweep for a wider range of test currents. (pp. 8-16 to 8-23)

IBM-PC/QuickBASIC Programs (Appendix A)

Program A-1: Diode Characterization. Program A-1 determines the variability of forward voltage, V_F , as the forward current, I_F , is varied across a certain range. Once test data are compiled, a plot of V_F vs. I_F is generated on the computer CRT.

Program A-2: Transistor Leakage Current: Using one Source Measure Unit, Program A-2 measures the leakage current, I_{CEO} , as the reverse bias voltage, V_{CEO} is varied. The program generates an I_{CEO} vs. V_{CEO} plot after data are collected.

Program A-3: Common-Emitter Characteristics. This program performs standard common-emitter characteristic tests of a typical small-signal NPN bipolar transistor. Two Model 236 or 237 Source Measure Units are required to run the program, with one unit sweeping I_B , and the second unit sweeping V_{CE} and measuring I_C . A total of five I_B values are used, and, at the conclusion of the test, a plot of all five I_C vs. V_{CE} curves is generated.

Program A-4: Common-Source Characteristics. This program uses two Source Measure Units to generate FET common-source characteristics. The first Source Measure Unit is used to sweep V_{GS} , and the second unit is used to sweep V_{DS} and measure I_D . Curves at five different V_{GS} values are generated by the program.

Program A-5: Log Sweep Threshold Test with Plotting. Program A-5 performs the self-bias threshold test and plots a log sweep of the results.

Program A-6: Gummel Plot. Program A-6 provides a Gummel plot of an NPN bipolar transistor with log (I_B , I_C) plotted vs. V_{BE} . Two Model 236 or 237 Source Measure Units are required; the first unit sweeps V_{BE} and measures I_B , and the second unit sources V_{CE} and measures I_C .

HOW TO USE THIS MANUAL

Outlines the overall system configuration and computer software required to run the example programs in this manual.

SECTION 1

General Information

Two-terminal Device Tests

Describes typical test procedures for two-terminal devices such as high-megohm resistors, diodes, and capacitors.

Details typical bipolar transistor tests such as common-emitter characteristics and Gummel plots.

Covers typical FET tests such as common-source characteristics and transconductance tests.

Describes using a Source Measure Unit or separate voltage source to provide substrate bias for semiconductor tests.

Discusses using Source Measure Units with other types of instruments such as current sources and electrometers.

SECTION 6 Using Source Measure Units with Other Instruments

Outlines methods to add scanner and matrix switching capabilities to a Source Measure Unit test system to increase system versatility.

Describes ways to maximize data throughput in a Source Measure Unit test system by using such features as binary data transfer.

Optimizing Measurement Speed

Source Measure Unit Test System

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SECTION 1 General Information

1.1 INTRODUCTION

The following paragraphs discuss the overall hardware and software configuration of the system necessary to run the example applications programs in this manual.

1.2 HARDWARE CONFIGURATION

1.2.1 System Configuration

Figure 1-1 shows the overall hardware configuration of a typical Source Measure Unit test system. The various components in the system perform the following functions:

Model 236/237 Source Measure Units: Each Model 236/237 Source Measure Unit can source voltage and simultaneously measure current, or source current and simultaneously measure voltage. One unit is necessary to run two-terminal device tests, while two units are required to run the bipolar transistor and FET tests. If programmable substrate bias is required, a third Source Measure Unit or a programmable voltage source will be necessary.

Model 8006 Test Fixture: The test fixture is the interface between the DUT (device under test). The Model 8006 includes sockets for axial-component, TO package, and 24-pin DIP package devices.

Computer: A Hewlett-Packard 9000 Series 200 or 300 computer equipped with an HP-IB interface controls the test system. An HP BASIC language processor card, installed in an IBM-PC, AT or compatible computer, can also be used.

Connecting Cables: Model 7078-TRX-3 triax cables are recommended for making connections between the Source Measure Units and the test fixture. In addition, IEEE-488 cables will be necessary to connect the Source Measure Units to the IEEE-488 (HP-IB) bus of the computer. Shielded IEEE-488 cables such as the Model 7007 are recommended for this application.

1.2.2 Remote/Local Sensing Considerations

In order to simplify test connections, most applications in this manual use local sensing for the Source Measure Units. Local sensing requires connecting only two cables between the Source Measure Units and the test fixture (OUTPUT HI and OUTPUT LO). Also, the appropriate jumpers between the test fixture signal panel and the component test module must be installed.

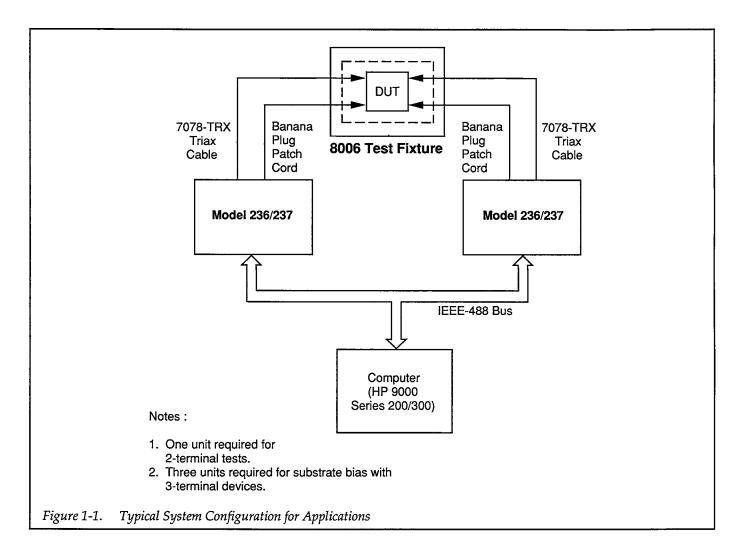
To optimize accuracy, you should use remote sensing in any of the applications (remote sensing is recommended for optimum accuracy with currents above 1mA). To use remote sensing, connect SENSE HI and SENSE LO to the test fixture, and add the necessary jumpers to the DUT. With this configuration, SENSE HI appears on the center conductor of the corresponding triax cable, and SENSE LO appears on the center conductor of the OUTPUT/ SENSE LO triax cable. See Section 2 of the Model 236/237 Operator's Manual for complete details on test connections.

WARNING

When a Model 236/237 is programmed for remote sensing, hazardous voltage may be present on the SENSE and OUTPUT terminals when the unit is in operate regardless of the programmed voltage or current. To avoid a possible shock hazard, always turn off all power before connecting or disconnecting cables to the Source Measure Unit or the associated test fixture.

In addition to the different connecting scheme, you must modify the corresponding program by changing the "O0X" command string (local sensing) to "O1X" (local sensing). For example, the command string,

OUTPUT 716; "O0X" ! Local sensing



should be changed to:

OUTPUT 716; "O1X" ! Remote sensing

1.3 SOFTWARE CONFIGURATION

1.3.1 Programming Language

All the programming examples in this manual are written in Hewlett-Packard BASIC 4.0 (upward-compatible versions such as BASIC 5.0 or 5.1 can also be used). This programming language was chosen for these examples for two reasons: (1) its easy-to-understand syntax, and (2) its versatility in controlling the IEEE-488 bus. In addition to BASIC, you must have the proper binaries (including graphics binaries) loaded into the computer. See the computer documentation for complete details.

1.3.2 Example Programs

Table 1-1 summarizes the example programs included in this manual. Note that recommended devices are also summarized in this table. Program modification will probably be required for devices with different characteristics.

Keep in mind that these example programs are presented only as examples, and they may not suit your particular applications. Also, a limited amount of error checking is incorporated into the programs, so care should be taken not to damage any device being tested. However, hopefully many of these example programs will serve as a base or model toward other more complex, applicationsspecific programs.

WARNING

Modifying the example programs to allow voltages greater than ±42V may create a

shock hazard. Connect interlock circuits before use, and connect the fixture screw to safety earth ground using #18 AWG minimum wire before using the programs.

Those who wish to run these programs but do not want to bother typing them in may obtain a diskette from the Keithley Instruments, Inc. Applications Department.

1.3.3 **Graphics Routines**

Graphics routines incorporated into many of the programs will plot simple graphs on the computer screen. You can modify the program to generate hard copy graphs on an HPGL plotter instead by changing the PLOTTER IS CRT, "INTERNAL" statement to read PLOTTER IS 705,"HPGL". Those with a bit-mapped graphics compatible printer can also dump graphics plots to the printer by using the DUMP GRAPHICS command, or use the corresponding computer key on those keyboards so equipped.

Program #	Description	Recommended Device*	Paragraph
1	Voltage coefficient	10GΩ-100GΩ	2.4
2	Capacitor leakage	0.01-1µF	2.5
3**	Diode V _F vs. I	1N4148	2.6
4**	$I_{\rm CVS}$. $V_{\rm CE}$ @ $I_{\rm B}$	2N5089 NPN	3.4
5**	Gummel plot	2N5089 NPN	3.5
6A/6B	Dc current gain	2N5089 NPN	3.6
7	Differential gain	2N5089 NPN	3.6
8**	Transistor ICEO	2N3904 NPN	3.7
9**	IDVS. VDS @ VGS	2N4392 JFET	4.4
10	gfs vs. VGS	2N4392 JFET	4.5
11	gfs vs. ID	2N4392 JFET	4.5
12A/12B**	Threshold voltage, V _T	User defined	4.6
13	ISB VS. VGS	TG-51	5.4
14	Unit substrate bias	User defined	5.4
15	V source substrate bias (FET)	User defined	5.5
16	V source bias (bipolar)	User defined	5.5
17	Unit/current source	2N5089 NPN	6.2
18	Unit/electrometer	2N4392 JFET	6.3
19	Power transistors	MJE240	6.4
20	Scanner/Unit, multiple DUTs	2N5089 NPN	7.2
21	Resistivity using matrix	User defined	7.3
22	Unit/matrix switching system	User defined	7.4
23	Diode Test, Binary Transfer	1N4148	8.3
24	Common-emitter, Binary Transfer	2N5089	8.4
25	Self-bias threshold with plotting	Enhancement/depletion FET	8.5
26	Log sweep threshold with plotting	Enhancement/depletion FET	8.5

Table 1-1. Example Program Summary

Devices recommended for use with example programs as written. Program modification may be required for use with DUTs having different characteristics. ** IBM-PC/QuickBASIC versions of these programs are discussed in Appendix A.

1.3.4 Factory Initialization

As written, the example programs assume that each Source Measure Unit is configured for factory initialization parameters. To ensure that these programs run properly, it may be necessary to return each Source Measure Unit to the factory initialized conditions. To do so from the front panel, use the MENU button to SELECT FACTORY INIT. You can also modify each program to send a "J0X" command to each instrument at run time. This command should be placed immediately after the instrument is placed in remote, but before the unit is programmed for any other operating modes. An initialization command should be sent separately to each instrument. An example of a partial listing is shown below.

	•••	
30	REMOTE 716	! Put Unit #1 in remote
35	OUTPUT 716;"J0X"	! Return Unit #1 to fac- tory init.
40	OUTPUT 716;"F0,0X"	! Source V, DC mode.
100	REMOTE 717	! Put Unit #2 in remote.
105	OUTPUT 717;"J0X"	! Return Unit #2 to fac- tory init.
110	OUTPUT 717;"F1,1X"	! Source I, sweep mode.
	•••	

1.3.5 General Programming Considerations

The following paragraphs outline a number of factors to consider when using the example programs or when writing your own programs to perform various tests.

Ranging

When using autoranging measure with sweeps, it is better to program a sweep that will result in down-range changes because upranging causes the instrument to first go into compliance and then work its way down. Programming sweeps in this manner will result in faster sweeps, all other factors being equal. Some types of tests, however, may be subject to hysteresis and should be programmed to go only in one direction.

For a similar reason, the measurement range of a Source Measure Unit that is used only as a source should be programmed for a suitable fixed range to avoid autoranging that could slow down the overall measurement.

One-shot Triggering

When a Model 236/237 is in a one-shot trigger mode, it will not return to the bias value after a sweep until it receives another trigger stimulus. Most of the example programs do not include this trigger, so you might wish to add a line to the programs to do so. For example, if a unit is programmed for trigger on GET, the following typical programming line could be added to return the instrument to the bias condition:

455 TRIGGER 716

Line Cycle Integration

Many examples program the units for line cycle integration using the "S2" command, which assumes that the instrument is being used on a 60Hz power line frequency. Those who are using the units on 50Hz should change any "S2" commands to "S3", which will correctly program the instrument for 50Hz line cycle integration.

When Is My Sweep Finished?

The best way to determine when a sweep is done is to program the instrument to generate an SRQ on sweep done, and then wait for the SRQ to occur. This is the method used by most of the example programs in this manual. Instead of using this method, you could also simply test the sweep done bit in the status byte by repeatedly serial polling the unit, as in the code fragment example below.

200	S = SPOLL (716)	! Serial poll unit.
210	IF NOT BIT(S,1) THEN 200	! Sweep done?

Note also that it is not necessary to wait for the sweep to finish before you begin requesting data. Simply begin asking for data immediately after triggering the sweep; each bit of data will be sent when it becomes available (Program 5, in fact, demonstrates this technique). Note, however, that you may run into a bus timeout error, depending on the programmed delay time and the controller you are using.

How Big is My Sweep?

In order to make each example program as simple as possible, the sweep size and thus the data arrays are fixed. In a practical test program, however, you probably will want the capability of automatically sizing your sweeps. This can be done with the help of the U8 command, which returns the number of source points in the sweep. The returned value could then be used to dimension any arrays and to size loop counters. The example code fragment below shows how to obtain the sweep size status word from the instrument.

300	OUTPUT 716;"U8X"	! Request status word.
310	ENTER 716;A\$! Input status word.
320	N=VAL(A\$[4,7])	! Convert to nu-
		meric.

Bias Value Programming with Sweeps

The bias value appears at the output both prior to and after a sweep. In order to ensure that your DUT is properly biased before and after a sweep, you may wish to add a bias voltage programming command to certain programs. For example, assume that you wish to add a 0V bias programming command to one of the programs. The following syntax would be used:

120	OUTPUT 716;"B0, 0, 0X"	! Program 0V bias,
		autorange, 0 delay

SECTION 2 Two-terminal Device Tests

2.1 INTRODUCTION

Two-terminal device tests discussed in this section include: voltage coefficient tests on resistors, leakage tests on capacitors, and diode characterization.

2.2 INSTRUMENT CONNECTIONS

Figure 2-1 shows the instrument connections for two-terminal device tests. Note that only one Source Measure Unit is required for these applications. Model 7078-TRX-3 triax cables are used to make triax connections, while banana plug patch cords can be used for binding post connections.

WARNING

Lethal voltages may be present when the test fixture lid is open. To avoid a possible shock hazard, the safety interlock circuit must be connected before use as shown in Figure 2-1.

Also, connect the test fixture screw to safety earth ground using #18 AWG wire minimum before use. Turn off all power before connecting or disconnecting wires or cables.

NOTES

1. Remote sensing connections are recommended for optimum accuracy. See paragraph 1.2.1 for details.

- 2. If measurement noise is a problem, or for critical, low-level applications, use shielded cable for all signal connections.
- 3. When using the Model 8002A, place the Picoammeter/Source-Measure switch in the Source-Measure position.

2.3 JUMPER INSTALLATION

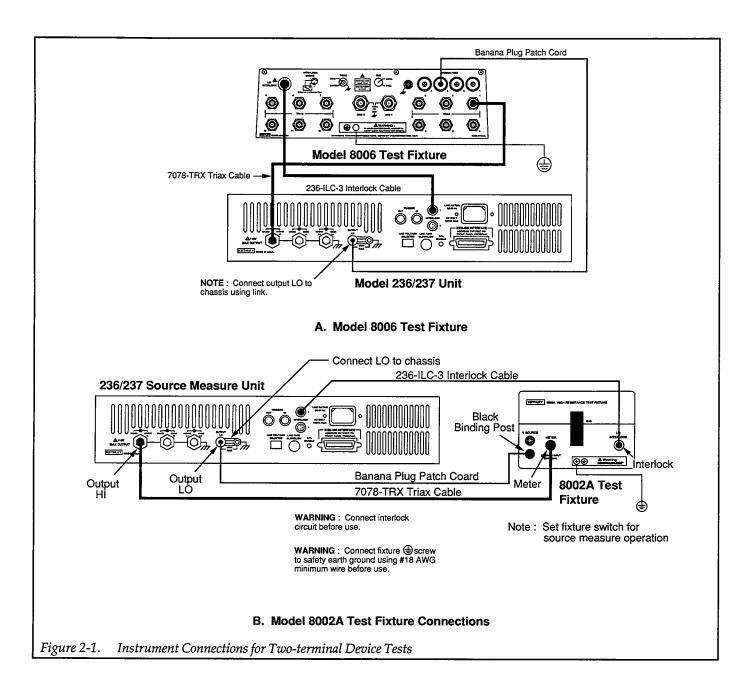
In order to complete connections to the device under test, Model 8006 Test Fixture jumpers must be installed, as shown in Figure 2-2. Note that local sensing is used in these applications, so one set of jumpers to the device socket is necessary.

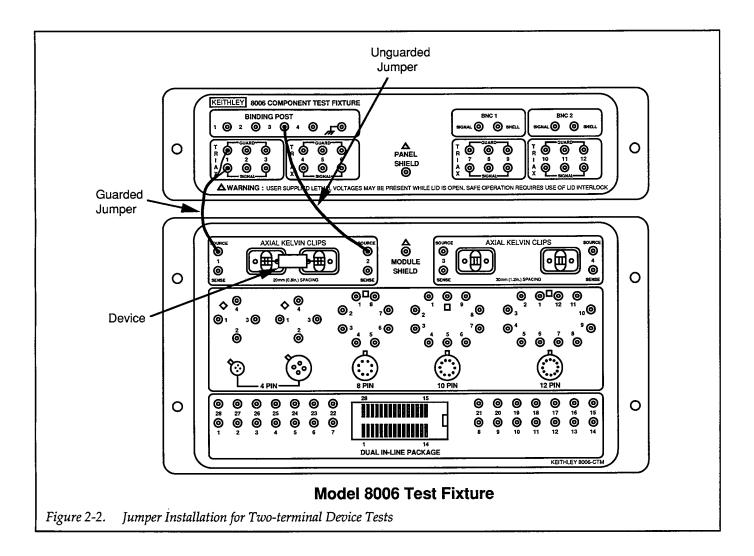
2.4 VOLTAGE COEFFICIENT TESTS OF RESISTORS

Resistors often show a change in resistance with applied voltage with high-megohm resistors (>10° Ω) showing the most pronounced effects. This change in resistance can be characterized as the voltage coefficient. The following paragraphs discuss voltage coefficient tests using a Model 236/237 Source Measure Unit.

2.4.1 Test Configuration

The test configuration for voltage coefficient measurements is shown in Figure 2-3. The Source Measure Unit sources the voltage across the resistor under test, and the picoammeter section measures the resulting current through the resistor.





2.4.2 Voltage Coefficient Calculations

Two different current readings at two different voltage values are required to calculate the voltage coefficient. Two resistance readings, R_1 and R_2 , are then obtained, and the voltage coefficient in %/V can then be calculated as follows:

Voltage Coefficient (% /V) =
$$\frac{100(R_2 - R_1)}{R_1(V_2 - V_1)}$$

Where: R_1 = resistance calculated with first applied voltage (V₁). R_2 = resistance calculated with second applied voltage (V₂).

For example, assume that the following values are obtained:

$$R_{1} = 1.01 \times 10^{10} \Omega$$
$$R_{2} = 1. \times 10^{10} \Omega$$
$$(V_{2} - V_{1}) = 10V$$

The voltage coefficient is:

Voltage Coefficient (% /V) =
$$\frac{100 (1 \times 10^8)}{1 \times 10^{10} (10)} = 0.1\%$$
 /V

2.4.3 Measurement Considerations

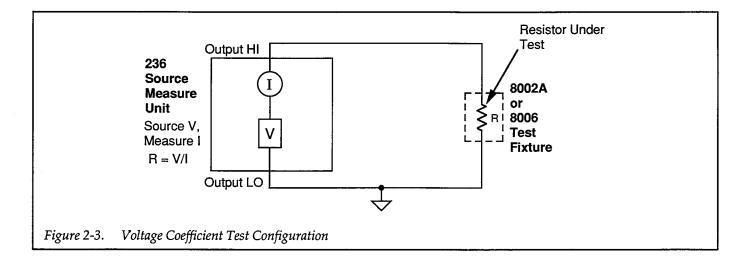
A couple of points should be noted when using this procedure to determine the voltage coefficient of highmegohm resistors. Keep in mind that any leakage resistance in the test system will degrade the accuracy of your measurements. To avoid such problems, use only a highquality test fixture such as the Model 8002A or 8006. Also, make certain that the test fixture sockets are kept clean and free of contamination.

In addition, there is an upper limit on the resistance value that can be measured using this test configuration. For one thing, the test fixture has a finite (although very high) path isolation value. Secondly, the maximum resistance is determined by the test voltage and current-measurement resolution of the test instrument. Finally, the instrument has a typical output impedance of $10^{15}\Omega$. To maximize measurement accuracy with a given resistor, use the highest test voltages possible.

2.4.4 Example Program 1: Voltage Coefficient Test

Program 1 below demonstrates programming techniques for voltage coefficient tests. Follow the steps below to use the test program.

- 1. With the power off, connect the Model 236 to the IEEE-488 interface of the computer.
- 2. Connect the test fixture to the Source Measure Unit using appropriate cables (see Figure 2-1).
- 3. Turn on the Model 236, and allow the unit to warm up for two hours for rated accuracy. Make sure the primary address of the unit is set to 16.
- 4. Turn on the computer, and boot up BASIC.



- 5. Enter the lines below into the computer.
- 6. Install the resistor being tested in the appropriate axial component socket of the test fixture, then close the test fixture lid.
- 7. RUN the program, then enter the required values when prompted to do so. You will be prompted to input two voltage values and a delay value. The two voltage values are the test voltages, and the delay value is the time between source on and measure.
- 8. The computer will then program the unit and measure the currents through the resistor. The calculated voltage coefficient and two resistance values will then be displayed on the CRT. If the unit is over compliance, or if the test fixture lid is open, an error message will be displayed.

2.4.5 Typical Program 1 Results

The actual voltage coefficient you obtain using the program will, of course, depend on the resistor being tested. Typical voltage coefficient obtained for a $10G\Omega$ resistor (Keithley part number R-319-10G) was about 8ppm/V (.008%/V).

2.4.6 Program 1 Description

For the following description, refer to the program below and the program flowchart, which is shown in Figure 2-4.

At the start of the program, a device clear is sent to the Source Measure Unit to return the unit to default state (line 20), and the unit is then placed in remote (line 30). After the screen is cleared (line 40), the Source Measure Unit is programmed as follows (lines 50-90):

- Source V, dc mode
- Local sense, trigger on GET
- 100mA compliance, autorange measure
- Data format to output measure data only with no prefix

• Line cycle integration, 32 reading filter (to minimize noise)

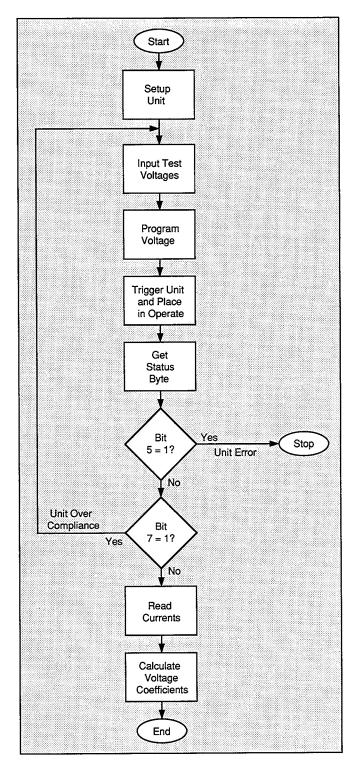


Figure 2-4. Program 1 Flowchart

After the unit is setup, the operator is then prompted to input the two test voltage values and the delay value (lines 90-150). Note that the voltage inputs are tested to verify that they are within the required 100V limits. After these inputs, the unit is programmed for the first source value (line 150), and the operator is then prompted to close the test fixture (line 160).

Once the operator signals to continue, the unit trigger is armed, and the unit is placed into operate (line 190). The status byte is then requested and checked to determine if the lid interlock is open (lines 210-250). If so, a message is displayed, and the program halts. The unit is then triggered (lines 270). After the programmed delay period (line 280), the status byte is requested, and bit 7 of the status byte is checked (line 300) to determine if the unit is over compliance. If so, the program loops back to allow the operator to input different voltage source values.

Assuming that all goes well, a current reading is then requested from the unit (line 350), and the second voltage is programmed (line 360). The second current reading is then obtained (line 370), and the resistance values and voltage coefficient are then calculated and displayed (lines 390-440).

10 REM RESISTOR VOLTAGE COEFFICIENT TEST PROGRAM REV. 1.3 (Program 1) ! Clear 236 20 CLEAR 7 ! Dimension error string 21 DIM Err\$[50] ! Put 236 in remote REMOTE 716 30 OUTPUT KBD;CHR\$(255);CHR\$(75); | Clear screen 40 50 OUTPUT 716; "F0,0X" I Source V, DC mode ! Local sense, trigger on GET
! 100mA compliance, autorange measure
! Output monocord OUTPUT 716;"O0T1,0,0,0X" OUTPUT 716;"L100E-3,0X" 60 70 OUTPUT 716; "G4,2,0X"! Output measure,no prefix,DCOUTPUT 716; "S2P5M128,0X"! Line cycle, 32 reading filter,SRQ OUTPUT 716;"64,2,0X" 80 90 INPUT "Enter voltage V1 (0-100)",V1 | Input first voltage IF ABS(V1)>100 THEN 100 ! Check V1 limits INPUT "Enter voltage V2",V2 ! Input second voltage IF ABS(V2)>100 THEN 120 ! Check V2 limits 100 110 120 130 INPUT "Enter source-measure delay (0-65000msec)",Dly ! Input delay 140 OUTPUT 716; "B"; V1; ", 0, "; Dly; "X" ! Program source and delay 150 PRINT "Close test fixture lid then press CONT to begin test" 160 170 PAUSE OUTPUT 715;"R1ZØX" 180 ! Arm trigger, suppress off 190 OUTPUT 716; "N1X" ! Turn on 236 output | Wait 0.1sec 200 WAIT .1 210 Stat=SPOLL(716) ! Serial poll 236 | Check for 236 error 220 IF BIT(Stat,5) THEN PRINT "236/237 error" 230 240 BEEP ! Wait for error to clear 241 WAIT 2 243 OUTPUT 716; "U1X" ! Request U1 word to clear error 244 ENTER 716;Err\$! Input error word STOP 250 260 END IF 270 TRIGGER 716 ! Trigger 236 ! Wait 280 WAIT D1y/1000+1 Stat=SPOLL(716) ! Serial poll 236 290 IF BIT(Stat,7) THEN ! Check for over compliance 300 310 PRINT "236 over compliance" 320 BEEP 330 GOTO 100 340 END IF 350 | Get first current reading ENTER 716;I1 OUTPUT 716;"B";V2;",0,";Dly;"X" ! Program V2 Voltage 360 ! Get second current reading 370 ENTER 716;I2 380 OUTPUT 716; "NØX" ! Turn off 236 output ! Compute R1 390 R1=V1/I1 ! Compute R2 400 R2 = V2/12Coeff=100*(R2-R1)/(R1*(V2-V1)) ! Compute voltage coefficient PRINT "COEFFICIENT=";Coeff;"%/V" ! Display voltage coefficient 410 420 430 PRINT "RESISTANCE R1=";R1 | Display resistance values 440 PRINT "RESISTANCE R2=";R2 450 END

2.5 CAPACITOR LEAKAGE TEST

One important parameter associated with capacitors is leakage current. Once the leakage current is known, the insulation resistance can be easily calculated. The amount of leakage current in a capacitor depends both on the type of dielectric as well as the applied voltage. With a test voltage of 100V, for example, ceramic dielectric capacitors have typical leakage currents in the nA to pA range, while polystyrene and polyester dielectric capacitors exhibit a much lower leakage current--typically in the fA (10⁻¹⁵A) range

2.5.1 Test Configuration

Figure 2-5 shows the test configuration for the capacitor leakage test. The Model 236/237 Source Measure Unit sources the test voltage across the capacitor, and it measures the resulting leakage current through the device. The resistor, R, is included for current limiting, and it also helps to reduce noise. A typical value for R is $1M\Omega$, although that value can be decreased for larger capacitor values. Note, however, that values under $10k\Omega$ are not recommended.

2.5.2 Leakage Resistance Calculations

Once the leakage current is known, the leakage resistance can easily be calculated from the applied voltage and leakage current value as follows:



For example, assume that you measured a leakage current of 25nA with a test voltage of 100V. The leakage resistance is simply:

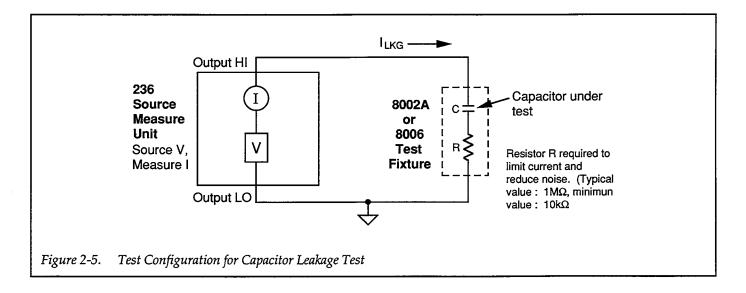
 $R = 100/25nA = 4G \Omega (4 \times 10^{9} \Omega)$

2.5.3 Measurement Considerations

After the voltage is applied to the capacitor, the device must be allowed to charge fully before the current measurement can be made. Otherwise, an erroneous current, with a much higher value, will be measured. The time period during which the capacitor charges is often termed the "soak" time. A typical soak time is seven time constants, or 7RC, which would allow settling to less than 0.1% of final value. For example, if R is $1M\Omega$, and C is 1μ F, the recommended soak time is seven seconds. With small leakage currents (<1nA), it may be necessary to use a fixed measurement range instead of autoranging.

2.5.4 Example Test Program 2: Capacitor Leakage Test

Program 2 below performs the capacitor leakage test described above. Follow the steps below to run the test using this program.



WARNING

Hazardous voltage may be present on the capacitor leads after running this test. Discharge the capacitor before removing it from the test fixture.

- 1. With the power off, connect the Model 236 to the IEEE-488 interface of the computer.
- 2. Connect the test fixture to the Source Measure Unit using appropriate cables (see Figure 2-1).
- 3. Turn on the Model 236, and allow the unit to warm up for two hours for rated accuracy. Make sure the primary address of the unit is set to 16.
- 4. Turn on the computer, and boot up BASIC.
- 5. Enter the lines below into the computer.
- 6. Discharge and install the capacitor being tested along with the series resistor in the appropriate axial component sockets of the test fixture. Install the necessary jumpers, then close the test fixture lid.

NOTE

The capacitor should be fully discharged before running the test.

- 7. RUN the program, then enter the required values when prompted to do so. You will be prompted to input the test voltage and soak time values. When entering the soak time, choose a value of at least 7RC to allow settling to within 0.1% of final value. At very low currents (<500fA), a longer settling time may be required to compensate for dielectric absorption, especially at high voltages.
- 8. The computer will then program the unit and then wait the programmed soak time as a delay time for settling. After settling, any offset current will be suppressed, and the Model 236 will be programmed for the test voltage value. After the soak time has passed, the computer will measure the leakage current, and then display the leakage current and calculate and display the leakage resistance. If the unit is over compliance, or if the test fixture lid is open, an error message will be displayed.

2.5.5 Typical Program 2 Results

As pointed out earlier, the exact value of leakage current will depend on the capacitor value as well as the dielectric. A typical value obtained for a 1µF aluminum electrolytic capacitor was about 80nA at 25V.

2.5.6 Program 2 Description

Refer to the program listing below and the flowchart in Figure 2-6 for the following program description,

After the unit is cleared and placed in remote (lines 20 and 30), the unit is programmed as follows (lines 50-90):

- Source V, dc mode
- Local sense, trigger on GET, continuous
- 10mA compliance, autorange measure
- Measure only data format, no prefix, dc data
- Line cycle integration, 32-reading filter (to minimize noise)

After initial setup of the Model 236, the operator is then prompted to input the desired test voltage (line 100) and the voltage limit is checked (line 110). Next, the desired settling/soak time is requested, and the operator is prompted for a signal to begin the test (lines 120-140); and the output is programmed to 0V (line 150). After the operator signal, the trigger is armed, and the unit is placed in operate (lines 160 and 170). The status byte is then requested after a 0.1sec delay period (lines 180 and 190), and the byte is checked to see if the test fixture lid is open (lines 200-240). If the lid is open, a message to that effect is displayed, and the program halts.

The unit is then triggered (line 250), and the computer then waits the programmed delay time to allow the circuit to settle (line 260). Suppress is then enabled to zero out any offset current in the test system (line 280). The computer then programs the test voltage and then waits the programmed soak time to allow the capacitor to charge fully (lines 290 and 300). Once the soak time has elapsed, the status byte is obtained, and a check for an over-compliance condition is made (lines 350-360). If an over-compliance condition is noted (flagged by status byte bit 7), the program loops back to allow the operator to input a new voltage value.

If no errors occur, a current reading is requested from the unit (line 380), and the current and calculated leakage resistance are then displayed (lines 400 and 410).

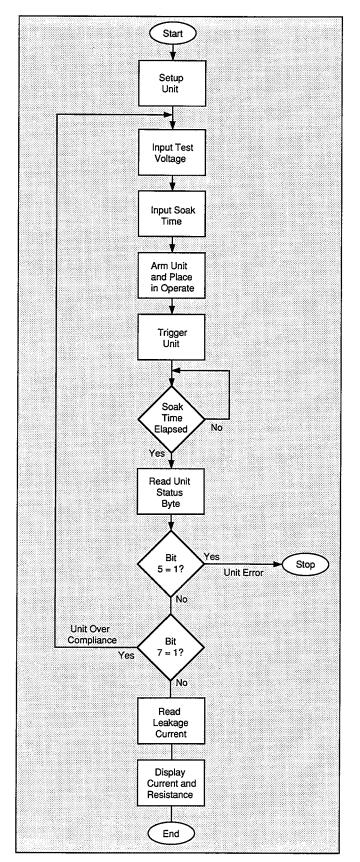


Figure 2-6. Program 2 Flowchart

```
10
       REM CAPACITOR LEAKAGE TEST PROGRAM REV. 1.3 (Program 2)
11
       DIM Err$[50]
                                                ! Dimension error string
20
       CLEAR 7
                                                 | Clear 236
30
       REMOTE 716
                                                 ! Put 236 in remote
       OUTPUT 716; "F0,0X"! Source V, DC modeOUTPUT 716; "00T1,0,0,0X"! Local sense, trigger on GETOUTPUT 716; "L10E-3,0X"! 10mA compliance, autorange measureOUTPUT 716; "64,2,0X"! Output measure no profile DCOUTPUT 716; "64,2,0X"! Output measure no profile DC
40
       OUTPUT KBD;CHR$(255);CHR$(75); ! Clear screen
50
60
70

      OUTPUT 716; "64,2,0X"
      ! Output measure, no prefix, DC

      OUTPUT 716; "S2P5M128,0X"
      ! Line cycle, 32 reading filter, SRQ

80
90
       INPUT "Enter test voltage (0-100)",V ! Input test voltage
100
       IF ABS(V)>100 THEN 100
                                                I Check V limits
110
       INPUT "Enter settling and soak time (seconds)", W ! Input time
120
130
       PRINT "Close test fixture lid then press CONT to begin test"
140
       PAUSE
       OUTPUT 716;"B0,0,0X"
150
                                                ! Program ØV
     OUTPUT 716;"R1ZØX"
160
                                               ! Arm trigger, suppress off
       OUTPUT 716; "N1X"
170
                                               ! Turn on 236 output
                                               ! Wait 0.1sec
180
       WAIT .1
       Stat=SPOLL(716)
190
                                               ! Serial poll 236
200
       IF BIT(Stat,5) THEN
                                               ! Check for 236 error
210
       BEEP
220
       PRINT "236/237 error"
221
       WAIT 2
                                               ! Wait for error to clear
222
       OUTPUT 716; "U1X"
                                               ! Request U1 word to clear error
       ENTER 715;Err$
                                                ! Input error word
223
230
       STOP
240
       END IF
250
       TRIGGER 716
                                                 ! Trigger 236
260
       PRINT "Waiting";W; "seconds for settling time"
       WAIT W
270
280
       OUTPUT 716;"Z1X"
                                                 ! Enable suppress
285
       WAIT 2
                                                 | Wait for suppress
290
       PRINT "Waiting";W;"seconds for soak time"
       OUTPUT 716; "B"; V; ",0,0X" ! Program DC voltage
300
310
       WAIT W+1
                                               | Wait soak time
       Stat=SPOLL(716)
320
                                               | Serial poll 236
       IF BIT(Stat,7) THEN
330
                                               ! Check for over compliance
340
     PRINT "236 over compliance."
350
       BEEP
360
       GOTO 100
370
       END IF
380
      ENTER 716;I
                                              ! Get 236 current reading
     OUTPUT 716; "NØX"
390OUTPUT 716; "NOX"I Turn off 236 output400PRINT "Leakage current=";I! Display leakage current410PRINT "Leakage resistance=";V/I! Display leakage resistance
420
       END
```

2.6 DIODE CHARACTERIZATION

The Model 236 is an ideal instrument to characterize diodes because it can source a current through the device, and measure the resulting forward voltage drop, V_F , across the device. The following paragraphs discuss the test configuration and give a sample test program for such tests.

2.6.1 Test Configuration

Figure 2-7 shows the test configuration for the diode characterization test. The Model 236 is used to source the forward current, I_F , through the diode under test, and it also measures the forward voltage, V_F , across the device. I_F is swept across the desired range of values, and V_F is measured at each current. Note that the same general configuration could be used to measure leakage current by reversing the diode, sourcing voltage, and measuring the leakage current.

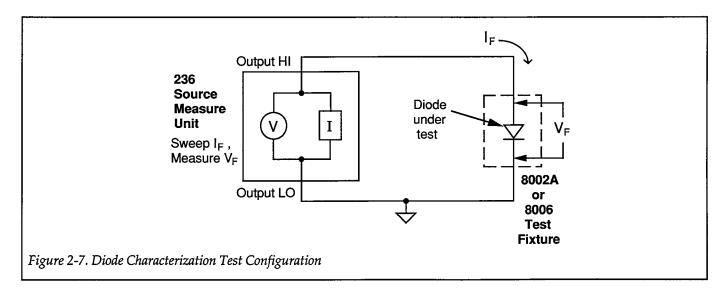
2.6.2 Measurement Considerations

Since the voltages being measured will be fairly small (≈ 0.6 V), remote sensing can be used to minimize the effects of voltage drops across the test connections and in the test fixture. To use remote sensing with the Model 8006 install both sets of jumpers to the axial Kelvin socket to be used for the diode being tested, and modify the test program accordingly.

2.6.3 Example Program 3: Diode Characterization

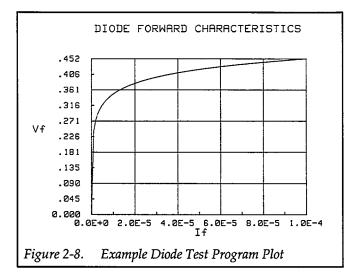
Program 3 below demonstrates the basic programming techniques for running the diode characterization test. Follow the steps below to use this program.

- 1. With the power off, connect the Model 236 to the IEEE-488 interface of the computer.
- 2. Connect the test fixture to the unit using appropriate triax cables (see Figure 2-1).
- 3. Turn on the Model 236, and allow the unit to warm up for two hours for rated accuracy. Make sure the primary address of the unit is set to 16.
- 4. Turn on the computer, and boot up BASIC.
- 5. Enter the lines below into the computer.
- 6. Install a small-signal silicon diode such as a 1N914 or 1N4148 in the appropriate axial socket of the test fixture. Be certain that the jumpers are properly installed, then close the test fixture lid.
- 7. RUN the program in the usual manner. The computer will program the Source Measure Unit and run the diode test using currents between $0\mu A$ and $100\mu A$ in $1\mu A$ increments using a fixed delay of 10msec.
- 8. Once the sweep has been completed, you will be prompted to press CONT to generate a plot of the data. A simple $V_F vs. I_F plot$ will then be displayed on the computer CRT.
- 9. To return to BASIC from the graph, press CONT.



2.6.4 Typical Program 3 Results

Figure 2-8 shows typical results obtained using example Program 3. These results are for a 1N914 silicon diode.



2.6.5 Program 3 Description

For the following description, refer to the program listing and the flowchart shown in Figure 2-9.

Initially, the OPTION BASE statement is used to declare that all array subscripts begin with 1 rather than 0 (line 20), and the reading array is then dimensioned for 101 points with two readings each (line 30). Next, the unit is cleared and placed in remote (lines 40 and 50), and the instrument is initialized as follows (lines 70-160):

- Source I, sweep mode
- Local sense, continuous trigger on GET
- 10V compliance, autorange measure
- Source and measure data format with no prefix and sweep data output
- SRQ on sweep done
- Suppress on (nulls offsets)
- Istart: 0µA
- Istop: 100μA
- Istep: 1μA

After setup, the sweep is then programmed (line 170), and the operator is prompted to signal the start of the test (lines 180 and 190). Following the operator signal, the trigger is armed (line 200), and the unit is placed into operate and triggered (lines 210 and 220). Following the

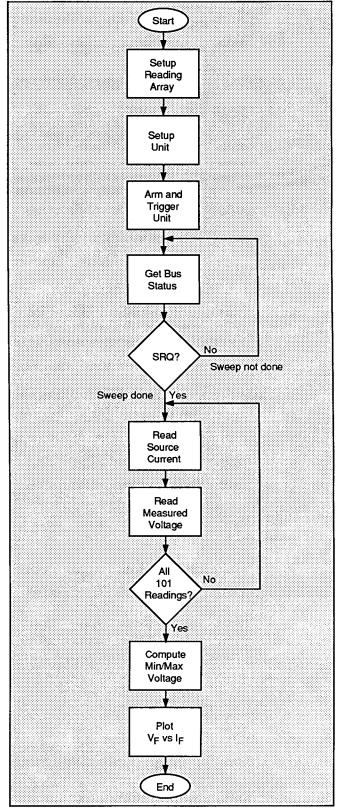


Figure 2-9. Program 3 Flowchart

trigger, the program enters a loop where it continuously checks the SRQ line on the bus to determine when the sweep is finished (lines 240 and 250).

When the unit finishes the sweep, it sets the SRQ line true, and the program falls out of the loop. The status byte is then read (line 260) to clear the SRQ, and the unit is placed in standby (line 270). Next, all 101 data points are requested from the computer (lines 280-300). Here, the source value, which is the forward current, is placed in element (I,1) of the reading array, and the measured voltage is placed in element (I,2) of the reading array. The minimum and maximum measured voltage values are then found (lines 310-360); these values are used to scale the Y axis of the plot.

The graphics routines are located in lines 410-670 of the program. Most of these are self-explanatory, but a few of them require comment. Note that the soft clip limits are defined by the VIEWPORT statement (line 500), while the X,Y scaling is performed by the WINDOW statement (line 510). Note that X axis scaling is determined by the programmed start and stop currents (Istart and Istop), while the Y axis limits (Ymin and Ymax) are the values determined from the minimum and maximum measured voltages. Finally, plotting is performed by the PLOT statement (line 560), which plots the entire reading array with one statement, and the axes are numbered (lines 570-670).

2.6.6 Modifying Program 3

As written, the program sets up the Source Measure Unit to step the current from $0\mu A$ to $100\mu A$ in $1\mu A$ increments. For other values, you can simply change the Istart, Istop, and Istep values in lines 130-150 to the required values, or (better yet), incorporate INPUT statements to allow operator input of those values. It may also be necessary to change the source range value from 6 (100µA range) to accommodate different current parameters.

If you choose values that result in a sweep length other than 101 points, additional modifications to the program will be necessary. The DIM statement declaration (line 30) and loop counter values (lines 280 and 330) must agree with the number of points in the sweep.

2.6.7 Using Log Sweeps

With some devices, it may be desirable to use a log sweep because of the wide range of currents necessary to perform the test. Program 3, for example, can be modified for a log sweep of the diode current by changing the Q1 command in line 170 to Q2 with appropriate parameters. For example, assume that you wish to sweep from 1µA to 100mA using a log sweep, the program lines would be modified as follows:

- 130 Istart=1E-6 ! Define 1µA start current Istop=100E-3 140 150 Points=1
- 170 OUTPUT 716;"Q2,"; Istart;","Istop;","; Points;",9,";Dly;"X"

! Define 100mA stop current

! Select 10 points per decade

Note that the start and stop currents are programmed just as before, although with a much wider range than would be practical with a linear sweep. With log sweep, however, the Points parameter, which defines the number of points per decade, replaces the Istep parameter that is used with the linear sweep. The source range is also changed to a value of 9 (100mA range).

2.6.8 Using Pulsed Sweeps

In some cases, it may be desirable to use a pulsed sweep to avoid device self-heating that could affect the test results. For example, Program 3 can be modified to use a staircase pulse sweep by substituting the Q4 command for the Q1 command along the correct parameters. For example, assume that you wish to step the current from 0µA to 100µA at 10µA increments with an on time of 10msec, and an off time of 90msec. The following lines would be added or substituted:

160 $t_{ON}=10$! Define 10msec on time. 165 ! Define 90msec off time. t_{OFF}=90 170 OUTPUT 716;"Q4,";

The main difference between programming the standard

staircase and pulsed staircase sweep is that on time and

off time are substituted for the delay time.

Istart;",";Istop;","; Istep;",0,";t_{ON};t_{OFF}; "χ"

10	REM DIODE CHARACTERIZATION TEST PROGRAM REV. 1.3 (Program 3)		
20	OPTION BASE 1	! First array subscript is 1	
30	DIM Reading(101,2)	! Dimension reading array (101 pts.)	
40		! Clear 236	
50		! Put 236 in remote	
60		! Clear screen	
70		! Source I, sweep mode	
80		! Local sense, trigger on GET	
90		! 10V compliance, autorange measure	
	•	· · · -	
100		! Source,measure,no prefix,sweep data	
110		! SRQ on sweep done	
115		! Program 0 bias value	
120		Enable suppress	
130		! Define ØuA start current	
140		! Define 100uA stop current	
150		! Define luA step current	
160		! Define 10msec delay value	
170	OUTPUT 716;"Q1,";Istart;",";Istop;"	,";Istep;",0,";Dly;"X" ! Program sweep	
180	PRINT "Close lid, press CONT to beg	in"	
190	PAUSE	! Wait to continue	
200		! Arm trigger	
210		! Turn on 236 output	
220		! Trigger 236 to start sweep	
230	PRINT "Waiting for sweep to end"		
240		! Get IEEE-488 bus status	
250		! Wait for SRQ on sweep done	
250			
		! Serial poll 236 to clear SRQ	
270		! Turn off 236 output	
280		! Loop for all readings	
290		9 Get 236 current and voltage readings	
300		! Loop back for next reading	
310		! Find minimum and maximum voltage	
320	Ymax=-MAXREAL		
330	FOR I=1 TO 101		
340	IF Reading(I,2) <ymin then="" ymin="Reading(I,2)</td"></ymin>		
350	IF Reading(I,2)>Ymax THEN Ymax=Reading(I,2)		
360	NEXT I		
370	PRINT "Press CONT to display graph"		
380	PRINT "Press CONT while in graph to	return to BASIC"	
390	PAUSE		
400		! Clear CRT	
410		! Initialize graphics	
420		! Define plot to CRT	
430	•	! Turn on graphics	
440		! Title graph	
450	LABEL "DIODE FORWARD CHARACTERISTIC	- ·	
1			
460	•	! Label X axis	
470	LABEL "If"		
480	•	! Label Y axis	
490	LABEL "Vf"		
500	VIEWPORT 30,120,20,85	! Define soft clip limits	
L			

```
510
      WINDOW Istart,Istop,Ymin,Ymax
                                          ! Scale graph
520
      X1=(Istop-Istart)/10
                                          ! Compute X axis increment
530
      Y1=(Ymax-Ymin)/10
                                          ! Compute Y axis increment
540
      GRID X1*2,Y1*2,Istart,Ymin
                                          ! Draw grid
                                          ! Add some tick marks
550
      AXES X1,Y1,Istart,Ymin
560
      PLOT Reading(*)
                                          ! Plot data
570
      CSIZE 4
                                          ! Define character size
580
     LORG 6
                                          1 Center characters
590
      CLIP OFF
                                          ! Turn off soft clipping
600
      FOR I=Istart TO Istop+.01*Istep STEP 2*X1 ! Number X axis
610
      MOVE I, Ymin-(Y1/4)
620
      LABEL USING "#,D.DESZ";I
630
      NEXT I
      FOR I=Ymin TO Ymax+.01*Y1 STEP Y1
640
                                          ! Number Y axis
650
      MOVE Istart-(1.3*X1),I+(.3*Y1)
660
     LABEL USING "#,MDD.DDD";I
670
      NEXT I
680
      PAUSE
690
      OUTPUT KBD;CHR$(255);CHR$(75);
                                          ! Turn off alpha display
      GRAPHICS OFF
700
                                          ! Turn off graphics display
710
      END
```

SECTION 3 Bipolar Transistor Tests

3.1 INTRODUCTION

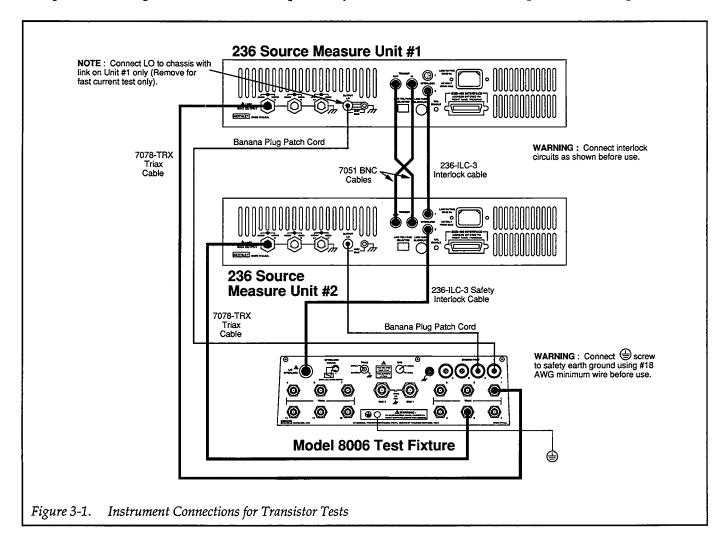
Bipolar transistor tests discussed in this section include: tests to generate common-emitter characteristic curves, Gummel plot, current gain, and transistor leakage tests.

3.2 INSTRUMENT CONNECTIONS

Figure 3-1 shows the instrument connections for the bipolar transistor tests outlined in this section. Two Model 236/237 Source Measure Units are required for the tests (except for the leakage current test, which requires only one Source Measure Unit). In addition, the Model 8006 test fixture is recommended to make connections to the transistor under test.

Model 7078-TRX-3 triax cables are recommended to make instrument-to-test fixture connections. In addition, the safety interlock connecting cables must be connected as shown.

WARNING Lethal voltages may be exposed when the test fixture lid is open. To avoid a possible



shock hazard, the safety interlock circuit must be connected as shown in Figure 3-1 before use. Connect fixture screw to safety earth ground using #18 AWG minimum wire before use. Turn off all power before connecting or disconnecting wires or cables.

Two final connections that must be made are the Source Measure Unit trigger connections. Connect the TRIGGER OUT jack of Unit #1 to the TRIGGER IN jack of Unit #2, and connect the TRIGGER OUT jack of Unit #2 to the TRIGGER IN jack of Unit #1. Use standard BNC-to-BNC cables such as the Model 7051 to make these connections.

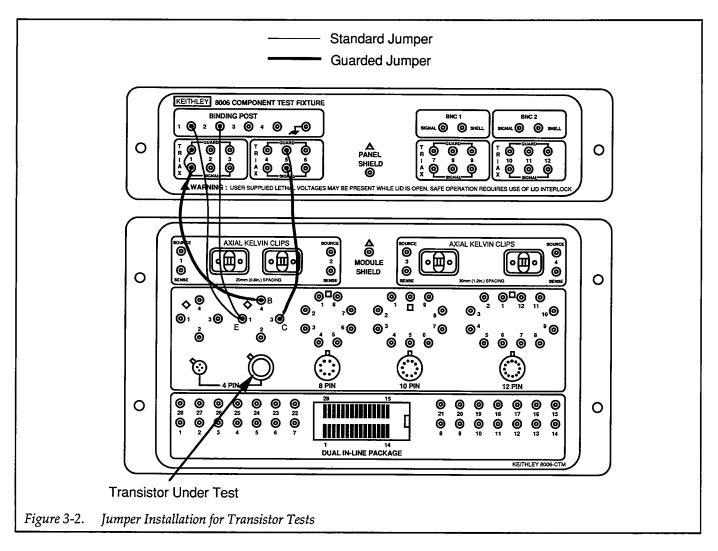
NOTES

1. Remote sensing connections are recommended for optimum accuracy. See paragraph 1.2.2 for details.

- 2. If measurement noise is a problem, or for critical, low-level applications, use shielded cable for all signal connections.
- 3. Most of the transistor test programs use external triggering. If the trigger jacks are not connected as shown, the programs will not function properly.

3.3 JUMPER INSTALLATION FOR TRANSISTOR TESTS

Figure 3-2 shows jumper installation for the transistor tests. The DUT itself should be placed in the appropriate four-terminal TO package socket, and the jumper connections should be made between the instrument panel jacks and the jacks on the component panel. Note that local sensing is used for most applications, so jumpers should be connected as shown.



3.4 COMMON-EMITTER CHARACTERISTICS

Common-emitter characteristics are probably the most familiar type of curves generated for bipolar transistors. Test data used to generate these curves is obtained by sweeping the base current, I_B , across the desired range of values at specific increments. At each base current value, the collector-emitter voltage, V_{CE} , is swept across the desired range, again at specific increments. At each V_{CE} value, the collector current, I_C , is measured.

Once the data are collected, a plot of I_C vs. V_{CE} is generated for each value of I_B . The result is a family of curves that shows how I_C varies with V_{CE} at specific I_B values.

3.4.1 Test Configuration

Figure 3-3 shows the test configuration for the commonemitter characteristic tests. Unit #1 sweeps I_B across the desired range, and Unit #2 sweeps V_{CE} and measures I_C . Note that an NPN transistor is shown as part of the test configuration. A small-signal NPN transistor with an approximate current gain of 500 (such as a 2N5089) is recommended for use with the test program below. Other similar transistors such as a 2N3904 may also be used, but the program may require modification.

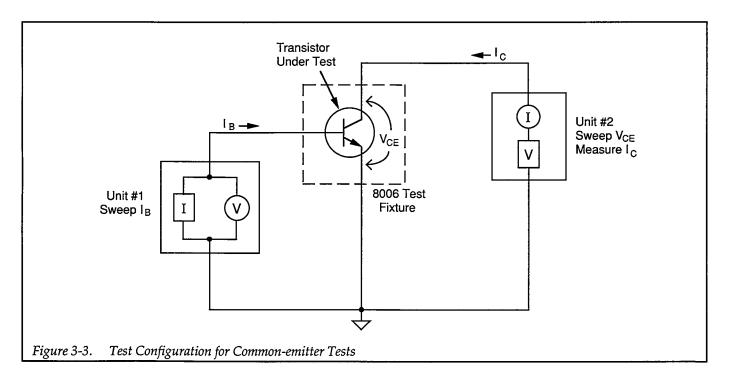
3.4.2 Measurement Considerations

A fixed delay period of 100msec, which is included in the program, may not be sufficient for testing some devices. Also, it may be necessary to change the programmed current values to optimize the tests for a particular device.

3.4.3 Program 4: Common-emitter Characteristics

Program 4 below can be used to run common-emitter characteristic tests on small-signal NPN transistors. In order to run the program, follow the steps below.

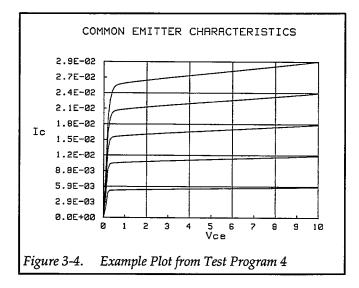
- 1. With the power off, connect both Model 236 Source Measure Units to the IEEE-488 interface of the computer.
- 2. Connect the test fixture to both units using appropriate cables (see Figure 3-1).
- 3. Turn on both Model 236 Source Measure Units, and allow the units to warm up for two hours for rated accuracy. Make sure the primary address of Unit #1 is set to 16 and that the primary address of Unit #2 is set to 17.
- 4. Turn on the computer, and boot up BASIC.
- 5. Enter the lines below into the computer.
- 6. Install a small-signal NPN silicon transistor such as a 2N5089 in the appropriate transistor socket of the test fixture. Be certain that the jumpers are properly installed, then close the test fixture lid.



- 7. RUN the program in the usual manner. The computer will program both units and run the commonemitter characteristic test on the device. The base current will be swept between $10\mu A$ and $50\mu A$ in $10\mu A$ increments, and the value of V_{CE} will be swept between 0V and 10V in 0.1V increments. A fixed delay of 100msec is also incorporated into the program.
- 8. Once the sweeps have been completed, you will be prompted to press CONT to generate a plot of the data. A simple I_C vs. V_{CE} plot will then be displayed on the computer CRT, with separate curves for each I_B value.
- 9. To return to BASIC from the graph, press CONT.

3.4.4 Typical Program 4 Results

Figure 3-4 shows typical results generated by example Program 4. A 2N5089 NPN silicon transistor was used to generate these test results.



3.4.5 Program 4 Description

For the following program description, refer to the program listing below and the flowchart shown in Figure 3-5.

Initially, the reading array is dimensioned (line 30) as a three-element array that will hold five sweeps of 101 points each, with two readings for each point. Next, both units are returned to default conditions by a DCL command (line 40), and Unit #1, which sweeps I_B , is set up as follows (lines 70-160):

• Source I, sweep mode

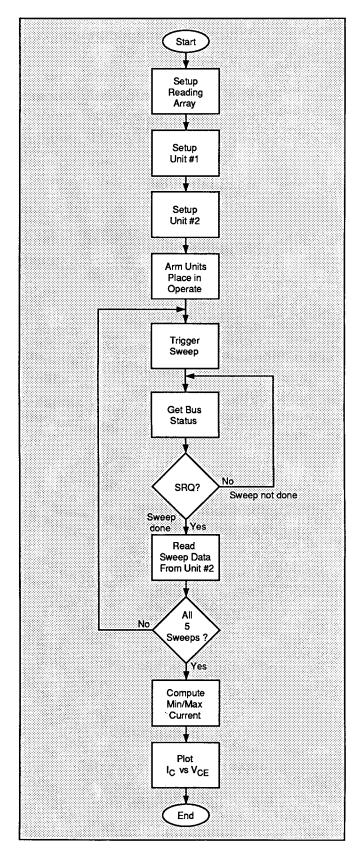


Figure 3-5. Program 4 Flowchart

- 1V compliance, 1.1V range
- Local sense
- Trigger on GET, one step per trigger, output trigger at end of delay
- Start I_B current: 10µA
- Stop I_B current: 50μA
- Step I_B current: 10μA
- Delay: 100msec
- Staircase sweep (limits determined by start, stop, and step current)

Following Unit #1 setup, Unit #2, which sweeps V_{CE} and measures I_{C} , is programmed as follows (lines 180-290):

- Source V, sweep mode
- Local sensing
- 100mA compliance, autorange measure
- Source measure data format with no prefix, sweep data
- SRQ on sweep done
- Trigger on external, one sweep per trigger
- Line cycle integration (to reduce noise)
- Suppress on (to null offsets)
- Start V_{CE} voltage: 0V
- Stop V_{CE} voltage: 10V
- Step V_{CE} voltage: 0.1V
- Staircase sweep (limits determined by start, stop, and step voltage)

Once the two units are ready to go, both triggers are armed and the units are placed into operate (lines 330 and 340). The main programming loop is then entered to generate the five I_B curve sweeps (line 350).

One of the key demonstrations of this test program is the subordinate-sweep configuration. To initiate each I_B curve sweep, Unit #1 is triggered over the bus by the IEEE GET command (line 370). This trigger causes Unit #1 to output the next programmed I_B current step. Following the programmed delay period, Unit #1 outputs a trigger pulse, which triggers Unit #2 to begin its sweep through all programmed V_{CE} values. At each V_{CE} value,

Unit #2 measures I_c , and stores the data until the sweep is done.

In order to synchronize the program with each sweep, the program enters a loop to wait for Unit #2 to generate an SRQ (lines 380 and 390) when it has finished a sweep. Once each sweep has finished, Unit #2 is serial polled to clear the SRQ line (line 400), and the data are read into the reading array (line 420). Array element (I,J,1) stores source (V_{CE}) information, and array element (I,J,2) stores measured data (I_C) information. Once all the data pertaining to the present sweep are read, the program loops back to generate the next sweep at the subsequent I_B value (line 440).

In order to properly scale the plot, the maximum and minimum I_C values must be determined. This operation is performed in lines 500-570 of the program. Next, the data are plotted (lines 590-930). Note that the X axis of the graph is scaled by the Vstart and Vstop parameters (line 690), while the the Y axis is scaled by the maximum and minimum IC values. Plotting is performed on the reading data (lines 740-790); note that the plot array (PLOT (*)) statement cannot be used in this situation because of the three-element array used to store reading data.

3.4.6 Modifying the Program

As written, the sweep limits and increments are set to fixed values. For I_B , the start, stop, and step values are 10 μ A, 50 μ A, and 10 μ A respectively, and the start, stop, and step V_{CE} values are 0V, 10V, and 0.1V respectively. Again, you can modify the program as required, or include INPUT statements to allow operator input of these parameters. For sweep lengths other than 101 points, additional modifications such as array dimension and loop counter must also be made.

You can also speed up the sweep process by shortening the delay parameter (line 150) or changing the integration period (line 250). Doing so, however, may result in inaccurate readings or unacceptable noise levels.

```
REM COMMON EMITTER CHARACTERISTIC TEST PROGRAM REV. 1.3 (Program 4)
10
20
     OPTION BASE 1
                                    ! First array subscript is 1
30
     DIM Reading(5,101,2)
                                    ! Dimension reading array (5 swps,101 pts)
40
     CLEAR 7
                                    ! Clear both Units
     OUTPUT KBD;CHR$(255);CHR$(75); ! Clear screen
50
60
     REMOTE 716
70
                                    ! Put Unit 1 in remote
80
     OUTPUT 716; "F1,1X"
                                    ! Source I, sweep mode
90
     OUTPUT 716; "L1,1X"
                                    1 1V compliance, 1.1V range
100
     OUTPUT 716;"00X"
                                    ! Local sense
     OUTPUT 716; "T1,1,2,0X"
110
                                    ! GET trigger cycle,out trig end of delay
     OUTPUT 716; "B0,0,0X"
                                    ! Program Ø bias value
115
120
     Istart=1.0E-5
                                    ! Define 10uA start Ib current
                                    | Define 50uA stop Ib current
130
     Istop≃5.0E-5
                                    ! Define 10 uA step Ib current
140
     Istep=1.0E-5
150
     Dly=100
                                    | Define 100msec Unit delay
     OUTPUT 716;"Q1,";Istart;",";Istop;",";Istep;",0,";Dly;"X" ! Pgm swp
160
170
     180
     REMOTE 717
                                    ! Put Unit 2 in remote
190
     OUTPUT 717; "F0,1X"
                                    ! Source V, sweep mode
     OUTPUT 717;"00X"
200
                                    ! Local sensing
     OUTPUT 717; "L100E-3,0X"
210
                                    ! 100mA compliance, autorange measure
220
     OUTPUT 717; "65,2,1X"
                                    ! Source,measure,no prefix,sweep data
230
     OUTPUT 717; "M2,X"
                                    ! SRQ on sweep done
     OUTPUT 717; "T3,0,0,0X"
                                    ! Trigger on external, continuous
240
     OUTPUT 717; "S2X"
250
                                    ! Line cycle integration
255
     OUTPUT 717; "B0,0,0X"
                                    ! Program Ø bias value
     OUTPUT 717; "Z1X"
260
                                    ! Enable suppress
270
     Vstart=0
                                    | Define ØV start Vce
280
     Vstop=10
                                    | Define 10V stop Vce
290
                                    ! Define 0.1V step Vce
     Vstep=.1
     OUTPUT 717; "Q1, "; Vstart; ", "; Vstop; ", "; Vstep; ", 0, "; Dly; "X" ! Pgm swp
300
310
     PRINT "Close lid, press CONT to begin test"
320
     PAUSE
     OUTPUT 716; "RIN1X"
330
                                    ! Arm Unit 1 trigger, turn on output
     OUTPUT 717; "RIN1X"
                                    ! Arm Unit 2 trigger, turn on output
340
                                    ! Loop for five Ib curves
350
     FOR I=1 TO 5
     PRINT "Generating sweep";I
360
370
                                    ! Trigger Unit 1
     TRIGGER 716
     STATUS 7,7;Stat
                                    ! Get IEEE-488 bus status
380
                                    ! Wait for Unit 2 SRQ on sweep done
390
     IF NOT BIT(Stat, 10) THEN 380
400
     Stat=SPOLL(717)
                                    ! Serial poll Unit 2 to clear SRQ
410
     FOR J=1 TO 101
                                    ! Loop for all 101 readings
420
     ENTER 717; Reading(I,J,1), Reading(I,J,2)! Get Vce and Ic data from Unit 2
430
                                    I Loop back for next reading
     NEXT J
440
     NEXT I
                                    ! Loop back for next Ib value
450
     OUTPUT 716; "NØX"
                                    ! Turn off Unit 1 output
     OUTPUT 717; "NØX"
                                    ! Turn off Unit 2 output
460
470
     PRINT "Press CONT to display graph"
480
     PRINT "Press CONT while in graph to return to BASIC"
490
     PAUSE
500
     Ymin=MAXREAL
                                    ! Find minimum and maximum Ic value
```

510 Ymax=-MAXREAL 520 FOR I=1 TO 5 530 FOR J=1 TO 101 540 IF Reading(I,J,2)<Ymin THEN Ymin=Reading(I,J,2) IF Reading(I,J,2)>Ymax THEN Ymax=Reading(I,J,2) 550 560 NEXT J 570 NEXT I 580 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 590 GINIT ! Initialize graphics 600 PLOTTER IS CRT, "INTERNAL" ! Define plot to CRT GRAPHICS ON 610 ! Turn on graphics 620 MOVE 20,95 ! Title graph 630 LABEL "COMMON EMITTER CHARACTERISTICS" 640 MOVE 70,10 ! Label X axis 650 LABEL "Vce" 660 MOVE 0,53 ! Label Y axis LABEL "Ic" 670 1 ! Define soft clip limits 680 VIEWPORT 30,120,20,85 690 WINDOW Vstart, Vstop, Ymin, Ymax ! Scale graph 700 Y1=(Ymax-Ymin)/10 ! Compute Y axis increment X1=(Vstop-Vstart)/10 ! Compute X axis increment 710 720 GRID 2*X1,2*Y1,Vstart,Ymin ! Draw grid 730 AXES X1,Y1,Vstart,Ymin ! Add some tick marks 740 FOR I=1 TO 5 ! Loop for all five curves 750 FOR J=1 TO 101 | Loop for all 101 points per curve 760 PLOT Reading(I,J,1), Reading(I,J,2) ! Plot point 770 NEXT J / Plot next point 780 PENUP ! Raise pen 790 NEXT I ! Plot next curve 800 ! Define character size CSIZE 4 810 LORG 6 | Center characters 820 CLIP OFF ! Turn off soft clip 830 FOR I=Vstart TO Vstop+.01*X1 STEP X1 ! Number X axis 840 MOVE I, Ymin-(Y1/4) 850 LABEL USING "#,K";I 860 NEXT I 870 FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis 880 MOVE Vstart-(1.3*X1),I+(.3*Y1) 890 LABEL USING "#,MD.DE";I 900 NEXT I 910 PAUSE OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear alpha screen 920 930 GRAPHICS OFF ! Clear graphics screen 940 END

3.5 GUMMEL PLOT

A Gummel plot is often used to determine current gain variations of a transistor. Data for a Gummel plot is obtained by sweeping the base-emitter voltage, V_{BE} , across the desired range of values at specific increments. At each V_{BE} value, both the base current, I_B , and collector current, I_C , are measured.

Once the data are taken, a plot of both I_B and I_C vs. V_{BE} is generated. Because of the large differences in magnitude between I_B and I_C , the Y axis is usually plotted logarithmically.

3.5.1 Test Configuration

Figure 3-6 shows the test configuration for Gummel plot tests. Unit #1 is used to sweep V_{BE} across the desired range, and it also measures I_B . Unit #2 sets V_{CE} to the desired fixed value, and it also measures I_C .

3.5.2 Measurement Considerations

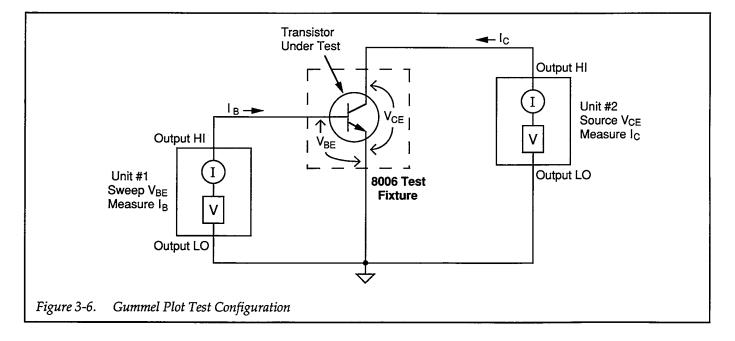
As written, the range of V_{BE} test values is from 0.7V to 0V in -0.01V increments. It may be necessary, however, to change these limits for best results with your particular device. See paragraph 3.5.6 for information. Note that the plot is done in reverse order to optimize autoranging per-

formance. Also, low currents will be measured so take the usual low-current precautions.

3.5.3 Program 5: Gummel Plot

Program 5 demonstrates the basic programming techniques for generating a Gummel plot. Follow the steps below to run this program.

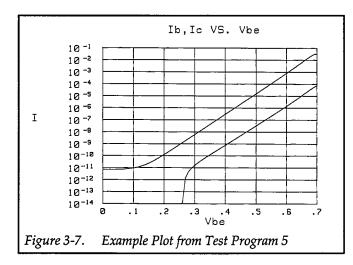
- 1. With the power off, connect both Model 236 Source Measure Units to the IEEE-488 interface of the computer.
- 2. Connect the test fixture to both units using appropriate triax cables (see Figure 3-1).
- 3. Turn on both Model 236 Source Measure Units, and allow the units to warm up for two hours for rated accuracy. Make sure the primary address of Unit #1 is set to 16 and that the primary address of Unit #2 is set to 17.
- 4. Turn on the computer, and boot up BASIC.
- 5. Enter the lines below into the computer.
- 6. Install a small-signal NPN silicon transistor such as a 2N5089 in the appropriate transistor socket of the test fixture. Be certain that the jumpers are properly installed, then close the test fixture lid.
- 7. RUN the program in the usual manner. The computer will program both units and run the test on the device. The base-emitter voltage will be swept between 0.7V and 0V in -0.01V increments, and both I_B and I_C will be measured at each V_{BE} value. Note that a fixed collector-emitter voltage of 10V is used for the tests.



- 8. Once the sweep has been completed, you will be prompted to press CONT to generate a plot of the data. A simple I_B and I_C vs. V_{BE} plot will then be displayed on the computer CRT, with separate logarithmic curves for I_B and I_C .
- 9. To return to BASIC from the graph, press CONT.

3.5.4 Typical Program 5 Results

Figure 3-7 displays a typical Gummel plot as generated by example Program 5. Again, the transistor used for this example was a 2N5089 NPN silicon transistor.



3.5.5 Program 5 Description

Refer to the Program 5 listing below and the flowchart shown in Figure 3-8 for the following description.

Initially, the data array is set up (lines 20 and 30), and both Source Measure Units are returned to their default conditions (line 40). Next, Unit #1, which sweeps V_{BE} and measures I_{B} , is set up as follows (lines 70-180):

- Source V, sweep mode
- 1mA compliance, autorange measure
- Local sensing
- Source and measure data format, no prefix, output sweep data
- External trigger, trigger starts measurement phase, output trigger end of delay
- Line cycle integration
- Start V_{BE} voltage: 0.7V
- Stop V_{BE} voltage: 0V
- Step V_{BE} voltage: 0.01V

- Staircase sweep (number of points determined by start, stop, and step voltages)
- 10msec delay

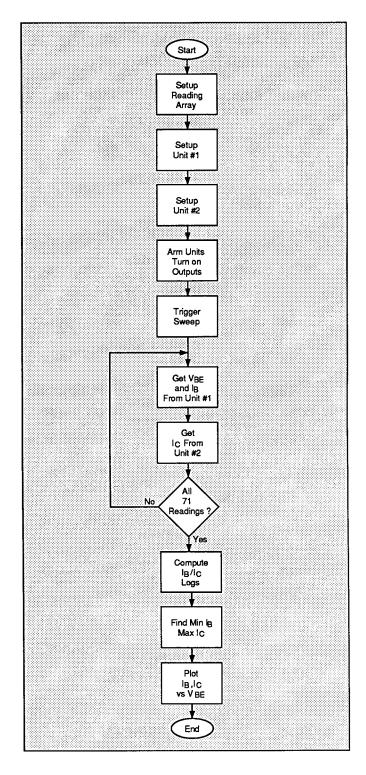


Figure 3-8. Program 5 Flowchart

Unit #2, which measures I_C, is programmed in the following manner (lines 200-290):

- Source V, sweep mode
- Local sensing
- 100mA compliance, autorange measure
- Measure data only, no prefix, sweep data
- Trigger on external, trigger starts source phase, output trigger on end of measurement
- Line cycle integration
- 10msec delay
- Constant sweep (number of points programmed to 71), V_{CE} =10V
- 10V bias voltage

Following unit setup, both unit triggers are armed, and the instruments are placed into the operate mode (lines 320 and 330).

Note that synchronized sweeps are used in this program, with Unit #1 triggering Unit #2 and vice versa. Since both Source Measure Units are programmed for the external trigger mode, the only way to trigger the test is to use the immediate trigger command, H0X (line 350). Once triggered, Unit #1 sets V_{BE} to the required value, and it then triggers Unit #2 at the end of the delay period. Unit #2 then sets V_{CE} and measures I_C at I_B . At the end of its measurement, Unit #2 triggers the next Unit #1 measurement, and the cycle repeats.

While sweep is being performed, a nested loop is entered to read the data from both units into the reading array (lines 360-390). Note that I_B and V_{BE} data from Unit #1 are placed into reading array elements (I,1) and I,2) respectively, while I_C data from Unit #2 is placed into reading array element (I,3).

Next, the the base 10 log of both I_B and I_C data is calculated (lines 440-490). At the same time, an arbitrary noise floor of 0.01pA is defined to eliminate offsets and noise in the final readings (lines 450-460). As pointed out earlier, these data are usually plotted logarithmically because of the wide differences between I_B and I_C . Finally, the maximum I_C and minimum I_B values are found in order to scale the Y axis of the graph (lines 510-560), and the closest even power of 10 for both maximum and minimum values are then set (lines 570 and 580). The results are then plotted in the usual manner (lines 600-1000).

3.5.6 Modifying the Program

If desired, you can modify the program for different sweeps by modifying the start, stop, and step currents to the required values (or add INPUT statements for runtime operator inputs). For sweep lengths other than 71, additional modifications such as array dimensioning and loop counters must also be included.

The fixed 10V V_{CE} value can also be modified, if required. Simply change the value declaration in the program, or add an INPUT statement for run-time operator input.

10 REM GUMMEL PLOT TEST PROGRAM REV. 1.3 (Program 5) 20 OPTION BASE 1 ! First array subscript is 1 DIM Reading(71,3) 30 ! Dimension reading array (71 pts) 40 CLEAR 7 ! Clear both Units OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear screen 50 60 70 REMOTE 716 ! Put Unit 1 in remote OUTPUT 716; "F0,1X" 80 ! Source V, sweep mode ! 1mA compliance,autorange measure 90 OUTPUT 716; "L1E-3,0X" 100 OUTPUT 716; "OØX" ! Local sense OUTPUT 716;"G5,2,1X" 110 ! Source,measure,no prefix,sweep data OUTPUT 716; "T3,4,2,0X" OUTPUT 716; "S2Z0X" ! Ext trigger,out trig end of delay ! Line cycle integration,suppress off 120 130 ! Program Ø bias value OUTPUT 716; "B0,0,0X" 135 Vstart=.7 | Define 0.7V start Vbe voltage 140 150 Vstop=0 ! Define ØV stop Vbe voltage 160 Vstep=-.01 | Define -0.01V step Vbe voltage 170 ! Define 10msec Unit delay D1v=10 OUTPUT 716; "Q1,"; Vstart; ", "; Vstop; ", "; Vstep; ", 0, "; Dly; "X" ! Program sweep 180 190 200 REMOTE 717 ! Put Unit 2 in remote 210 OUTPUT 717; "F0,1X" I Source V, sweep mode OUTPUT 717;"00X" 220 ! Local sensing OUTPUT 717; "L100E-3,0X" ! 100mA compliance,autorange measure 230 OUTPUT 717; "G4,2,1X" 240 ! Measure,no prefix,sweep data ! External trigger, out trig end of meas ! Define 10V constant Vce OUTPUT 717;"T3,1,4,0X" 250 260 Vce=10 270 OUTPUT 717; "S2ZØX" ! Line cycle integration, suppress off OUTPUT 717; "B"; Vce; ",0,0X" ! Set bias value to Vce 280 OUTPUT 717; "Q0,"; Vce; ",0,"; Dly; ",71X" ! Program constant sweep,71 points 290 300 PRINT "Close lid, press CONT to begin test" 310 PAUSE 320 OUTPUT 716; "RIN1X" | Arm Unit 1 trigger, turn on output OUTPUT 717; "RINIX" ! Arm Unit 2 trigger,turn on output 330 340 PRINT "Generating sweep" 350 OUTPUT 716;"HØX" 1 Trigger Unit 1 to start sweep 360 FOR I=1 TO 71 ! Loop for all 71 readings 370 ENTER 716; Reading(I,1), Reading(I,2)! Get Vbe and Ib data from Unit 1 380 ENTER 717;Reading(I,3) ! Get Ic data from Unit 2 390 NEXT I I Loop back for next readings OUTPUT 716; "NØX" 400 ! Turn off Unit 1 output 410 OUTPUT 717; "NØX" | Turn off Unit 2 output 420 PRINT "Press CONT to display graph" 430 PRINT "Press CONT while in graph to return to BASIC" 440 ! Take LOG values of Ib and Ic FOR I=1 TO 71 450 IF Reading(I,2)<1.E-14 THEN Reading(I,2)=1.E-14 ! Set Ib noise floor 460 IF Reading(I,3)<1.E-14 THEN Reading(I,3)=1.E-14 ! Set Ic noise floor 470 Reading(I,2)=LGT(Reading(I,2)) ! Take common log of Ib 480 Reading(I,3)=LGT(Reading(I,3)) ! Take common log of Ic 490 NEXT I ! Loop back for next data point 500 PAUSE Ymin=MAXREAL 510 Find minimum Ib and maximum Ic value

520 Ymax=~MAXREAL 530 FOR I=1 TO 71 ! Loop for all 71 points 540 IF Reading(I,2)<Ymin THEN Ymin=Reading(I,2) ! Check Ymin against Ib 550 IF Reading(I,3)>Ymax THEN Ymax=Reading(I,3) ! Check Ymax against Ic 560 NEXT I ! Loop back for next point 570 Ymax=INT(Ymax)+1 1 Scale Ymax to even power of 10 Ymin=INT(Ymin) 580 ! Scale Ymin to even power of 10 OUTPUT KBD;CHR\$(255);CHR\$(75); | Clear screen 590 600 GINIT ! Initialize graphics PLOTTER IS CRT, "INTERNAL" 610 ! Define plot to CRT 620 GRAPHICS ON ! Turn on graphics 630 MOVE 55,90 ! Title graph 640 LABEL "Ib,Ic VS. Vbe" 650 MOVE 70.10 ! Label X axis LABEL "Vbe" 660 670 MOVE 0,53 ! Label Y axis 680 LABEL "I" 690 VIEWPORT 30,120,20,85 | Define soft clip limits 700 WINDOW Vstop, Vstart, Ymin, Ymax ! Scale graph 710 $Y_{1} = 1$! Define Y axis scaling increment 720 Y2=Ymin ! Define Y axis label value increment 730 Y3=ABS((Ymax-Ymin)/12) 1 Define Y axis label spacing increment 740 X1=(Vstart-Vstop)/7 ! Compute X axis increment 750 GRID X1,Y1,Vstop,Ymin ! Draw grid 760 FOR I=71 TO 1 STEP -1 ! Loop for all 71 points 770 PLOT Reading(I,1), Reading(I,2) ! Plot Ib point 780 NEXT I ! Plot next Ib point 790 PENUP | Raise pen 800 FOR I=71 TO 1 STEP -1 ! Loop for all 71 points 810 PLOT Reading(I,1),Reading(I,3) ! Plot Ic point 820 NEXT I ! Plot next Ic point 830 CSIZE 4 ! Define character size 840 LORG 6 1 Center characters | Turn off soft clipping 850 CLIP OFF 860 FOR I=Vstop TO Vstart+.01*X1 STEP X1 ! Number X axis 870 MOVE I, Ymin-(Y3/4) 880 LABEL USING "#,K";I 890 NEXT I 900 FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis 910 MOVE Vstop-(.95*X1),I+(.3*Y3) 920 CSIZE 4.5 930 LABEL "10" 940 MOVE Vstop-(.5*X1),I+(.35*Y3) 950 CSIZE 3 960 LABEL USING "#,K";I 970 NEXT I 980 PAUSE 990 OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear alpha screen. 1000 GRAPHICS OFF ! Clear graphics screen 1010 END

3.6 CURRENT GAIN

The following paragraphs discuss two methods for determining dc current gain, as well as ways to measure ac current gain.

3.6.1 Gain Calculations

The common-emitter dc current gain of a bipolar transistor is simply the ratio of the dc collector current to the dc base current of the device. The dc current gain is calculated as follows:

$$\beta = \frac{I_{C}}{I_{B}}$$

 $\begin{array}{ll} \mbox{Where:} & \beta = \mbox{current gain} \\ & I_C = \mbox{dc collector current} \\ & I_B = \mbox{dc base current} \end{array}$

Often the differential or ac current gain is used instead of the dc value because it more closely approximates the performance of the transistor under small-signal ac conditions. In order to determine the differential current gain, two values of collector current (I_{C1} and I_{C2}) at two different base currents (I_{B1} and I_{B2}) are measured. The current gain is then calculated as follows:

$$\beta_{ac} = \frac{\Delta I_{C}}{\Delta I_{B}}$$

 $\begin{array}{ll} \mbox{Where:} & \beta_{ac} = ac \mbox{ current gain} \\ & \Delta I_C = I_{C2}\text{-}I_{C1} \\ & \Delta I_B = I_{B2}\text{-}I_{B1} \end{array}$

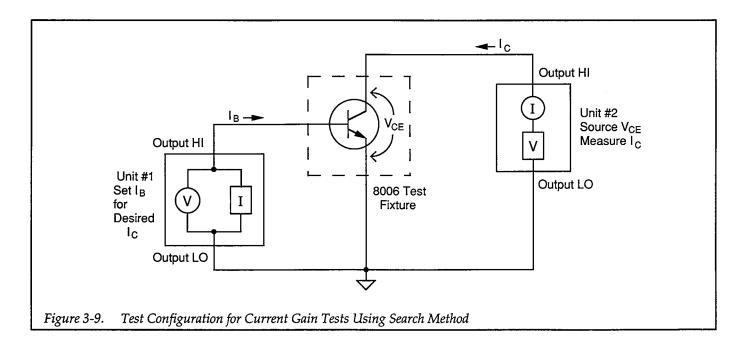
Test for both dc and ac current gain are generally done at one specific value of V_{CE}. Ac current gain tests should be performed with as small a ΔI_B as possible so that the device remains in the linear region of the curve.

3.6.2 Test Configuration for Search Method

Figure 3-9 shows the test configuration for the search method of dc current gain tests and ac gain tests. Unit #1 is used to supply I_{B1} and I_{B2} . Unit #2 sources V_{CE} , and it also measures the collector currents I_{C1} and I_{C2} .

3.6.3 Measurement Considerations

When entering the test base currents, take care not to enter values that will saturate the device. The approximate base current value can be determined by dividing the desired collector current value by the typical current gain for the transistor being tested.



3.6.4 Program 6A: Dc Current Gain Using Search Method

Use Program 6A to perform dc current gain tests on bipolar transistors. Proceed as follows:

- 1. With the power off, connect both Model 236 Source Measure Units to the IEEE-488 bus of the computer.
- 2. Connect the test fixture to both units using appropriate triax cables (see Figure 3-1 for details on test connections).
- 3. Turn on both Source Measure Units, and allow them to warm up for at least two hours for rated accuracy. Be sure that the primary address of Unit #1 is set to 16, and that the primary address of Unit #2 is set to 17.
- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines below into the computer
- 6. Install a small-signal NPN silicon transistor such as a 2N5089 in the desire test fixture socket. Install the required jumpers, then close the test fixture lid.
- 7. RUN the program, and follow the prompts on the screen. You will be prompted to enter the desired maximum and minimum base current values for the I_C search as well as the target collector current value, and the desired value of V_{CE}. When entering the base currents, keep the approximate current gain of the device in mind so as not to saturate the device. Also, enter a sufficient base current range to allow a successful search.
- 8. Once the parameters are entered, the units will be programmed accordingly, and the collector current of the device will be measured. The program will perform an iterative search to determine the closest match to the target I_C (within ±5%). The dc current gain of the device at specific I_B and I_C values will then be displayed on the computer CRT. If the search is unsuccessful, rerun the program with a more appropriate set of base current values.

3.6.5 Typical Program 6A Results

A typical current gain for a 2N5089 would be about 500. Note however, that the current gain of the device could be as low as 300 or as high as 800.

3.6.6 Program 6A Description

For the following description, refer to the flowchart shown in Figure 3-10 and the Program 6A listing shown

below.

Initially, the iteration variables are defined (lines 20 and 30), and both units are returned to default conditions (line 40). Unit #1, which sources I_B , is set up as follows (lines 70-120):

- Source I, dc mode
- 1V compliance, 1.1V range
- Local sense
- GET trigger, continuous
- Dc current mode, value determined by user-input $I_{\mbox{\scriptsize B}}$ value

The user is then prompted to enter the minimum and maximum I_B values, as well as the target I_c .

Following Unit #1 setup, Unit #2, which sources V_{CE} and measures I_{C} , is configured as follows (lines 180-250):

- Source V, dc mode
- Local sense
- 100mA compliance, autorange measure
- Source only data format, no prefix, dc data output
- Trigger on GET, continuous
- Dc voltage, value determined by user-input $V_{\mbox{\scriptsize CE}}$ value
- Two-second delay

Once the operator signals to continue the program (lines 260 and 270), both Source Measure Unit triggers are armed and the units are placed into operate (lines 280 and 290). Next, the units are triggered (lines 310-320), and the iteration counter is incremented and tested against the programmed limit (lines 330 and 340). If the number of iterations has been exceeded, a message to that effect is displayed, and the program halts.

Assuming that the number of iterations has not been exceeded, Unit #1 is programmed with the base current value (line 390), and, after a two-second delay (line 410), the status byte is obtained from Unit #2 (line 420). Bit 7 in the status byte is then checked (lines 410-450) to see if it is set. If so, Unit #2 is over compliance, the operator is then notified, and the program is halted.

Assuming no error, the value of I_C is requested (line 470), and the value is checked against the target (lines 480-570) to see if it is within $\pm 5\%$. If no match is found, a new I_B value is computed, and the program loops back to per-

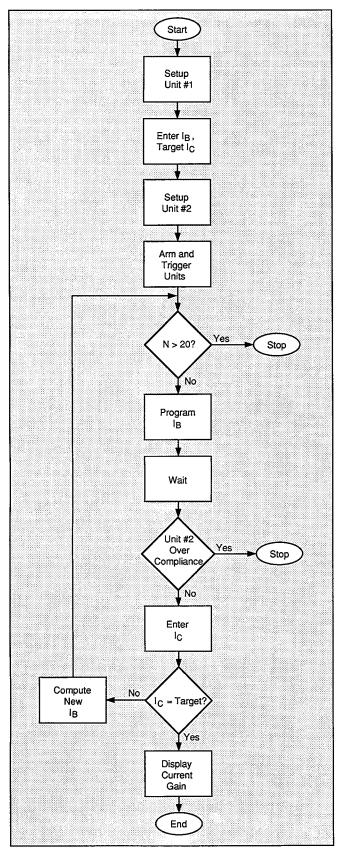


Figure 3-10. Program 6A Flowchart

form the test again at the new value. Finally, both units are placed into standby (lines 580 and 590), and the dc current gain is calculated and displayed (line 600).

3.6.7 Modifying Program 6A

For demonstration purposes, the I_C target match tolerance is set to $\pm 5\%$. You can, of course, change this tolerance as required. Similarly, the iteration limit is set to 20. Again, this value can be adjusted for greater or fewer iterations as necessary. Note that it may be necessary to increase the number of iterations if the target range is reduced.

3.6.8 Configuration for Fast Current Gain Tests

Figure 3-11 shows the test configuration for an alternate method of current gain tests -- one that is much faster than the search method discussed previously. Unit #1 is used to supply V_{CE} , and it also measures I_B. Unit #2 sources the emitter current, I_E, rather than the collector current, I_C. Since we are sourcing emitter current instead of collector current, the current gain calculations must be modified as follows:

$$\beta = \frac{I_E - I_B}{I_B}$$

WARNING

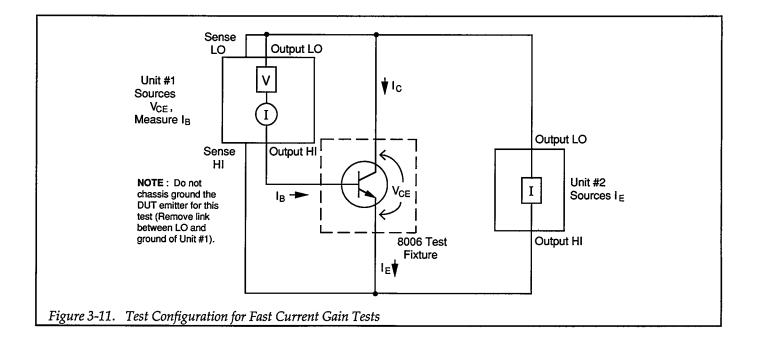
When a Model 236/237 is programmed for remote sensing, hazardous voltage may be present on the SENSE and OUTPUT terminals when the unit is in operate regardless of the programmed voltage or current. To avoid a possible shock hazard, always turn off all power before connecting or disconnecting cables to the Source Measure Unit or the associated test fixture.

NOTE

Because of the connection convention used, I_E and V_{CE} must be programmed for opposite polarity than normal. With an NPN transistor, for example, both V_{CE} and I_E must be negative.

```
10
      REM SEARCH METHOD DC CURRENT GAIN TEST PROGRAM REV. 1.3 (Program 6A)
20
      Iterations=20
                                     ! Define number of iterations
30
      N=0
                                     ! Iteration counter
40
      CLEAR 7
                                     ! Clear both Units
      OUTPUT KBD; CHR$(255); CHR$(75); ! Clear screen
50
60
      70
                                     ! Put Unit 1 in remote
      REMOTE 716
80
      OUTPUT 716; "F1,0X"
                                     ! Source I, DC mode
90
      OUTPUT 716; "L1,1X"
                                    1 1V compliance, 1.1V range
      OUTPUT 716; "00Z0X"
100
                                     ! Local sense, suppress off
110
      OUTPUT 716; "T1,0,0,0X"
                                     ! GET trigger, continuous
120
      D1y=2000
                                     ! Define 2sec Unit delay
      INPUT "Enter maximum base current", Ib1 | Input max search Ib
INPUT "Enter minimum base current", Ib2 | Input min search Ib
130
140
150
      Ib=(Ib1-Ib2)/2+Ib2
                                     ! Compute start Ib
      INPUT "Enter target Ic value", Itarget ! Input target Ic
160
170
      REMOTE 717
180
                                     ! Put Unit 2 in remote
190
      OUTPUT 717; "F0,0X"
                                     ! Source V, DC mode
      OUTPUT 717; "00M128,0X"
200
                                    ! Local sensing,SRQ.
210
      OUTPUT 717; "L100E-3,0X"
                                    ! 100mA compliance,autorange measure
      OUTPUT 717; "G4,2,0Z0X"
220
                                    ! Measure, no prefix, DC data, suppress off
230
      OUTPUT 717; "T1,0,0,0X"
                                    ! Trigger on GET, continuous
240
      INPUT "Enter Vce",Vce
                                    ! Input Vce
250
      OUTPUT 717; "B"; Vce; ",0, "; Dly; "X" ! Program DC, autorange, delay
260
      PRINT "Close lid, press CONT to begin test"
270
      PAUSE
280
      OUTPUT 716; "RINIX"
                                     ! Arm Unit 1 trigger, turn on output
290
      OUTPUT 717; "RINIX"
                                     ! Arm Unit 2 trigger, turn on output
300
      PRINT "Measuring..."
                                     1 Trigger Unit 1
310
      TRIGGER 716
320
      TRIGGER 717
                                     ! Trigger Unit 2
330
      N=N+1
                                     ! Increment iteration counter
340
      IF N>Iterations THEN
                                     | Check for maximum iterations
350
      BEEP
360
      PRINT "More than"; Iterations; "iterations"
370
      STOP
380
      END IF
390
      OUTPUT 716; "B"; Ib; ",0, "; Dly; "X" ! Program Ib
400
      WAIT D1y/1000+1
                                     ! Wait for settling
410
      Stat=SPOLL(717)
                                     ! Serial poll Unit 2
420
      IF BIT(Stat,7) THEN
                                     ! Check for over compliance
430
      BEEP
440
     PRINT "Unit 2 is over current compliance"
450
     STOP
460
     END IF
470
     ENTER 717; Ic
                                     ! Get Ic reading from Unit 2
     IF Ic>1.05*Itarget THEN
480
                                    ! Check for Ic > target
490
     Ibi=Ib
500
     Ib=Ib-(Ib-Ib2)/10
```

```
510
      GOTO 330
      END IF
520
530
      IF Ic<.95*Itarget THEN
                                    ! Check for Ic < target</p>
540
      Ib2=Ib
550
      Ib=Ib+(Ib1-Ib)/10
560
      GOTO 330
570
      END IF
580
      OUTPUT 716; "NØX"
      OUTPUT 717; "NØX"
                                    ! Turn off Unit 1 output
590
                                    ! Turn off Unit 2 output
      PRINT "Current gain (@ Ib=";Ib;"Ic=";Ic;"):";Ic/Ib ! Display current gain
600
610
      END
```



3.6.9 Program 6B: Dc Current Gain Using Fast Method

Use Program 6B below to demonstrate the fast method of measuring current gain of bipolar transistors. Proceed as follows:

- 1. With the power off, connect both Model 236 Source Measure Units to the IEEE-488 bus of the computer.
- 2. Connect the test fixture to both units using appropriate triax cables (see Figure 3-1 and Figure 3-11 for details on instrument and test fixture connections). Note that OUTPUT HI of Unit #1 is connected to the base of the DUT, while SENSE HI of Unit #1 is connected to the emitter.
- 3. Turn on both Source Measure Units, and allow them to warm up for at least two hours for rated accuracy. Be sure that the primary address of Unit #1 is set to 16, and that the primary address of Unit #2 is set to 17.
- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines below into the computer
- 6. Install a small-signal NPN silicon transistor such as a 2N3904 or 2N5089 in the desired test fixture socket. Install the required jumpers (use Figure 3-11 as a guide), then close the test fixture lid.
- 7. RUN the program as usual. The emitter current will be swept between 1mA and 10mA at 1mA incre-

ments. At each I_E value, the base current will be measured by Unit #1.

8. After the parameters are measured, the computer will request the test data from the units, and the emitter current and gain values will be displayed on the computer CRT. Note that the program reverses the polarity of the emitter currents in order to display true polarity.

3.6.10 Program 6B Description

For the following description, refer to the flowchart shown in Figure 3-12 and the Program 6B listing shown below.

Initially, both units are returned to default conditions (line 20). Unit #1, which sources V_{CE} and measures I_B , is set up as follows (lines 50-130):

- Source V, sweep mode
- 1mA compliance, autorange measure
- Remote sense
- External trigger, source phase start, output trigger end of measure
- Measure only data format, no prefix or suffix, sweep data
- 10msec delay
- Constant sweep mode, $V_{CE} = -10V$, constant sweep with 10 points.

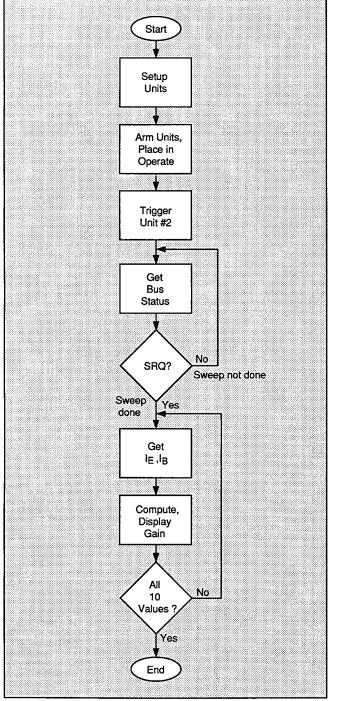


Figure 3-12. Program 6B Flowchart

Following Unit #1 setup, Unit #2, which sources I_E , is configured as follows (lines 150 -260):

- Source I, sweep mode
- Local sense
- 11V compliance, 11V range
- Source only data format, no prefix, sweep data output
- External trigger, start source phase, trigger out end of delay
- SRQ on sweep done
- Start current: –1mA
- Stop current: -10mA
- Step current: -1mA
- 10msec delay
- Staircase sweep mode

Once the operator signals to continue the program (lines 270 and 280), both Source Measure Unit triggers are armed and the units are placed into operate (lines 290 and 300). Next, Unit #2 is triggered to start the sweep (line 310), and the program enters a loop to wait for SRQ on sweep done (lines 330 and 340).

When the SRQ occurs, Unit #2 is serial polled in order to clear the SRQ (line 340), and both units are placed into standby (lines 350 and 360). The I_B and I_E values are requested (lines 410 and 420), and the current gain for each set of values is computed and displayed (line 430).

3.6.11 Modifying Program 6B

As written, the range of emitter current values is between -1mA and -10mA at -1mA increments. You can, of course, modify these values as required. Additional program modifications may be required if these parameters are changed. You could also add graphing capabilities to the program to plot current gain as a function of collector current by modifying the plotting routines from one of the other applications programs in this manual.

10 REM HIGH-SPEED DC CURRENT GAIN TEST PROGRAM REV. 1.3 (Program 6B) 20 CLEAR 7 ! Clear both Units 30 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 40 50 REMOTE 716 | Put Unit 1 in remote OUTPUT 716; "F0,1X" 60 I Source V, sweep mode OUTPUT 716; "L1E-3,0X" ! 1mA compliance, autorange measure 70 OUTPUT 716; "01Z0X" 80 ! Remote sense, suppress off OUTPUT 716; "T3,1,4,0X" OUTPUT 716; "G4,2,1X" ! External trigger, out trig end of meas 90 100 ! Measure only,no prefix,sweep data 101 OUTPUT 716; "B0,0,0X" ! Program Ø bias value 110 | Define -10V Vce Vce=-10 120 D1v=10 ! Define 10msec delay 130 OUTPUT 716; "Q0,"; Vce; ",0,"; Dly; ",10X" ! Program fixed sweep, 10 points 140 150 REMOTE 717 ! Put Unit 2 in remote OUTPUT 717; "F1,1X" 160 ! Source I, sweep mode OUTPUT 717;"00Z0X" 170 ! Local sensing, suppress off | 11V compliance, 11V range | Source,no prefix,sweep data OUTPUT 717;"L11,2X" 180 OUTPUT 717; "G1,2,1X" OUTPUT 717; "T3,1,2,0X" OUTPUT 717; "M2,X" OUTPUT 717; "B0,0,0X" Istant=-1 5-7 190 ! External trigger, out trig end of delay 200 210 ! SRQ on sweep done ! Program Ø bias value 215 220 Istart=-1.E-3 I Define -1mA start le current 230 Istop=-1.0E-2 ! Define -10mA stop Ie current 240 | Define -1mA step Ie current Istep=-1.E-3 250 Dly=10 | Define 10msec delay OUTPUT 717;"Q1,";Istart;",";Istop;",";Istep;",0,";Dly;"X" 260 270 PRINT "Close lid, press CONT to begin test" 280 PAUSE 290 OUTPUT 716; "RIN1X" ! Arm Unit 1 trigger, turn on output 300 OUTPUT 717; "RINIX" | Arm Unit 2 trigger, turn on output 310 OUTPUT 717;"HØX" ! Trigger Unit 2 to start sweep ! Get bus status 320 STATUS 7,7;Stat 330 IF NOT BIT(Stat,10) THEN 320 | Wait for SRQ 340 Stat=SPOLL(717) Serial poll Unit 2 to clear SRQ ! Turn off Unit 1 output,local sense ! Turn off Unit 2 output 350 OUTPUT 716; "N000X" 360 OUTPUT 717; "NØX" 370 PRINT "Ie","GAIN" PRINT "-----" 380 390 PRINT 400 FOR I=1 TO 10 ! Get base current from Unit 1 ! Get emitter current from Unit 2 410 ENTER 716; Ib 420 ENTER 717;Ie PRINT -Ie,(-Ie-Ib)/Ib Compute/display gain 430 440 NEXT I 450 END

3.6.12 Program 7: Ac Current Gain

NOTE

For the sake of simplicity, this program does not include the iterative search algorithm included in Program 6A. To test at a specific I_C value, first use Program 6A to determine the base current at that target value, and enter I_B values slightly above and below when prompted to do so in Program 7.

- 1. With the power off, connect both Model 236 Source Measure Units to the IEEE-488 bus of the computer.
- 2. Connect the test fixture to both units using appropriate triax cables (see Figure 3-1 and Figure 3-9 for details on test connections).
- 3. Turn on both Source Measure Units, and allow them to warm up for at least two hours for rated accuracy. Be sure that the primary address of Unit #1 is set to 16, and that the primary address of Unit #2 is set to 17.
- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines below into the computer
- 6. Install a small-signal NPN silicon transistor in the desired test fixture socket. Install the required jumpers, then close the test fixture lid.
- 7. RUN the program, and follow the prompts on the screen. You will be prompted to enter two base current values and then the desired value of V_{CE} . When entering the base current, keep the the two values as close together as possible so that the device remains in its linear operating region. A change in I_B of about 20% from one value to another would be a good starting point.
- 8. Once the parameters are entered, the units will be programmed accordingly, and both the collector currents of the device (one at each base current value) will be measured. The ac current gain of the device will then be displayed on the computer CRT.

3.6.13 Typical Program 7 Results

The differential current gain obtained for a given sample of a 2N5089 NPN transistor would typically be about the same as the dc current gain-about 500. Again, values could range from a low of 300--to a high of 800 or so.

3.6.14 Program 7 Description

For the following description, refer to the flowchart shown in Figure 3-13 and the Program 7 listing shown below.

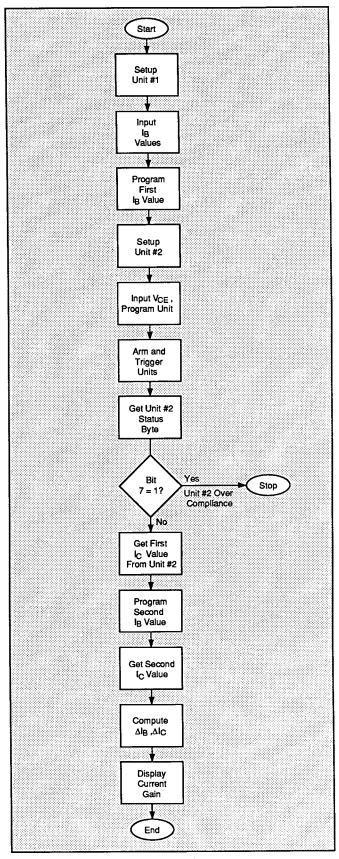


Figure 3-13. Program 7 Flowchart

After both units are returned to default conditions (line 20), Unit #1 is set up as follows (lines 50-120):

- Source I, dc mode
- 1V compliance, 1.1V range
- Local sense
- GET trigger, continuous
- Dc current mode, IB values determined by user input

Following Unit #1 setup, Unit #2 is configured as follows (lines 140-200):

- Source V, dc mode
- Local sense
- 100mA compliance
- Source only data format, no prefix, dc data output
- Trigger on GET, continuous
- Two-second source-measure delay
- Dc voltage, value determined by user-input V_{CE} value

Once the operator signals to continue the program (lines 230 and 240), both Source Measure Unit triggers are armed and the units are placed into operate (lines 250 and 260). Next, the units are triggered (lines 280 and 290), and

the status byte is obtained from Unit #2 (line 310). Bit 7 in the status byte is then checked (lines 320-350) to see if it is set. If so, Unit #2 is over compliance, the operator is then notified, and the program is halted.

Assuming no error, the value of I_{C1} is requested (line 370), and Unit #1 is programmed with the second base current value, I_{B2} (line 380). The second collector current, I_{C2} , is then requested from the unit (line 400), and ΔI_B and ΔI_C are then computed (lines 410 and 420). Both units are placed into standby (lines 430 and 440), and, finally, the differential current gain is calculated and displayed (line 450).

3.6.15 Modifying Program 7

As with the dc current gain, ac current gain is often tested at specific values of I_C. Again, a search algorithm similar to the one in Program 6A could be added to the program. Such an algorithm would allow you to enter the desired collector current values, and it would then perform an iterative search to automatically determine the two correct base current values that would result in the desired collector currents.

REM DIFFERENTIAL CURRENT GAIN TEST PROGRAM REV. 1.3 (Program 7) 10 20 CLEAR 7 ! Clear both Units 30 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 40 50 REMOTE 716 ! Put Unit 1 in remote 60 OUTPUT 716; "F1,0X" ! Source I, DC mode 70 OUTPUT 716; "L1,1X" 1 1V compliance, 1.1V range 80 OUTPUT 716;"00X" ! Local sense 90 OUTPUT 716; "T1,0,0,0X" | GET trigger,continuous 100 INPUT "Enter first base current", Ib1 ! Input first base current 110 INPUT "Enter second base current", Ib2! Input second base current 120 OUTPUT 716; "B"; Ib1; ",0,0X" ! Program DC value, autorange, delay 130 140 REMOTE 717 ! Put Unit 2 in remote 150 OUTPUT 717; "F0,0X" I Source V, DC mode 160 OUTPUT 717; "00M128,0Z0X" ! Local sensing,SRQ,suppress off 170 OUTPUT 717; "L100E-3,0X" 100mA compliance,autorange measure 180 OUTPUT 717; "G4,2,0X" ! Measure,no prefix,DC data OUTPUT 717;"T1,0,0,0X" 190 ! Trigger on GET,continuous 200 D1y=2000 ! Define 2sec Unit 2 delay INPUT "Enter Vce",Vce ! Input Vce 210 220 OUTPUT 717; "B"; Vce; ",0,"; Dly; "X" ! Program DC, autorange, delay 230 PRINT "Close lid, press CONT to begin test" 240 PAUSE OUTPUT 716; "RINIX" 250 ! Arm Unit 1 trigger, turn on output 260 OUTPUT 717; "RINIX" ! Arm Unit 2 trigger, turn on output 270 PRINT "Measuring..." 280 TRIGGER 716 ! Trigger Unit 1 290 TRIGGER 717 ! Trigger Unit 2 300 WAIT D1y/1000+1 ! Settling time 310 Stat=SPOLL(717) ! Serial poll Unit 2 320 IF BIT(Stat,7) THEN ! Check for over compliance 330 BEEP 340 PRINT "Unit is over current compliance" 350 STOP 36Ø END IF 370 ENTER 717:Ic1 | Get first Ic reading from Unit 2 380 OUTPUT 716; "B"; Ib2; ",0,"; Dly; "X" ! Program Unit 1 for second Ib value 390 WAIT 2 ! Wait two second for settling 400 ENTER 717; Ic2 | Get second Ic reading from Unit 2 410 Delta_ib=ABS(Ib2-Ib1) ! Compute delta Ib 420 Delta_ic=ABS(Ic2-Ic1) I Compute delta Ic OUTPUT 716; "NØX" 430 ! Turn off Unit 1 output 440 ! Turn off Unit 2 output OUTPUT 717; "NØX" 450 PRINT "Differential current gain=";Delta_ic/Delta_ib ! Display gain 460 END

3.7 TRANSISTOR LEAKAGE CURRENT

Leakage currents, such as I_{CBO} (collector-base, emitter open) and I_{CEO} (collector-emitter, base open) can be tested using a single Source Measure Unit. The following paragraphs discuss I_{CEO} tests and also include an example program for making such tests.

3.7.1 Test Configuration

Figure 3-14 shows the basic test configuration for performing I_{CEO} tests. Note that only one Source Measure Unit is required to make such tests. The Source Measure Unit sources the collector-emitter voltage, V_{CEO} , and the instrument also measures I_{CEO} . Often, V_{CEO} is swept across the desired range of values, and the resulting I_{CEO} values are plotted against V_{CEO} , as is the case with the example program included in this section.

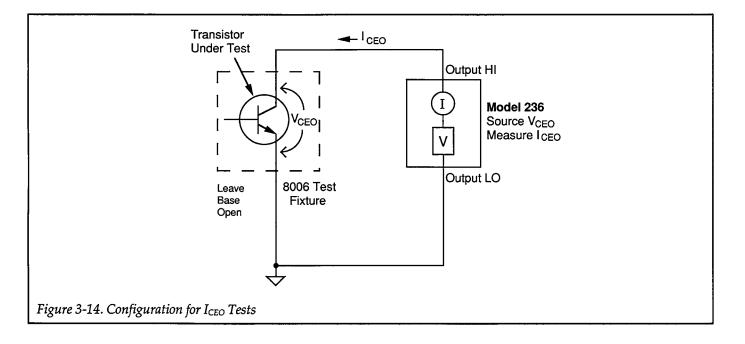
The base of the transistor should be left open. The same general circuit configuration can be used to measure I_{CBO} ; connect the Source Measure Unit between the collector and base, and leave the emitter open instead.

Breakdown tests can also be performed using the same I_{CEO} circuit setup. In this case, the Source Measure Unit is used to source I and measured the breakdown voltage, V, in order to better control device power at breakdown.

3.7.2 Program 8: ICEO Test

Use Program 8 below to run I_{CEO} tests on bipolar transistors. Follow the steps below to run the program.

- 1. With the power off, connect the Model 236 Source Measure Unit to the IEEE-488 interface of the computer.
- 2. Connect the test fixture to the Source Measure Unit using appropriate triax cables (see Figure 2-1 for details on single-unit connections).
- 3. Turn on the Model 236 Source Measure Unit, and allow the unit to warm up for two hours for rated accuracy. Make sure the primary address of the unit is set to 16.
- 4. Turn on the computer, and boot up BASIC.
- 5. Enter the lines below into the computer.
- 6. Install a small-signal NPN silicon transistor such as a 2N3904 in the appropriate transistor socket of the test fixture. Be certain that the jumpers are properly installed to collector and emitter only (the base terminal should be left open), then close the test fixture lid.
- 7. RUN the program in the usual manner. The computer will program the unit and run the test on the device. V_{CEO} will be swept between 0V and 10V in 0.1V increments, and I_{CEO} will be measured at each V_{CEO} value. A fixed delay of 100msec is also incorporated into the program. Because of the low current levels involved, line-cycle integration is used to reduce noise levels.
- 8. Once the sweep has been completed, you will be prompted to press CONT to generate a plot of the

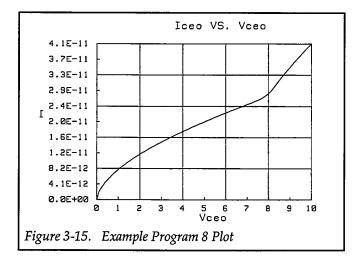


data. A simple $I_{\mbox{\tiny CEO}}$ vs. $V_{\mbox{\tiny CEO}}$ plot will then be displayed on the computer CRT.

- 9. To return to BASIC from the graph, press CONT.
- Stop V_{CEO} voltage: 10V
- Step V_{CEO} voltage: 0.1V
- Staircase sweep mode

3.7.3 Typical Program 8 Results

Figure 3-15 shows an example I_{CEO} vs. V_{CEO} plot generated by Program 8. The device used for this example was a 2N3904 NPN transistor.



3.7.4 Program 8 Description

Refer to Figure 3-16 and the listing below for the following description.

At the start of the program, the array is set up to handle 101 data points with two values for each point (lines 20 and 30). After being cleared (line 40), the Source Measure Unit, which sweeps V_{CEO} and measures I_{CEO} , is set up as follows:

- Source V, sweep mode
- Local sense, trigger on GET, continuous
- 10mA compliance, autorange measure
- Source and measure data format, no prefix, sweep data
- SRQ on sweep done
- Line cycle integration
- Suppress on (to null offset current)
- Start V_{CEO} voltage: 0V

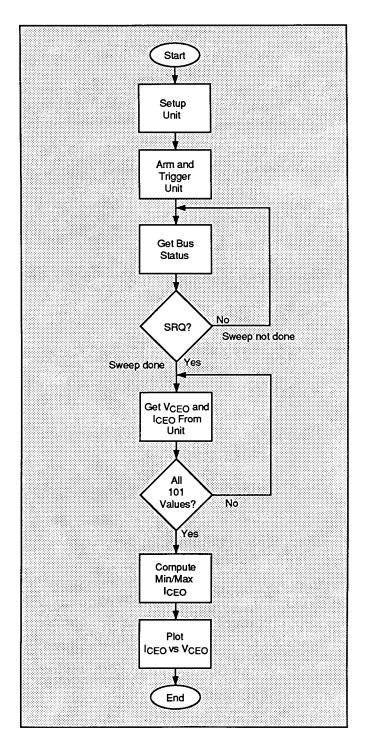


Figure 3-16. Program 8 Flowchart

After the start signal from the operator (lines 190 and 200), the trigger is armed (line 210) and the unit is placed into operate (line 220). Next, the unit is triggered to begin the sweep (line 230), and the program enters a loop waiting for the unit to generate an SRQ on sweep done (lines 250-260).

When the sweep is done, the unit generates the SRQ, the program falls through the loop, and it then serial polls the unit to clear the SRQ (line 270). The unit is placed in standby (line 280), and the program enters a loop to request sweep data from the instrument (lines 290-310). Note that V_{CEO} values are placed into elements (I,1), and I_{CEO} values are stored in elements (I,2) of the reading array.

The maximum and minimum I_{CEO} values are then determined (lines 340-370, and the data is then graphed on the

computer CRT (lines 420-670). A simple plot, scaled to maximum and minimum I_{CEO} and V_{CEO} values is generated on the computer CRT.

3.7.5 Modifying Program 8

For different sweep values, simply modify the Vstart, Vstop, and Vstep values and source range parameter as appropriate. As an alternative, you can add INPUT statements with appropriate error checking to allow operator input of these parameters.

In order to speed up the test procedure, you may wish to use a faster integration period. Simply change the command string in line 120 as appropriate. Note, however, that changing this parameter may result in unacceptable reading noise.

	· · · · · · · · · · · · · · · · · · ·	
10	REM BIPOLAR TRANSISTOR LEAKAGE TES	T PROGRAM REV. 1.3 (Program 8)
20		! First array subscript is 1
30		! Dimension reading array (101 pts.)
40		Clear 236
50		! Put 236 in remote
60		! Clear screen [.]
70		! Source V, sweep mode
80		! Local sense, trigger on GET
90		10mA compliance, autorange measure
100	•	! Source,measure,no prefix,sweep data
110		! SRQ on sweep done
120		! Line cycle integration
125		! Program Ø bias value
130		! Enable suppress
140		! Define ØV start voltage
150		! Define 10V stop voltage
160		! Define 0.1V step voltage
170	,	! Define 100msec delay value
180		,";Vstep;",0,";Dly;"X" ! Program sweep
190	PRINT "Close lid, press CONT to beg.	
200		! Wait to continue
210		Arm trigger
220		Turn on 236 output
230		! Trigger 236
240	PRINT "Waiting for sweep to end"	
250		! Get IEEE-488 bus status
260	IF NOT BIT(Stat,10) THEN 250	
270	-	! Serial poll 236 to clear SRQ
280		! Turn off 236 output
290		! Loop for all readings
300		! Get Vceo and Iceo values from Unit
310		! Loop back for next reading
320		! Find minimum and maximum Iceo
330	Ymax=-MAXREAL	
340	FOR I=1 TO 101	
350	IF Reading(I,2) <ymin td="" then="" ymin≑reading(i,2)<=""></ymin>	
360	IF Reading(I,2)>Ymax THEN Ymax=Reading(I,2)	
370	NEXT I	
380	PRINT "Press CONT to display graph"	
390	PRINT "Press CONT while in graph to	return to BASIC"
400	PAUSE	
410		! Clear screen
420		! Initialize graphics
430		! Define plot to CRT
440	•	! Turn on graphics
450		! Title graph
460	LABEL "Iceo VS. Vceo"	
470		! Label X axis
480	LABEL "Vceo"	
490		! Label Y axis
500	LABEL "I"	

```
510
      VIEWPORT 30,120,20,85
                                          ! Define soft clip limits
520
      WINDOW Vstart,Vstop,Ymin,Ymax
                                          ! Scale graph
530
      Y1=(Ymax-Ymin)/10
                                          ! Compute Y axis increment
      X1=(Vstop-Vstart)/10
540
                                          ! Compute X axis increment
550
      GRID 2*X1,2*Y1,Vstart,Ymin
                                          ! Draw grid
560
      AXES X1,Y1,Ustart,Ymin
                                          ! Add some tick marks
570
      PLOT Reading(*)
                                          ! Plot data
580
      CSIZE 4
                                          ! Define character size
590
     LORG 5
                                          ! Center characters
      CLIP OFF
                                          ! Turn off soft clipping
600
610
      FOR I=Vstart TO Vstop+.01*X1 STEP X1 ! Number X axis
620
      MOVE I, Ymin-(Y1/4)
630
      LABEL USING "#,K";I
640
      NEXT I
650
      FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis
660
      MOVE Vstart+(1.3*X1),I+(.3*Y1)
670
      LABEL USING "#,MD.DE";I
680
      NEXT I
690
      PAUSE
700
      OUTPUT KBD;CHR$(255);CHR$(75);
                                        ! Clear alpha screen
710
      GRAPHICS OFF
                                          ! Clear graphics screen
720
      END
```

SECTION 4 FET Tests

4.1 INTRODUCTION

FET tests discussed in this section include: tests to generate common-source characteristic curves, and transconductance tests. Example programs for each of these applications are also included.

4.2 INSTRUMENT CONNECTIONS

Figure 4-1 shows the instrument connections for the FET tests outlined in this section. Note that these connections are essentially identical to the connections used for the bipolar transistor tests discussed in Section 3. Two Model 236/237 Source Measure Units are required for the tests,

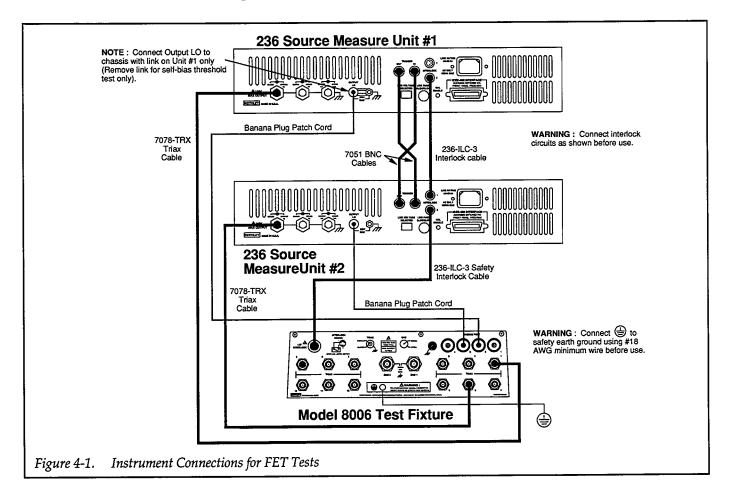
and, once again, the Model 8006 test fixture is recommended for connections to the FET under test.

A Model 7078-TRX-3 triax cables are recommended to make instrument-to-test fixture connections. In addition, the safety interlock connecting cable must be connected as shown.

WARNING

Lethal voltages may be exposed when the test fixture lid is open. To avoid a possible shock hazard, the safety interlock circuit must be connected as shown in Figure 4-1be-

fore use. Connect the fixture screw to safety earth ground using #18 AWG minimum wire before use. Turn off all power be-



fore connecting or disconnecting wires or cables

Two final connections that must be made are the unit trigger connections. Connect the TRIGGER OUT jack of Unit #1 to the TRIGGER IN jack of Unit #2, and connect the TRIGGER OUT jack of Unit #2 to the TRIGGER IN jack of Unit #1. Use standard BNC-to-BNC cables such as the Model 7051 to make these connections.

NOTES

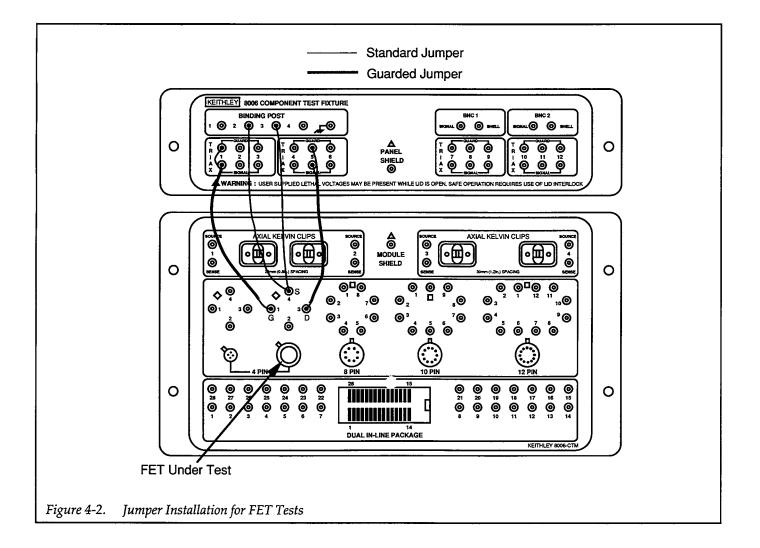
- 1. Remote sensing connections are recommended for optimum accuracy. See paragraph 1.2.2 for details.
- 2. If measurement noise is a problem, or for critical, low-level applications, use shielded cable for all signal connections.
- 3. The FET test programs use external triggering. If the trigger jacks are not connected as shown, the programs will not function properly.

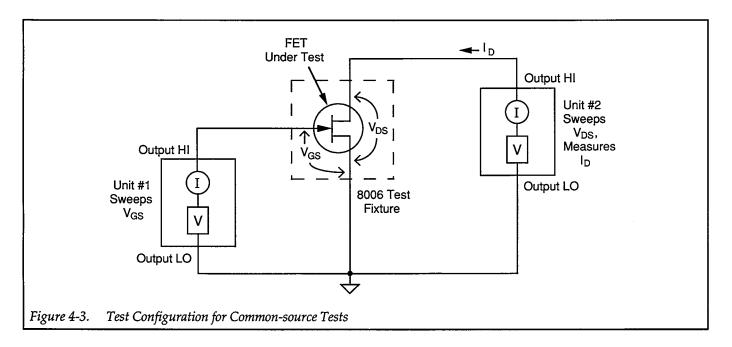
4.3 JUMPER INSTALLATION FOR FET TESTS

Figure 4-2 shows jumper installation for the transistor tests. The FET itself should be placed in the appropriate four-terminal TO package socket, and the jumper connections should be made between the instrument panel jacks and the jacks on the component panel. Note that local sensing is used for most applications, so jumpers should be connected as shown.

4.4 COMMON-SOURCE CHARACTERISTICS

One of the more common FET tests involving family of curves are common-source characteristics. Such tests are very similar to the common-emitter characteristic tests outlined earlier except, of course, for the fact that an FET rather than a bipolar transistor is involved.





Test data for common-source characteristics are obtained by sweeping the gate-source voltage, V_{GS} , across the desired range of values at specific increments. At each V_{GS} value, the drain-source voltage, V_{DS} is swept through the required range, once again at the desired increments. At each V_{DS} value, the drain current, I_D , is measured. Plots made from this data show I_D vs. V_{DS} with one curve for each value of V_{GS} .

4.4.1 Test Configuration

Figure 4-3 shows the test configuration for the commonsource tests. Unit #1 sweeps V_{GS} , while Unit #2 sweeps V_{DS} , and the instrument also measures I_D . For this programming example, a small-signal, N-channel JFET such as a 2N4392 is recommended.

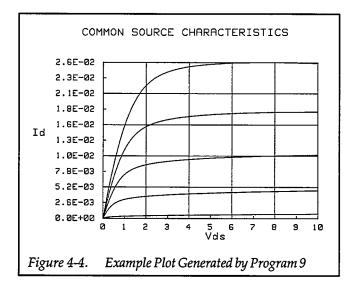
4.4.2 Program 9: Common-source Characteristics

Program 9 below outlines general programming techniques for measuring common-source characteristics. Follow the steps outlined below to use this program.

- 1. With the power off, connect both Source Measure Units to the IEEE-488 bus of the computer.
- 2. Connect both Source Measure Units to the test fixture using suitable triax cables (see Figure 4-1 for details on test connections).
- 3. Turn on both units, and allow them to warm up for at least two hours for rated accuracy. Verify that the primary address of Unit #1 is set to 16; the primary address of Unit #2 should be set to 17.
- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines from Program 9 below into the computer.
- 6. Place a small-signal N-channel JFET such as a 2N4392 in the appropriate transistor socket. Install the correct jumpers, then close the test fixture lid.
- 7. RUN the program in the usual fashion. The computer will step through V_{GS} values between -2V and 0V using 0.5V steps. At each V_{GS} step, V_{DS} will be stepped between 0V and 10V at 0.1V increments. At each increment, I_D will be measured. Once data are collected, a plot of I_D vs. V_{DS} for each V_{GS} value will be displayed.
- 8. To return to BASIC from the graph, press CONT.

4.4.3 Typical Program 9 Results

Figure 4-4 shows a typical plot generated by example Program 9. A 2N4392 N-channel JFET was used to generate these curves.



4.4.4 Program 9 Description

For the following description, refer to the Program 9 listing and the flowchart shown in Figure 4-5.

Initially, the array is set up for five sweeps of 101 data points each (lines 20 and 30), and the units are returned to default conditions (line 40). Next, Unit #1, which sweeps V_{GS} , is programmed as follows (lines 70-160):

- Source V, sweep mode
- 1mA compliance, 1mA range
- Local sense
- GET trigger, one trigger per point, output trigger end of delay
- Start V_{GS} voltage: –2V
- Stop V_{GS} voltage: 0V
- Step V_{GS} voltage: 0.5V
- Delay: 100msec
- Staircase sweep

Following Unit #1 setup, Unit #2, which sweeps V_{DS} and measures I_D , is configured as follows (lines 180-300):

- Source V, sweep mode
- Local sensing
- 100mA compliance, autorange measure

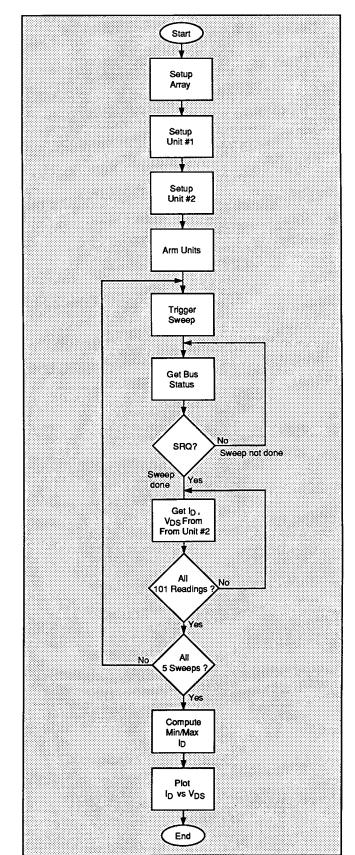


Figure 4-5. Program 9 Flowchart

- Source, measure data format, no prefix, sweep data output
- SRQ on sweep done
- External trigger, continuous
- Start V_{DS} voltage: 0V
- Stop V_{DS} voltage: 10V
- Step V_{DS} voltage: 0.1V
- Suppress enabled
- Line cycle integration
- Staircase sweep

Following setup of both units, the operator is prompted to begin the test (lines 310 and 320), and both units are armed and placed into operate (lines 330 and 340). Next, the program enters a loop to perform I_D vs. V_{DS} sweeps, one sweep for each value of V_{CS} (line 330).

Program 9 uses subordinate-sweep triggering to sequence through the sweeps. At the start of the main program loop, Unit #1 is GET triggered (line 370), at which point it sets its output to the current V_{GS} voltage step in the sweep list. At the end of the programmed delay period, Unit #1 outputs a trigger pulse that triggers Unit #2 via its external trigger input. Once triggered, Unit #2 goes through its sweep list of V_{DS} values, measuring and storing I_D along the way. Since suppress is enabled, the first reading of each sweep (at $V_{DS} = 0V$) will be stored as the suppress value, nulling any offset.

While the sweep is being processed, the program enters a loop that waits for an SRQ to occur (lines 380 and 390). Af-

ter Unit #2 finishes its sweep, it generates the SRQ, and the program falls out of the loop and requests data from Unit #2 (lines 410-430). Note that V_{DS} data are placed into array elements (I,J,1), and measured I_D data are placed into array elements (I,J,2). Once data input has been completed, the program loops back to perform the next sweep (line 440). After all five sweeps are completed, both Source Measure Units are placed into standby (lines 450 and 460).

Next, an array search is performed to determine the maximum and minimum measured values of I_D (lines 500-570). Finally, the data are plotted with I_D along the Y axis, and V_{DS} along the X axis. Note that the graph is scaled according to the maximum and minimum V_{DS} values (X axis), and the maximum and minimum I_D values (Y axis).

4.4.5 Modifying Program 9

For other V_{GS} values, simply modify the Vgstart, Vgstop, and Vgstep variables as required (or use INPUT statements). For values that result in more or less than five sweeps, additional modifications to array size and corresponding loop counters must also be made.

Similarly, V_{DS} can be swept over a different range by changing the Vdstart, Vdstop, and Vdstep variables to the desired values (or, again add INPUT statements). The same general considerations regarding program modifications for array size and loop counter values also apply.

```
10
     REM COMMON SOURCE CHARACTERISTIC TEST PROGRAM REV. 1.3 (Program 9)
20
      OPTION BASE 1
                                    ! First array subscript is 1
30
     DIM Reading(5,101,2)
                                    ! Dimension reading array (5 swps,101 pts)
40
      CLEAR 7
                                    I Clear both Units
50
      OUTPUT KBD; CHR$(255); CHR$(75); ! Clear screen
60
     70
     REMOTE 716
                                    ! Put Unit 1 in remote
80
      OUTPUT 716; "F0.1X"
                                    ! Source V, sweep mode
90
     OUTPUT 716; "L1E-3,7X"
                                    1 1mA compliance, 1mA range
100
     OUTPUT 716; "OØX"
                                    ! Local sense
110
     OUTPUT 715; "T1,1,2,0X"
                                    ! GET trigger cycle,out trig end of delay
115
     OUTPUT 716;"B0,0,0X"
                                    ! Program Ø bias voltage .
120
     Vostart=-2
                                   ! Define -2V start Vgs voltage
130
     Vastop=0
                                   ! Define ØV stop Vgs voltage
140
     Vqstep≃.5
                                    ! Define 0.5V step Vgs voltage
150
     Dly=100
                                    ! Define 100msec Unit delay
160
     OUTPUT 716; "Q1, "; Vgstart; ", "; Vgstop; ", "; Vgstep; ", Q, "; Dly; "X" ! Pqm swp
170
     180
     REMOTE 717
                                    ! Put Unit 2 in remote
190
     OUTPUT 717; "F0,1X"
                                    ! Source V, sweep mode
200
     OUTPUT 717; "OØX"
                                    ! Local sensing
210
     OUTPUT 717; "L100E-3,0X"
                                   | 100mA compliance,autorange measure
     OUTPUT 717;"G5,2,1X"
220
                                   ! Source, measure, no prefix, sweep data
230
     OUTPUT 717; "M2,X"
                                   ! SRQ on sweep done
240
     OUTPUT 717; "T3,0,0,0X"
                                   I Trigger on external, continuous
245
     OUTPUT 717;"B0,0,0X"
                                   ! Program Ø bias value
250
     OUTPUT 717; "Z1X"
                                    ! Enable suppress
260
     OUTPUT 717; "S2X"
                                    ! Line cycle integration
270
     Vdstart=0
                                   ! Define ØV start Vds
280
     Vdstop=10
                                    ! Define 10V stop Vds
290
     Vdstep=.|
                                    ! Define 0.1V step Vds
     OUTPUT 717; "Q1, "; Vdstart; ", "; Vdstop; ", "; Vdstep; ", 0, "; Dly; "X" ! Pgm swp
300
310
     PRINT "Close lid, press CONT to begin test"
320
     PAUSE
330
     OUTPUT 716; "RINIX"
                                    ! Arm Unit 1 trigger, turn on output
340
     OUTPUT 717; "RINIX"
                                    ! Arm Unit 2 trigger, turn on output
350
     FOR I=1 TO 5
                                    ! Loop for five Vgs curves
360
     PRINT "Generating sweep"; I
370
     TRIGGER 716
                                    ! Trigger Unit 1
380
     STATUS 7,7;Stat
                                    ! Get IEEE-488 bus status
390
     IF NOT BIT(Stat,10) THEN 380
                                    ! Wait for Unit 2 SRQ on sweep done
400
     Stat=SPOLL(717)
                                    ! Serial poll Unit 2 to clear SRQ
410
     FOR J=1 TO 101
                                    ! Loop for all 101 readings
420
     ENTER 717; Reading(I,J,1), Reading(I,J,2)! Get Vds and Id data from Unit 2
430
     NEXT J
                                    ! Loop back for next reading
440
     NEXT I
                                    ! Loop back for next Vgs value
450
     OUTPUT 716; "NØX"
                                    ! Turn off Unit 1 output
460
     OUTPUT 717; "NØX"
                                    ! Turn off Unit 2 output
470
     PRINT "Press CONT to display graph"
480
     PRINT "Press CONT while in graph to return to BASIC"
490
     PAUSE
500
     Ymin=MAXREAL
                                    ! Find minimum and maximum Id value
```

510 Ymax=-MAXREAL 520 FOR I=1 TO 5 530 FOR J=1 TO 101 540 IF Reading(I,J,2)<Ymin THEN Ymin=Reading(I,J,2) 550 IF Reading(I,J,2)>Ymax THEN Ymax=Reading(I,J,2) 560 NEXT J 570 NEXT I 580 OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear screen ! Initialize graphics 590 GINIT 600 PLOTTER IS CRT, "INTERNAL" ! Define plot to CRT 610 GRAPHICS ON ! Turn on graphics ! Title graph 620 MOVE 20,95 630 LABEL "COMMON SOURCE CHARACTERISTICS" 640 MOVE 70,10 ! Label X axis LABEL "Vds" 650 660 MOVE 0,53 ! Label Y axis LABEL "Id" 670 680 VIEWPORT 30,120,20,85 ! Define soft clip limits 690 WINDOW Vdstart, Vdstop, Ymin, Ymax ! Scale graph 700 Y1=(Ymax-Ymin)/10 I Compute Y axis increment | Compute X axis increment 710 X1=(Vdstop-Vdstart)/10 720 GRID 2*X1,2*Y1,Vdstart,Ymin ! Draw grid 730 AXES X1,Y1,Vdstart,Ymin 1 Add some tick marks 740 FOR I=1 TO 5 ! Loop for all five curves 750 FOR J=1 TO 101 ! Loop for all 101 points per curve PLOT Reading(I,J,1), Reading(I,J,2) ! Plot point 760 770 ! Plot next point NEXT J 780 PENUP ! Raise pen 790 NEXT I ! Plot next curve ! Define character size 800 CSIZE 4 810 LORG 6 ! Center characters ! Turn off soft clip 820 CLIP OFF 830 FOR I=Vdstart TO Vdstop+.01*X1 STEP X1 ! Number X axis 840 MOVE I, Ymin-(Y1/4) 850 LABEL USING "#,K";I 860 NEXT I 870 FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis 880 MOVE Vdstart-(1.3*X1),I+(.3*Y1) 890 LABEL USING "#,MD.DE";I 900 NEXT I 910 PAUSE 920 OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear alpha screen 930 GRAPHICS OFF ! Clear graphics screen 940 END

4.5 TRANSCONDUCTANCE TESTS

The forward transconductance, g_{fs} , of an FET is usually measured at a specific frequency (for example 1kHz). Such a test can be simulated with dc values by using as small an incremental change in dc parameters as possible. For example, assume that we source two gate-source voltages, V_{GS1} and V_{GS2} , and measure two resulting drain currents, I_{D1} and I_{D2} . The forward transconductance can then be approximated as follows:

$$g_{fs} \approx \frac{\Delta I_D}{\Delta V_{GS}}$$

Two common plots involving g_{fs} include g_{fs} vs. V_{GS} and g_{fs} vs. I_D . The programming examples included in this section demonstrate how to generate g_{fs} vs. V_{GS} and g_{fs} vs. I_D plots.

4.5.1 Test Configuration

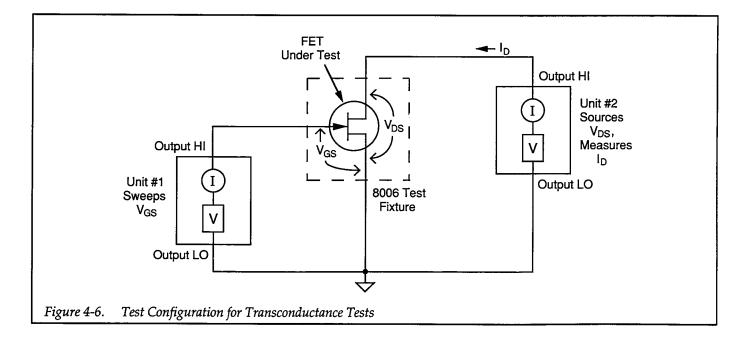
Figure 4-6 shows the general test configuration for transconductance tests. Unit #1 sweeps V_{GS} , while Unit #2 sources V_{DS} and also measures I_D . g_{fs} values are computed from incremental changes in I_D and V_{DS} . Note that a

small-signal N-channel JFET such as a 2N4392 is recommended for use with the example program below.

4.5.2 Program 10: Transconductance vs. Gate Voltage Test

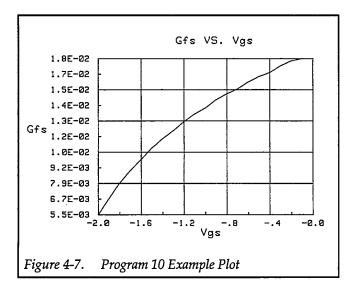
Use Program 10 below to generate a typical $g_{\rm fs}$ vs. $V_{\rm GS}$ plot.

- 1. With the power off, connect both Source Measure Units to the IEEE-488 bus of the computer.
- 2. Connect both Source Measure Units to the test fixture using suitable cables (see Figure 4-1 for details on test connections).
- 3. Turn on both Source Measure Units, and allow them to warm up for at least two hours for rated accuracy. Verify that the primary address of Unit #1 is set to 16; the primary address of Unit #2 should be set to 17.
- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines from Program 10 below into the computer.
- 6. Place a small-signal N-channel JFET such as a 2N4392 in the appropriate transistor socket. Install the correct jumpers, then close the test fixture lid.
- 7. RUN the program in the usual fashion. The computer will step through V_{GS} values between -2V and 0V using 0.1V steps. At each increment, I_D will be measured using a fixed 10V V_{DS} value is used for the test. Once data are collected, a plot of g_{fs} vs. V_{GS} is displayed on the computer CRT.
- 8. To return to BASIC from the graph, press CONT.



4.5.3 Typical Program 10 Results

Figure 4-7 shows a typical g_{fs} vs. V_{GS} plot as generated by the example program. Again, a 2N4392 N-channel JFET was used for the example plot.



4.5.4 Program 10 Description

Refer to the program listing below and the flowchart in Figure 4-8 for the following description of Program 10.

Initially, the data arrays are defined (lines 20-40) to hold 20 or 21 reading points. Note that two arrays are used in this program. The reading array will hold data obtained from the test instruments, while the plot array will hold computed $g_{\rm fs}$ and $V_{\rm GS}$ values to be plotted. After the instruments are returned to default conditions (line 50), Unit #1, which sweeps $V_{\rm GS}$, is programmed as follows (lines 80-190):

- Source V, sweep mode
- 1mA compliance, 1mA range
- Local sense
- Source only data format, no prefix, sweep data output
- External trigger, one trigger per step, output trigger on end of measurement
- SRQ on sweep done
- Start V_{GS} voltage: –2V
- Stop V_{GS} voltage: 0V
- Step V_{GS} voltage: 0.1V
- Delay: 100msec
- Staircase sweep

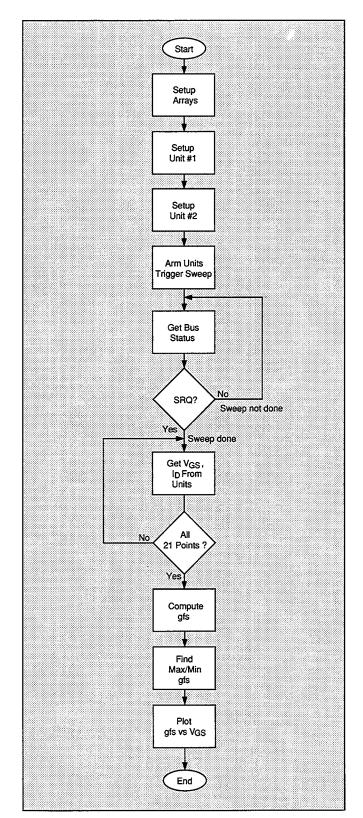


Figure 4-8. Program 10 Flowchart

Unit #2, which sources V_{DS} and measures I_D , is then configured in the following manner (lines 200-300):

- Source V, sweep mode
- Local sense
- 100mA compliance, autorange measure
- Measure only data format, no prefix, sweep data out
- External trigger, trigger source, output trigger on end of measurement
- Line cycle integration
- Delay: 100msec
- Constant sweep, 10V constant V_{DS} value, 21 points

After operator signal (lines 310 and 320), both units are armed and placed into operate (lines 330 and 340). Unit #1 is then triggered to start the sweep by using the immediate trigger command (line 360). Once Unit #1 is triggered, it sets V_{GS} to the programmed value, and it then triggers Unit #2 at the end of the measurement (using external triggering). Unit #2 then sets V_{DS} to the programmed value. Following the delay, Unit #2 measures I_D and it then triggers Unit #1 to go on to the next V_{GS} value. The process repeats until all points in the sweep have been taken. While the sweep is being performed, the program waits in a loop for Unit #2 to generate an SRQ on sweep done (lines 370 and 380). Once the SRQ occurs, the data are read into the reading array (lines 400-430), and the Source Measure Units are placed into standby (lines 440 and 450). Note that the V_{CS} values are placed into array elements (I,1), and the I_D values are stored in array elements (I,2).

Next, we encounter the part of the program where the transconductance values are calculated (lines 500-550). First, the V_{GS} values are simply transferred from the (I,1) elements of the reading array to the (I,1) elements of the plot array (line 510). Next, ΔV_{GS} values are computed by subtracting the (I,1) values from the (I+1,1) values (line 520), and ΔI_D values are similarly computed by subtracting (I+1,2) values from (I,2) values (line 530). Finally, each transconductance value is computed from ΔI_D and ΔV_{GS} and stored in the corresponding element of the plot array (line 540).

The maximum and minimum transconductance values are then determined for Y axis scaling (lines 560-610), and the data are plotted with g_{fs} along the Y axis and V_{GS} along the X axis (lines 630-920).

10	REM TRANSCONDUCTANCE-GATE VOLTA	GE TEST PROGRAM REV. 1.3 (Program 10)
20	OPTION BASE 1	! First array subscript is 1
30	DIM Reading(21,2)	! Dimension reading array (21 points)
40	DIM Plot_array(20,2)	! Dimension plot array (20 points)
50	CLEAR 7	! Clear both Units
60	OUTPUT KBD;CHR\$(255);CHR\$(75);	
70		Vgs·) ************************************
80	REMOTE 716	! Put Unit 1 in remote
90	OUTPUT 715; "F0,1X"	! Source V, sweep mode
100	OUTPUT 716; "L1E-3,7X"	! 1mA compliance,1mA range
110	OUTPUT 716; "OØX"	! Local sense
120	OUTPUT 716; "G1,2,1"	! Output source,no prefix,sweep data
130	OUTPUT 716; "T3,1,4,0X"	! External trigger, out trig end of measure
140	OUTPUT 715; "M2,X"	! SRQ on sweep done
145	OUTPUT 716; "B0,0,0X"	! Program 0 bias value
150	Vgstart=-2) Define -2V start Vgs voltage
160	Vgstop=0	! Define ØV stop Vgs voltage
170	5 1	! Define 0.1V step Vgs voltage
180	D1y=100	! Define 100msec Unit delay
190		gstop;",";Vgstep;",0,";Dly;"X" ! Pgm swp
200		s Vds, measures Id) ***************
210	REMOTE 717	! Put Unit 2 in remote
220	OUTPUT 717;"F0,1X"	! Source V, sweep mode
230	OUTPUT 717;"OØX"	! Local sensing
240	OUTPUT 717;"L100E-3,0X"	! 100mA compliance,autorange measure
250	OUTPUT 717;"G4,2,1X"	! Measure,no prefix,sweep data
260	OUTPUT 717;"T3,1,4,0X"	! Trig ext,start source,out end of meas
270	OUTPUT 717;"S2Z0X"	! Line cycle integration, suppress off
275	OUTPUT 717;"B0,0,0X"	! Program Ø bias value
280	Vds=10	! Define 10V Vds
290	D1y=100	! 100msec Unit 2 delay
300		;",21X" ! Constant sweep,21 points
310	PRINT "Close lid, press CONT to	
320	PAUSE	
330	OUTPUT 716; "RINIX"	! Arm Unit 1 trigger,turn on output
340	OUTPUT 717; "RINIX"	! Arm Unit 2 trigger, turn on output
350	PRINT "Generating sweep"	
360	OUTPUT 716; "HØX"	! Trigger Unit 1 to start sweep
370	STATUS 7,7;Stat	! Get IEEE-488 bus status
380		! Wait for Unit 1 SRQ on sweep done
390	Stat=SPOLL(716)	! Serial poll Unit 1 to clear SRQ
400	FOR $I=1$ TO 21	! Loop for all 21 readings
400	ENTER 716;Reading(I,1)	! Get Vgs data from Unit 1
470	ENTER 717;Reading(I,2)	! Get Id data from Unit 2
420	NEXT I	! Loop back for next data point
430	NEXT I OUTPUT 716;"NØX"	! Turn off Unit 1 output
		! Turn off Unit 2 output
450	OUTPUT 717; "NØX"	
460	PRINT "Press CONT to display gr	
470	PRINT "Press CONT while in grap	JN TO NETALLY TO RUPTO
480	PAUSE	VE CTOPE IN DUCT APPAV
490	REM COMPUTE TRANSCONDUCTANCE AI	
500	FOR I=1 TO 20	! Loop for all gfs points
1		

```
510
      Plot_array(I,1)=Reading(I,1) ! Store Vgs in plot array
520
      Delta_vgs=ABS(Reading(I+1,1)-Reading(I,1)) ! Compute delta Vgs
530
      Delta_id=ABS(Reading(I+1,2)-Reading(I,2)) ! Compute delta Id
540
      Plot_array(I,2)=Delta_id/Delta_vgs
                                                  ! Compute gfs
550
      NEXT I
                                     ! Loop back for next point
560
      Ymin=MAXREAL
                                     ! Find minimum and maximum gfs value
570
      Ymax=-MAXREAL
580
      FOR I=1 TO 20
590
      IF Plot_array(I,2)<Ymin THEN Ymin=Plot_array(I,2)</pre>
600
      IF Plot_array(I,2)>Ymax THEN Ymax=Plot_array(I,2)
610
      NEXT I
620
      OUTPUT KBD; CHR$(255); CHR$(75); ! Clear screen
                                      ! Initialize graphics
630
      GINIT
640
      PLOTTER IS CRT, "INTERNAL"
                                     ! Define plot to CRT
                                     ! Turn on graphics
650
      GRAPHICS ON
660
      MOVE 60,90
                                     ! Title graph
670
     LABEL "Gfs VS. Vos"
680
      MOVE 70,10
                                     | Label X axis
      LABEL "Vgs"
690
700
                                      ! Label Y axis
      MOVE 0,53
      LABEL "Gfs"
710
720
      VIEWPORT 30,120,20,85
                                    | Define soft clip limits
730
      WINDOW Vgstart, Vgstop, Ymin, Ymax ! Scale graph
740
      Y1=(Ymax-Ymin)/10
                                   ! Compute Y axis increment
                                    - ! Compute X axis increment
750
      X1=(Vgstop-Vgstart)/10
760
      GRID 2*X1,2*Y1,Vgstart,Ymin
                                     | Draw grid
770
      AXES X1,Y1,Vgstart,Ymin
                                     ! Add some tick marks
780
      PLOT Plot array(*)
                                     ! Plot array
790
                                      | Define character size
      CSIZE 4
800
     LORG 6
                                      1 Center characters
                                      ! Turn off soft clipping
810
     CLIP OFF
820
     FOR I=Vgstart TO Vgstop+.01*X1 STEP 2*X1 ! Number X axis
830
      MOVE I, Ymin-(Y1/4)
840
     LABEL USING "#,MD.D";I
850
      NEXT I
860
      FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis
870
      MOVE Vgstart-(1.3*X1),I+(.3*Y1)
880
     LABEL USING "#,D.DE";I
890
     NEXT I
900
      PAUSE
910
      OUTPUT KBD; CHR$(255); CHR$(75); ! Clear alpha screen
920
      GRAPHICS OFF
                                      ! Clear graphics screen
930
      END
```

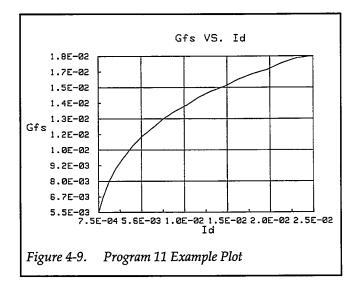
4.5.5 Program 11: Transconductance vs. Drain Current Test

Use Program 11 below to generate a typical I_D vs. V_{GS} plot.

- 1. With the power off, connect both Source Measure Units to the IEEE-488 bus of the computer.
- 2. Connect both Source Measure Units to the test fixture using suitable triax cables (see Figure 4-1 for details on test connections).
- 3. Turn on both units, and allow them to warm up for at least two hours for rated accuracy. Verify that the primary address of Unit #1 is set to 16; the primary address of Unit #2 should be set to 17.
- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines from Program 11 below into the computer.
- 6. Place a small-signal N-channel JFET such as a 2N4392 in the appropriate transistor socket. Install the correct jumpers, then close the test fixture lid.
- 7. RUN the program in the usual fashion. The computer will step through V_{GS} values between -2V and 0V using 0.1V steps. At each increment, I_D will be measured using a fixed 10V V_{DS} value is used for the test. Once data are collected, a plot of g_{fS} vs. I_D is displayed on the computer CRT.
- 8. To return to BASIC from the graph, press CONT.

4.5.6 Typical Program 11 Results

Figure 4-9 shows a typical g_{fs} vs. I_D plot as generated by the example program. Again, a 2N4392 N-channel JFET was used for the example plot.



4.5.7 Program 11 Description

Refer to the program listing below and the flowchart in Figure 4-10 for the following description of Program 11.

Initially, the data arrays are defined (lines 20-40) to hold 20 or 21 reading points. Once again, two arrays are used in this program. The reading array will hold data obtained from the test instruments, while the plot array will hold computed g_{fs} and I_D values to be plotted. After the instruments are returned to default conditions (line 50), Unit #1, which sweeps V_{GS} , is programmed as follows (lines 80-190):

- Source V, sweep mode
- 1mA compliance, 1mA range
- Local sense
- Source only data format, no prefix, sweep data output
- External trigger, one trigger per step, output trigger on end of measurement
- SRQ on sweep done
- Start V_{GS} voltage: -2V
- Stop V_{GS} voltage: 0V
- Step V_{GS} voltage: 0.1V
- Delay: 100msec
- Staircase sweep

Unit #2, which sources V_{DS} and measures I_D , is then configured in the following manner (lines 200-300):

- Source V, sweep mode
- Local sense
- 100mA compliance, autorange measure
- Source and measure data format, no prefix, sweep data output
- External trigger, trigger source, output trigger on end of measurement
- Delay: 100msec
- Constant sweep, 10V constant V_{DS} value, 21 points

After operator signal (lines 310 and 320), both units are armed and placed into operate (lines 330 and 340). Unit #1 is then triggered to start the sweep by using the immediate trigger command (line 360). Once Unit #1 is triggered, it sets V_{GS} to the programmed value, and it then triggers Unit #2 (using external triggering). Unit #2 then sets V_{DS} to the programmed value. Following the prescribed delay period, Unit #2 measures I_D and it then triggers Unit #1 to go on to the next V_{GS} value. The process repeats until all points in the sweep have been taken. While the sweep is being performed, the program waits in a loop for Unit #2 to generate an SRQ on sweep done (lines 370 and 380). Once the SRQ occurs, the data are read into the reading array (lines 400-430), and the Source Measure Units are placed into standby (lines 440 and 450). Note that the V_{GS} values are placed into array elements (I,1), and the I_D values are stored in array elements (I,2).

Next, we encounter the part of the program where the transconductance values are calculated (lines 500-550). First, the I_D values are simply transferred from the (I,1) elements of the reading array to the (I,1) elements of the plot array (line 510). Next, ΔV_{GS} values are computed by subtracting the (I,1) values from the (I+1,1) values (line 520), and ΔI_D values are similarly computed by subtracting (I+1,2) values from (I,2) values (line 530). Finally, each transconductance value is computed from ΔI_D and ΔV_{GS} and stored in the corresponding element of the plot array (line 540).

The maximum and minimum transconductance values are then determined for Y axis scaling (lines 560-610), and the maximum and minimum I_D values are also computed (lines 620-670). Finally, data are plotted with g_{fs} along the Y axis and I_D along the X axis (lines 710-980).

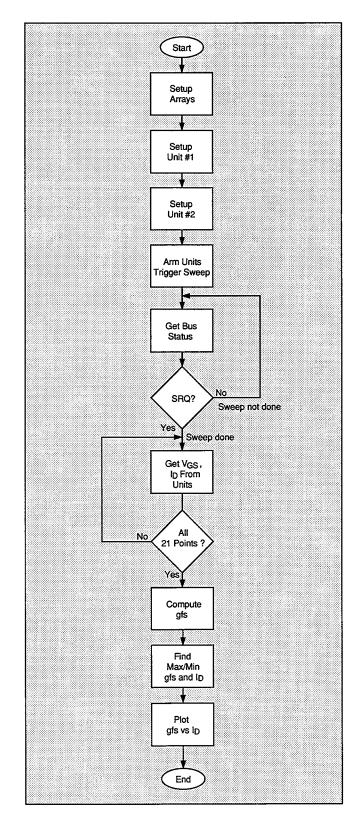


Figure 4-10. Program 11 Flowchart

10	REM TRANSCONDUCTANCE-DRAIN CURR	ENT TEST PROGRAM REV. 1.3 (Program 11)
20		! First array subscript is 1
30		! Dimension reading array (21 points)
40		! Dimension plot array (20 points)
50		! Clear both Units
60	OUTPUT KBD;CHR\$(255);CHR\$(75);	
70		· crear screen Vgs > *****
70 80	REMOTE 716	! Put Unit 1 in remote
		! Source V, sweep mode
90	OUTPUT 716; "F0,1X"	
100	OUTPUT 716; "L1E-3,7X"	! 1mA compliance, 1mA range
110		! Local sense
120	OUTPUT 716; "G1,2,1"	! Output source, no prefix, sweep data
130		! External trigger,out trig end of measure
140	OUTPUT 716;"M2,X"	! SRQ on sweep done
145	OUTPUT 715;"B0,0,0X"	!`Program Ø bias value
150	5	! Define -2V start Vgs voltage
160		! Define ØV stop Vgs voltage
170	Vgstep=.1	! Define .1V step Vgs voltage
180	D1y = 100	! Define 100msec Unit delay
190		stop;",";Vgstep;",Ø,";Dly;"X" ! Pgm swp
200		Vds, measures Id) ***************
210	REMOTE 717	! Put Unit 2 in remote
220	OUTPUT 717; "FØ,1X"	! Source V, sweep mode
230	OUTPUT 717; "00X"	! Local sensing
240		! 100mA compliance,autorange measure
250	•	! Measure,no prefix,sweep data
260		! Trig ext,start source,out end of meas
270	• • • •	! Line cycle integration, suppress off
276	OUTPUT 717; "BØ,Ø,ØX"	! Program Ø bias value
280	Dly=100	! 100msec Unit 2 delay
	Uds=10	1 Define 10V Vds
290		
300		",21X" Constant sweep,21 points
310	PRINT "Close lid, press CONT to	begin test
320	PAUSE	
330	OUTPUT 716; "RINIX"	! Arm Unit 1 trigger,turn on output
340	OUTPUT 717; "RINIX"	I Arm Unit 2 trigger, turn on output
350	PRINT "Generating sweep"	
360	OUTPUT 716;"HØX"	! Trigger Unit 1 to start sweep
370	STATUS 7,7;Stat	! Get IEEE-488 bus status
380	•	! Wait for Unit 1 SRQ on sweep done
390	Stat=SPOLL(716)	! Serial poll Unit 1 to clear SRQ
400	FOR I=1 TO 21	! Loop for all 21 readings
410	ENTER 716;Reading(I,1)	! Get Vgs data from Unit 1
420	ENTER 717;Reading(I,2)	! Get Id data from Unit 2
430	NEXT I	! Loop back for next data point
440	OUTPUT 716; "NØX"	! Turn off Unit 1 output
450	OUTPUT 717; "NØX"	! Turn off Unit 2 output
460	PRINT "Press CONT to display gr	
470	PRINT "Press CONT while in grap	
480	PAUSE	
480	REM COMPUTE TRANSCONDUCTANCE AN	IN STORE IN PLOT ARRAY
490 500	FOR I=1 TO 20	! Loop for all gfs points
ששכ	FUR 1-1 10 20	: LOOD IOI GII GIS POINTS
L		

510 Plot_array(I,1)=Reading(I,2) | Store Id in plot array 520 Delta_vgs=ABS(Reading(I+1,1)-Reading(I,1)) ! Compute delta Vgs 530 Delta_id=ABS(Reading(I+1,2)-Reading(I,2)) ! Compute delta Id 540 Plot_array(I,2)=Delta_id/Delta_vgs ! Compute gfs 550 NEXT I ! Loop back for next point 560 Ymin=MAXREAL ! Find minimum and maximum gfs value 570 Ymax=-MAXREAL 580 FOR I=1 TO 20 590 IF Plot_array(I,2)<Ymin THEN Ymin=Plot_array(I,2)</pre> 600 IF Plot_array(I,2)>Ymax THEN Ymax=Plot_array(I,2) 610 NEXT I 620 Xmin=MAXREAL ! Find minimum and maximum Id value 630 Xmax=-MAXREAL 640 FOR I=1 TO 20 IF Plot_array(I,1)<Xmin THEN Xmin=Plot_array(I,1)</pre> 650 660 IF Plot_array(I,1)>Xmax THEN Xmax=Plot_array(I,1) 670 NEXT I 680 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 690 GINIT ! Initialize graphics 700 PLOTTER IS CRT, "INTERNAL" ! Define plot to CRT 710 GRAPHICS ON ! Turn on graphics 720 MOVE 60.90 ! Title graph 730 LABEL "Gfs VS. Id" 740 MOVE 70,10 ! Label X axis 750 LABEL "Id" 760 MOVE 0,53 ! Label Y axis LABEL "Gfs" 770 VIEWPORT 30,120,20,85 ! Define soft clip limits WINDOW Xmin,Xmax,Ymin,Ymax ! Scale graph 780 790 Y1=(Ymax-Ymin)/10 800 ! Compute Y axis increment 810 X1=(Xmax-Xmin)/10 ! Compute X axis increment 820 GRID 2*X1,2*Y1,Xmin,Ymin | Draw grid 830 AXES X1,Y1,Xmin,Ymin ! Add some tick marks 840 PLOT Plot_array(*) ! Plot array 850 CSIZE 4 | Define character size 860 LORG 6 ! Center characters ! Turn off soft clipping 870 CLIP OFF 880 FOR I=Xmin TO Xmax+.01*X1 STEP 2*X1 | Number X axis 890 MOVE I, Ymin-(Y1/4) 900 LABEL USING "#,MD.DE";I 910 NEXT I 920 FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis 930 MOVE Xmin-(1.3*X1),I+(.3*Y1) 940 LABEL USING "#,D.DE";I 950 NEXT I 960 PAUSE 970 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear alpha screen 980 GRAPHICS OFF | Clear graphics screen 990 END

4.6 THRESHOLD TESTS

The threshold voltage, V_T , is a critical parameter for FET characterization as well as process control. Basically, there are a number of methods for determining V_T including several transconductance methods, the two point extrapolated V_T method, as well as the V_T @ I_D search method. In this paragraph, we will discuss the I_D search method for finding V_T along with a self-biasing method that takes advantage of the special capabilities of the Models 236 and 237.

4.6.1 Search Method Test Configuration

Figure 4-11 shows the general test configuration for the search method threshold voltage tests. Unit #1 sources V_{CS} , while Unit #2 sources V_{DS} and also measures I_D . An iterative search process is included in the program to allow you to enter a target I_D value.

4.6.2 Program 12A: Threshold Voltage Tests Using Search Method

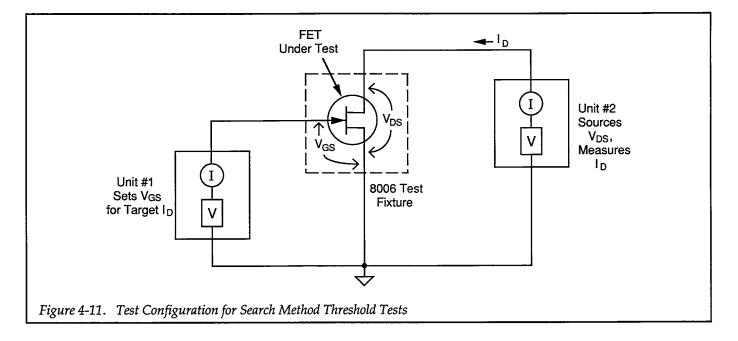
Use Program 12A below to perform the $V_{\rm T}$ test using the search for target $I_{\rm D}$ method.

- 1. With the power off, connect both Source Measure Units to the IEEE-488 bus of the computer.
- 2. Connect both units to the test fixture using suitable triax cables (see Figure 4-1 for details on test connections).

- 3. Turn on both units, and allow them to warm up for at least two hours for rated accuracy. Verify that the primary address of Unit #1 is set to 16; the primary address of Unit #2 should be set to 17.
- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines from Program 12 below into the computer.
- 6. Place the desired N-channel FET in the appropriate transistor socket. Install the correct jumpers, then close the test fixture lid.
- 7. RUN the program in the usual fashion. The computer will prompt you to enter two V_{GS} values which correspond to the V_{GS} variation range. Also, type in the desired fixed value for V_{DS} when prompted to do so. Finally, enter the target I_D value at which V_T is to be determined, and continue the program when ready to begin the test (typical I_D = 100 μ A).
- 8. The program will then step through the search process and attempt to match the drain current to the target value to within $\pm 5\%$ by varying V_{GS}. If more than 20 iterations are necessary, or if Unit #2 is found to be over compliance, you will be notified of that fact, and the program will halt.
- 9. If the search is successful, the value of V_{GS} which resulted in the target I_D value will then be displayed. This V_{GS} value is V_T . If the search is unsuccessful, rerun the program and choose a more appropriate set of V_{GS} values.

4.6.3 Program 12A Description

Refer to the program listing below and the flowchart in Figure 4-12 for the following description of Program 12A.



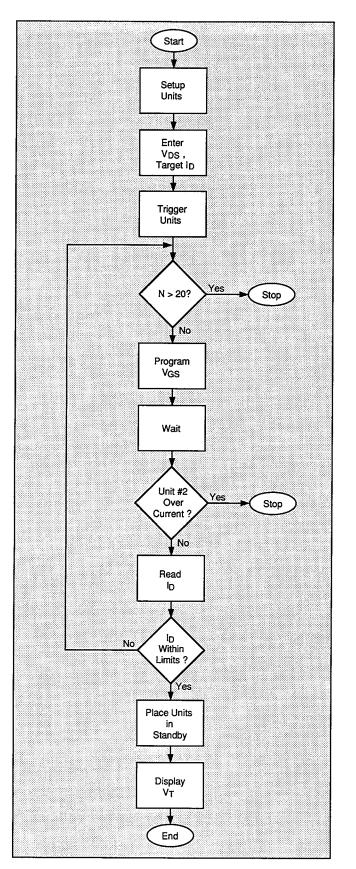


Figure 4-12. Program 12A Flowchart

Initially, the instruments are returned to default conditions (line 20), and the iteration variables are defined (lines 30 and 40). Next, Unit #1, which sources V_{GS} , is programmed as follows (lines 70-110):

- Source V, dc mode
- 1mA compliance, 1mA range
- Local sense
- Trigger on GET, continuous
- Delay: 1sec

Next, the range of V_{GS} values is entered, the the start value for V_{GS} is computed (lines 130-150). Unit #2, which sources V_{DS} and measures I_D , is then configured in the following manner (lines 170-260):

- Source V, dc mode
- Local sense
- 100mA compliance, autorange measure
- Measure only data format, no prefix, dc data output
- Trigger on GET, continuous
- Line cycle integration
- Bias value determined by user input

The desired V_{DS} and I_D values are then entered (lines 240 and 250), and, after operator signal (lines 270 and 280), both Source Measure Units are armed and placed into operate (lines 290 and 300) and finally triggered (lines 320 and 330). The iteration counter is then incremented and then checked against the maximum number of allow iterations (lines 340 and 350). If the iterative search exceeds the allowed limit, a message to that effect is displayed, and the program halts.

Assuming the number of iterations has not exceeded the allowed limit, Unit #1 is programmed with the presentlycomputed value of V_{GS} (line 400). After a one-second delay, Unit #2 is serial polled and its status byte is checked to determine whether or not the unit is over current compliance (lines 420 and 430). If so, an error message is displayed, and the program halts.

The program then requests a drain current reading (I_D) from Unit #2 (line 480), and then checks to see if the drain current value is close to the target I_D value (lines 490-580). If the I_D value is not within the required range (\pm 5%), the program computes a new V_{CS} value and then loops back to perform the test loop again. Finally, both units are placed into standby (lines 590 and 600), and the V_T value at the actual I_D is displayed (line 610).

4.6.4 Modifying Program 12A

As written, the program sets the number of iterations to search for target I_D to 20 (line 30). You can change this variable to perform the iterative search as many times as is necessary. Similarly, the allowed range for the I_D target

search is $\pm 5\%$. Again, you can change this tolerance range as tight as necessary by modifying the limits in lines 490 and 540. Note that reducing the target range will probably require an increase in the number of iterations as well.

```
REM SEARCH METHOD THRESHOLD VOLTAGE TEST PROGRAM REV. 1.3 (Program 12A)
10
20
     CLEAR 7
                                   ! Clear both Units
30
     Iterations=20
                                   ! Define maximum search iterations
40
     N=0
                                   ! Set iteration counter
50
     OUTPUT KBD; CHR$(255); CHR$(75); ! Clear screen
     60
70
     REMOTE 716
                                  | Put Unit 1 in remote
     OUTPUT 716; "F0,0X"
80
                                   I Source V, DC mode
     OUTPUT 716; "L1E-3,7X"
90
                                  ! 1mA compliance, 1mA range
100
     OUTPUT 716;"00X"
                                   ! Local sense
     OUTPUT 716; "T1,0,0,0X"
110
                                   | GET trigger,continuous
120
     D1y=1000
                                   ! Define 1 sec Unit delay
     INPUT "Enter more positive Vgs", Vgs1 ! Input greater Vgs
130
140
     INPUT "Enter more negative Vgs", Vgs2 ! Input lesser Vgs
     Vgs=(Vgs1-Vgs2)/2+Vgs2
                                  ! Compute start Vgs
150
160
     170
                                   ! Put Unit 2 in remote
     REMOTE 717
     OUTPUT 717; "F0,0X"
180
                                   ! Source V, DC mode
190
     OUTPUT 717; "00M128,0X"
                                  ! Local sensing,SRQ
     OUTPUT 717;"L100E-3,0X"
200
                                   1 100mA compliance autorange measure
210
     OUTPUT 717; "G4,2,0X"
                                  ! Measure,no prefix,DC data
220
     OUTPUT 717; "S2ZØX"
                                  ! Line cycle integration, suppress off
230
     OUTPUT 717; "T1,0,0,0X"
                                  | Trigger on GET,continuous
240
     INPUT "Enter Vds",Vds
                                   ! Input Vds
250
     INPUT "Enter target Id", Itarget | Input target Id for search
     OUTPUT 717; "B"; Vds; ",0,"; Dly; "X" ! Program DC, autorange, delay
260
270
     PRINT "Close lid, press CONT to begin test"
280
     PAUSE
290
     OUTPUT 716; "RINIX"
                                   ! Arm Unit 1 trigger, turn on output
                                   I Arm Unit 2 trigger, turn on output
300
     OUTPUT 717; "RINIX"
     PRINT "Measuring..."
310
320
     TRIGGER 716
                                   ! Trigger Unit 1
330
     TRIGGER 717
                                   ! Trigger Unit 2
340
     N=N+1
                                   ! Increment iteration counter
350
     IF N>Iterations THEN
                                   ! Check for maximum iterations
360
     BEEP
370
     PRINT "More than"; Iterations; "iterations"
380
     STOP
390
     END IF
400
     OUTPUT 716; "B"; Vgs; ",0,"; Dly; "X" ! Program Unit 1 Vgs value
     WAIT Dly/1000+1
410
                                  | Wait for settling
420
     Stat=SPOLL(717)
                                   I Serial poll Unit 2
                                   ! Check for over compliance
430
     IF BIT(Stat.7) THEN
440
     BEEP
450
     PRINT "Unit 2 is over current compliance"
     STOP
460
470
     END IF
480
                                   ! Get Id reading from Unit 2
     ENTER 717; Id
490
     IF Id>1.05*Itarget THEN
                                  ! Check for Id > target
500
     Vas1=Vas
```

510 Vgs=Vgs-(Vgs-Vgs2)/20 520 GOTO 340 530 END IF ! Check for Id < target 540 IF Id<.95*Itarget THEN 550 Vgs2=Vgs 560 Vgs=Vgs+(Vgs1-Vgs)/20 570 GOTO 340 580 END IF 590 OUTPUT 716; "NØX" ! Turn off Unit 1 output OUTPUT 717; "NØX" ! Turn off Unit 2 output 600 PRINT "Vt=";Vgs;"V @ Id=";Id ! Display threshold voltage 610 620 END

4.6.5 Self-bias Threshold Test Configuration

Figure 4-13 shows the general test configuration for the self-bias method of threshold voltage tests. Unit #1 sources the drain current (assumed to be the same as the source current), and it also measures the threshold voltage, V_T . Unit #2 sources V_{DS} . This arrangement allows very rapid threshold voltage measurement (milliseconds per reading) at very low currents, and it can be used with both enhancement-mode and depletion-mode FETs. Note that the high-impedance sensing circuits and the floating capabilities of the Models 236/237 are key characteristics that allow this special configuration to be used.

WARNING

When a Model 236/237 is programmed for remote sensing, hazardous voltage may be present on the SENSE and OUTPUT terminals when the unit is in operate regardless of the programmed voltage or current. To avoid a possible shock hazard, always turn off power before connecting or disconnecting cables to the Source Measure Unit or the associated test fixture.

NOTE

Both V_{DS} and I_D must be programmed with reversed polarity because of the connection configuration used. For example, for an N-channel FET, both V_{DS} and I_D must be negative.

These values will result in proper biasing of the DUT. Also, the sign of the measured V_T value will be reversed.

4.6.6 Self-bias Method Measurement Considerations

There is a limit as to the maximum voltage that can appear between the sense and source leads of each Source Measure Unit. For that reason, the maximum threshold voltage that can be measured with this method is defined as follows:

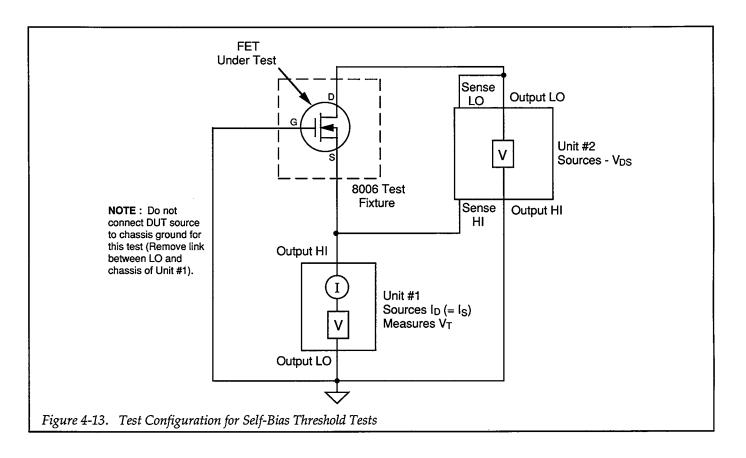
$$V_{MAX} = 12 - 10 \left(\frac{V_{DS}}{V_{FS}}\right)$$

Where: V_{MAX} = maximum threshold voltage V_{DS} = V_{DS} sourced by Unit 2 V_{FS} = full scale voltage of Unit 2

For example, if V_{DS} has a value of 5V with the unit on the 11V measurement range, the maximum voltage is:

$$V_{MAX} = 12 - 10(5/11) = 7.45V$$

From this relationship, it can be seen that the voltage range of Unit #2 should be set as high as possible.



4.6.7 Program 12B: Self-bias Threshold Voltage Tests

Use Program 12B below to perform the self-bias threshold voltage test.

- 1. With the power off, connect both Source Measure Units to the IEEE-488 bus of the computer.
- 2. Connect both units to the test fixture with suitable triax cables using Figure 4-13 as a guide. Note that remote sensing connections are used for Unit #2, and that both OUTPUT LO and SENSE LO of Unit #2 are connected to the drain of the device under test. With this configuration, it will be necessary to program negative V_{DS} and I_D values in order to properly bias the DUT.
- 3. Turn on both units, and allow them to warm up for at least two hours for rated accuracy. Verify that the primary address of Unit #1 is set to 16; the primary address of Unit #2 should be set to 17.
- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines from Program 12B below into the computer.
- 6. Place the desired N-channel (enhancement-mode or depletion-mode) FET in the appropriate transistor

socket. Install the correct jumpers (using Figure 4-13 as a guide), then close the test fixture lid.

- 7. RUN the program in the usual fashion. The computer will program Unit #1 to step through I_D current values between $-10\mu A$ and $-100\mu A$ at $-10\mu A$ increments, using a Omsec user delay for maximum speed and a fixed V_{DS} value of -10V.
- 8. After data are collected, the computer will display the V_T values at the 10 tested I_D currents on the computer CRT. Both I_D and V_T values will be sign-adjusted for correct displayed polarity.

4.6.8 Program 12B Description

Refer to the program listing below and the flowchart in Figure 4-14 for the following description of Program 12B.

Initially, the instruments are returned to default conditions (line 20). Next, Unit #1, which sources I_D and measures V_T , is programmed as follows (lines 50-170):

- Source I, sweep mode
- 10V compliance, 11V range
- Local sense
- Trigger on GET, continuous

- Source, measure data, no prefix or suffix, sweep data
- SRQ on sweep done
- Fastest integration rate, filter off
- Start ID current: -10µA
- Stop ID current: -100µA
- Step ID current: -10µA
- Delay: 0msec

Next, Unit #2, which sources V_{DS} is then configured in the following manner (lines 190-250):

- Source V, DC mode
- Remote sensing
- 100mA compliance, 100mA range
- Trigger on GET, continuous
- –10V fixed V_{DS} value

After operator signal (lines 260 and 270), both Source Measure Units are armed and placed into operate (lines 280 and 290) and triggered (lines 300 and 310). The program then enters a loop to wait for Unit #1 to generate an SRQ (lines 320 and 330). After the SRQ, Unit #1 is serial polled to clear the SRQ (line 340), and both units are placed into standby (lines 350 and 360). The ten V_T values are then read from Unit #1 and displayed on the computer CRT (lines 380-430). Note that both I_D and V_T values are corrected for proper polarity.

4.6.9 Modifying Program 12B

As written, the program tests for threshold voltages at 10 values of I_D between -10μ A and -100μ A at -10μ A increments (as pointed out previously, the programmed drain currents must be negative with an N-channel device because of the test configuration used). These values can be changed to the required values simply by modifying the corresponding variables in the program. Also, plotting routines from another program could be adapted and added to generate a plot of V_T vs. I_D . Paragraph 8.5 demonstrates V_T vs. I_D plotting.

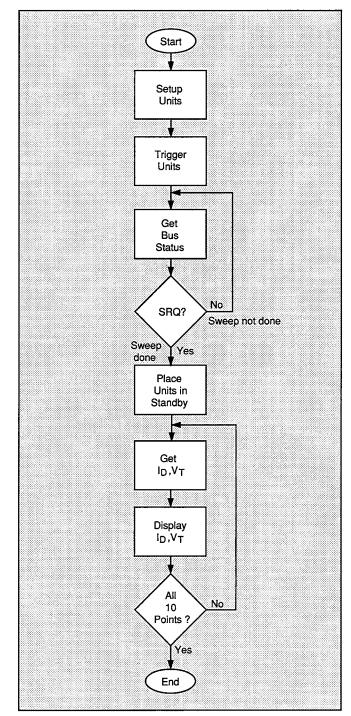


Figure 4-14. Program 12B Flowchart

10 REM SELF BIAS THRESHOLD VOLTAGE TEST PROGRAM REV. 1.3 (Program 12B) 20 CLEAR 7 ! Clear both Units OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 30 40 50 REMOTE 716 | Put Unit 1 in remote ! Source I, sweep mode БØ OUTPUT 716; "F1,1X" OUTPUT 716; "L10,2X" 70 ! 10V compliance, 11V range OUTPUT 716;"O0Z0X" 80 ! Local sense, suppress off 90 OUTPUT 716; "T1,0,0,0X" | GET trigger,continuous 100 OUTPUT 716; "65,2,1X" I Source data, no prefix, sweep data 110 OUTPUT 716; "M2,X" ! SRQ on sweep done OUTPUT 716; "SØPØX" 120 ! Fast integration, filter off OUTPUT 716;"B0,0,0X" ! Program Ø bias value 125 ! Define -10uA start current 130 Istart=-1.0E-5 | Define -100uA stop current 140 Istop=-1.00E-4 ! Define -10uA step current 150 Istep=-1.0E-5 ! Define 0 sec Unit delay 160 D1v=0 OUTPUT 716; "Q1, "; Istart; ", "; Istop; ", "; Istep; ", 0, "; Dly; "X" ! Pgm swp 170 180 ! Put Unit 2 in remote REMOTE 717 190 200 OUTPUT 717; "FØ,ØX" ! Source V, DC mode OUTPUT 717; "01X" 210 ! Remote sensing 220 OUTPUT 717;"L100E-3,9X" ! 100mA compliance,100mA range OUTPUT 717; "T1,0,0,0X" ! Get trigger, continuous 230 ! Define -10V Vds value 240 Vds=-10 OUTPUT 717 ;"B";Vds;",3,";Dly;"X" ! Program DC, 110V range,delay 250PRINT "Close lid, press CONT to begin test" 260 270 PAUSE 280 OUTPUT 716; "RIN1X" ! Arm Unit 1 trigger, turn on output 290 OUTPUT 717; "R1N1X" | Arm Unit 2 trigger, turn on output ! Trigger Unit 2 300 TRIGGER 717 ! Trigger Unit 1 310 TRIGGER 716 ! Get bus status 320 STATUS 7,7;Stat IF NOT BIT(Stat,10) THEN 320 ! Wait for SRQ 330 ! Serial poll Unit 1 to clear SRQ 340 Stat=SPOLL(716) | Turn off Unit 1 output 350 OUTPUT 716; "NØX" OUTPUT 717; "N000X" ! Turn off Unit 2 output,local sense 360 370 PRINT 380 PRINT "Id", "Vt" PRINT "------390 FOR I=1 TO 10 ! Loop for all 10 readings 400 ENTER 716;Id,Vt PRINT -Id,-Vt ! Get reading ! Print reading, adjust signs 410 420 430 NEXT I 440 END

SECTION 5 Using Substrate Bias

5.1 INTRODUCTION

Thus far in this manual, we have concentrated on performing tests on devices that do not require substrate bias. Since many devices, especially those in complex packages, do require some form of substrate bias, our discussion would not be complete without discussing methods for applying and programming substrate bias.

In the following paragraphs, we will discuss two methods of applying substrate bias: (1) adding an additional Model 236/237 Source Measure Unit, and (2) using a Model 230 Programmable Voltage Source

5.2 SUBSTRATE BIAS INSTRUMENT CONNECTIONS

WARNING

Interlock circuits must be connected before use. Connect fixture \bigoplus to safety earth ground using #18 AWG minimum wire before use. Turn off all power before connecting or disconnecting wires or cables.

5.2.1 Source Measure Unit Substrate Bias Connections

Figure 5-11 shows test connections when using an additional Source Measure Unit to apply substrate bias. Unit #1 and Unit #2 perform the same functions as outlined earlier in this section, and Unit #3 is used to apply substrate bias. Once again, the Model 8006 Component Test Fixture is recommended for test connections, along with Model 7078-TRX-3 triax cables. Note that the connecting cables to Unit #3 assume that local sensing will be used even though that may not be the situation in many cases.

5.2.2 Voltage Source Substrate Bias Connections

Figure 5-2 shows bias connections using a Model 230 Programmable Voltage Source for substrate bias connections. The two Source Measure Units are connected to the Model 8006 test fixture using Model 7078-TRX-3 triax cables just as before. The Model 230 Voltage Source is connected to two of the binding posts on the test fixture using banana plug patch cords. Note that remote sensing is not used in this application; remote sensing could be added by connecting the sense terminals of the voltage source to the two remaining binding posts on the test fixture.

NOTES

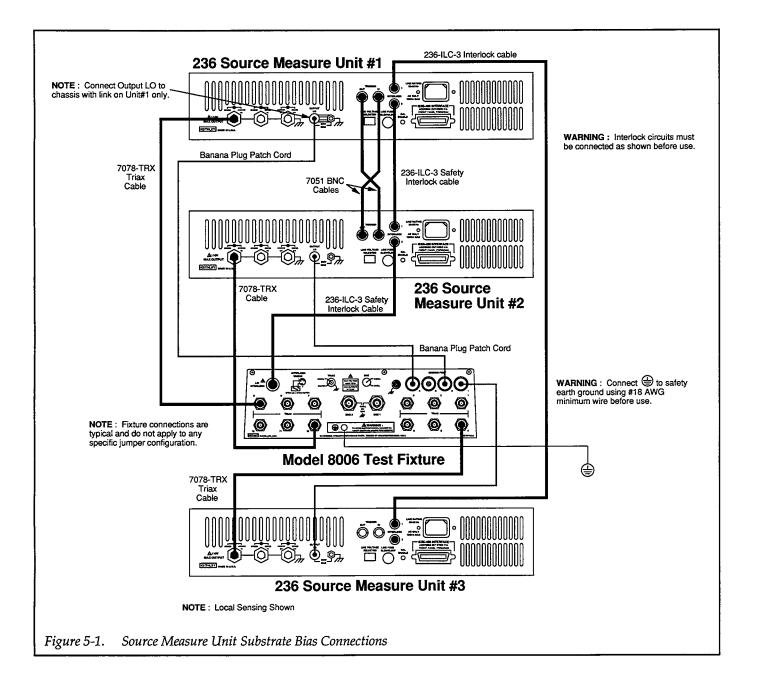
- 1. Remote sensing connections are recommended for optimum accuracy. See paragraph 1.2.2 for details.
- If measurement noise is a problem, or for critical, low-level applications, use shielded cable for all signal connections.

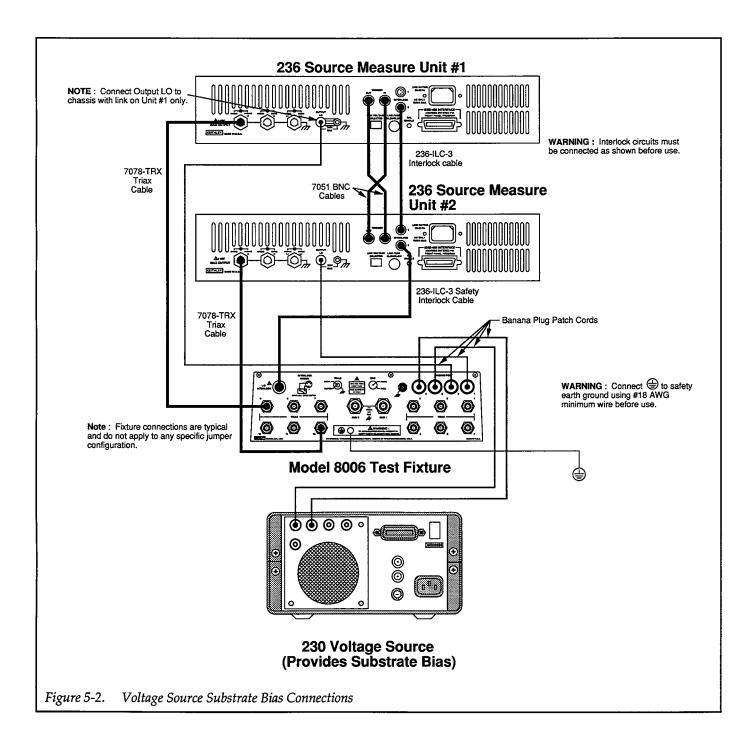
5.3 SUBSTRATE BIAS JUMPER CONNECTIONS

If you are using the Model 8006 test fixture, you must install appropriate jumpers to complete bias connections (jumpers must also be installed for remaining device connections as outlined earlier in this manual). The exact jumper configuration will, of course, depend on the type of device packages you intend to use for the programming examples in this section.

5.4 SOURCE MEASURE UNIT SUBSTRATE BIASING

The following paragraphs discuss using a Model 236/237 Source Measure Unit to provide substrate biasing. In the first example, the substrate current, I_{SB} , is measured as the gate-source voltage, V_{GS} is swept across the desired range. A plot of I_{SB} vs. V_{GS} is generated by the program. In the second example, the third Source Measure Unit provides substrate bias for common-source characteristic tests.





5.4.1 Program 13 Test Configuration

Figure 5-3 shows the test configuration for Program 13 listed below. Unit #1 is used to sweep V_{GS} , while Unit #2 sources V_{DS} . Unit #3 applies a user-defined substrate bias, V_{SB} , to the device under test, and it also measures the substrate current, I_{SB} .

5.4.2 Example Program 13: Substrate Current vs. Gate-source Voltage

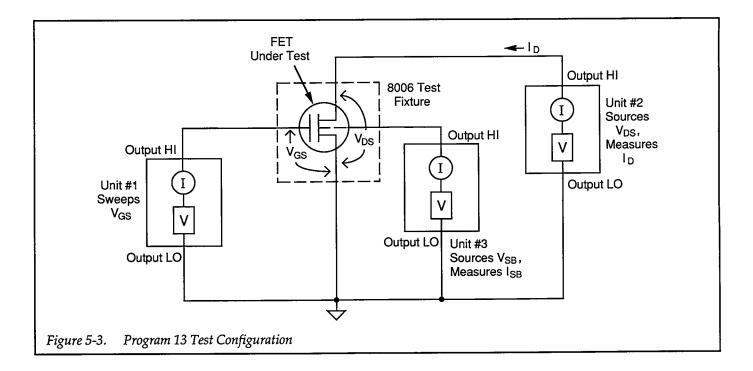
Program 13 below demonstrates methods to generate an I_{SB} vs. V_{GS} plot. Follow the steps below to use this program.

- 1. With the power off, connect all three Source Measure Units to the IEEE-488 bus of the computer.
- 2. Connect all three units to the test fixture using suitable triax cables. See Figure 5-1 for details on test connections.

NOTE

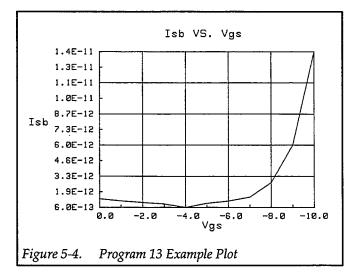
The external trigger jacks of Unit #1 and Unit #3 must be connected together instead of Unit #1 and Unit #2 as shown. Connect the TRIG-GER OUT jack of Unit #1 to the TRIGGER IN jack of Unit #3, and connect the TRIGGER OUT jack of Unit #3 to the TRIGGER IN jack of Unit #1.

- 3. Turn on all three units, and allow them to warm up for at least two hours for rated accuracy. Verify that the primary address of Unit #1 is set to 16, the primary address of Unit #2 should be set to 17, and the primary address of Unit #3 is set to 18.
- 4. Turn on the computer, then boot up BASIC.
- Enter the lines from Program 13 below into the computer.
- 6. Place a P-channel, enhancement-mode FET with substrate terminal in the appropriate test fixture socket (Keithley part number TG-51). Install the correct jumpers (including substrate bias connections), then close the test fixture lid.
- 7. RUN the program in the usual fashion. Enter the desired value of substrate bias voltage when prompted to do so. With a P-channel device, the voltage should be positive.
- 8. The computer will then step through V_{GS} values between 0V and -10V using -1V steps. At each step, the substrate current, I_{SB} , will be measured. After data are collected, a plot of I_{SB} vs. V_{GS} will be generated.
- 9. To return to BASIC from the graph, press CONT.



5.4.3 Typical Program 13 Results

Figure 5-4 shows a typical plot generated by example Program 13. This plot was made using a Keithley TG-51 MOSFET.



5.4.4 Program 13 Description

For the description below, refer to the flowchart in Figure 5-5 and the Program 13 listing.

Initially, the reading array is defined for 11 points (line 40). After all three Source Measure Units are returned to default conditions (line 50), Unit #1, which sweeps V_{GS} , is configured as follows (lines 80-180):

- Source V, sweep mode
- 1µA compliance, 1µA range
- Local sense
- External trigger, one trigger per source cycle, output trigger at end of delay
- Source only data format, no prefix, sweep data
- SRQ on sweep done
- Start V_{GS} voltage: 0V
- Stop V_{GS} voltage: -10V
- Step V_{GS} voltage: –1V
- Delay: 10sec
- Staircase sweep

Next, Unit #2, which sources V_{DS} , is set up to operate in the following manner (lines 200-260):

- Source V, dc mode
- Local sensing

- 100mA compliance, 100mA range
- GET trigger, continuous
- Fixed V_{DS} voltage: –10V

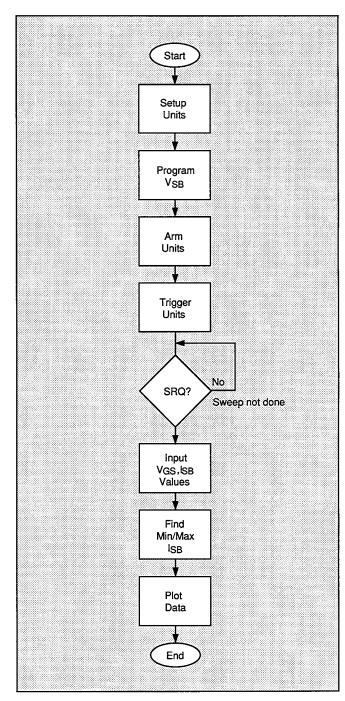


Figure 5-5. Program 13 Flowchart

Finally, Unit #3, which sources V_{SB} and measures I_{SB} , is programmed as follows (lines 280-370):

- Source V, sweep mode
- Local sensing
- 1µA compliance, autorange measure
- External trigger, output trigger at end of each measurement
- Line cycle integration, maximum filtering (32 readings)
- Constant sweep, 11 points, user programmed voltage value

After the operator signal to begin, (lines 380 and 390), all three Source Measure Units are armed and placed into operate (lines 400-420). Unit #2 is then triggered (line 430), and Unit #1 is triggered with the H0X command (line 440) to initiate the sweep.

When Unit #1 is triggered, it sets V_{GS} to the present value in its sweep list. At the end of the programmed delay period, Unit #1 triggers Unit #3 to take a current (I_{SB}) measurement via the external trigger jacks. After Unit #3 measures I_{SB} , it externally triggers Unit #1 to go to the next point in the sweep, and the process repeats.

Meanwhile, the program waits in a loop for Unit #3 to finish its sweep (lines 450 and 460), as indicated by an SRQ. When Unit #3 finishes each sweep, it generates the SRQ, and the program falls out of the loop. The sweep data are then transmitted to the computer (lines 480-510), with V_{CS} placed into array elements (I,1), and I_{SB} values stored in array elements (I,2).

Next, all three units are placed in standby (lines 520-540), and, after operator signal to continue (lines 550-560), the maximum and minimum I_{SB} values are determined (lines 580-630). Finally, the data are plotted (lines 650-940), with I_{SB} along the Y axis, and V_{DS} along the X axis.

5.4.5 Modifying Program 13

For different sweeps, the Vgstart, Vgstop, and Vgstep values can be changes as required. For different sweep lengths, array size and loop counter values must be adjusted accordingly. You can also change the V_{DS} value, if desired, by modifying that parameter accordingly.

10 REM SUBSTRATE CURRENT VS. GATE VOLTAGE TEST PROGRAM REV. 1.3 (Program 13) REM SUBSTRATE BIAS AND MEASUREMENT BY SOURCE MEASURE UNIT 20 ! First array subscript is 1 30 OPTION BASE 1 DIM Reading(11,2) | Dimension reading array (11 points) 40 50 CLEAR 7 ! Clear instruments 60 OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear screen 70 80 REMOTE 716 | Put Unit | in remote OUTPUT 716;"FØ,1X" ! Source V, sweep mode 90 OUTPUT 716;"L1E-6,4X" 100 ! luA compliance, luA range 110 OUTPUT 716;"00X" ! Local sense OUTPUT 716;"T3,1,2,0X" ! External trigger,out trig end of delay 120 130 OUTPUT 716; "G1,2,1X" I Source data,no prefix, sweep data OUTPUT 716;"M2,X" I SRQ on sweep done 140 OUTPUT 716;"B0,0,0X" 145 ! Program 0 bias value 150 Vostart=0 ! Define ØV start Vgs voltage Vastop=-10 ! Define -10V stop Vgs voltage 160 170 ! Define -1V step Vgs voltage Vgstep=-1 ! Define 10sec Unit delay 180 Dly=10000 OUTPUT 716;"Q1,";Vgstart;",";Vgstop;",";Vgstep;",0,";Dly;"X" ! Pgm swp 190 200 | Put Unit 2 in remote 210 REMOTE 717 220 OUTPUT 717;"F0,0X" ! Source V, DC mode OUTPUT 717;"OØX" 230 ! Local sensing OUTPUT 717; "L100E-3,9X" ! 100mA compliance, 100mA range 240 OUTPUT 717; "T1,0,0,0X" 250 | Trigger on GET,continuous ! Define -10V Vds 260 Vds = -10OUTPUT 717;"B";Vds;",0,0X" I Program Vds 270 280 290 REMOTE 718 ! Put Unit 3 in remote OUTPUT 718; "F0,1X" ! Source V, sweep mode 300 OUTPUT 718;"00Z0X" ! Local sensing, suppress off 310 OUTPUT 718;"L1E-6,0X" 320 ! 1uA compliance,autorange measure OUTPUT 718; "T3,1,4,0X" OUTPUT 718; "64,2,1X" OUTPUT 718; "S2P5X" ! Trigger on ext, out trig end of meas 330 ! Measure data,no prefix,sweep data 340 350 Line cycle integration, max filtering OUTPUT 718;"B0,0,0X" 355 | Program Ø bias value INPUT "Enter substrate bias (>0)", Vsub! Input desired substrate bias 360 OUTPUT 718; "Q0, "; Vsub; ",0, "; Dly; ",11X" ! Program substrate bias 370 PRINT "Close lid, press CONT to begin test" 380 390 PAUSE OUTPUT 716; "RIN1X" ! Arm Unit 1 trigger, turn on output 400 OUTPUT 717; "RIN1X" ! Arm Unit 2 trigger, turn on output 410 OUTPUT 718; "RINIX" 420 I Arm Unit 3 trigger, turn on output | Trigger Unit 2 430 TRIGGER 717 ! Trigger Unit 1 to start sweep 440 OUTPUT 716; "HØX" 450 STATUS 7,7;Stat ! Get bus status IF NOT BIT(Stat,10) THEN 450 ! Wait for SRQ 460 470 ! Serial poll Unit 1 to clear SRQ Stat=SPOLL(716) 480 FOR I=1 TO 11 ! Loop for all 11 readings ENTER 716;Reading(I,1) 490 | Get Vgs data from Unit 2 500 ENTER 718;Reading(I,2) | Get Isb data from Unit 3

```
510
      NEXT I
                                      ! Loop back for next Vgs value
520
      OUTPUT 716; "NØX"
                                     ! Turn off Unit 1 output
                                     ! Turn off Unit 2 output
530
      OUTPUT 717; "NØX"
                                     ! Turn off Unit 3 output
540
      OUTPUT 718; "NØX"
550
      PRINT "Press CONT to display graph"
560
      PRINT "Press CONT while in graph to return to BASIC"
570
      PAUSE
580
      Ymin=MAXREAL
                                     I Find minimum and maximum Isb value
590
      Ymax=-MAXREAL
600
      FOR I=1 TO 11
610
      IF Reading(I,2)<Ymin THEN Ymin=Reading(I,2)
620
      IF Reading(I,2)>Ymax THEN Ymax=Reading(I,2)
630
      NEXT I
640
      OUTPUT KBD; CHR$(255); CHR$(75); ! Clear screen
650
      GINIT
                                     ! Initialize graphics
660
      PLOTTER IS CRT, "INTERNAL"
                                     ! Define plot to CRT
670
      GRAPHICS ON
                                     ! Turn on graphics
680
      MOVE 55,90
                                     ! Title graph
690
      LABEL "Isb VS. Vgs"
                                     | Label X axis
700
      MOVE 70,10
      LABEL "Vgs"
710
720
      MOVE 0,53
                                     ! Label Y axis
      LABEL "Isb"
730
740
      VIEWPORT 30,120,20,85
                                    ! Define soft clip limits
750
      WINDOW Vgstart, Vgstop, Ymin, Ymax ! Scale graph
760
      Y1=(Ymax-Ymin)/10
                                     | Compute Y axis increment
      X1=(Vgstop-Vgstart)/10
770
                                     I Compute X axis increment
780
      GRID 2*X1,2*Y1,Vgstart,Ymin
                                    ! Draw grid
790
      AXES X1,Y1,Vgstart,Ymin
                                     ! Add some tick marks
800
      PLOT Reading(*)
                                     ! Plot reading array
                                     ! Define character size
810
      CSIZE 4
820
     LORG 5
                                      I Center characters
830
                                      ! Turn off soft clipping
      CLIP OFF
      FOR I=Vgstart TO Vgstop+.01*X1 STEP 2*X1 ! Number X axis
840
850
      MOVE I, Ymin-(Y1/4)
860
      LABEL USING "#,MDD.D"; I
870
      NFXT I
880
      FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis
890
      MOVE Vgstart-(1.3*X1),I+(.3*Y1)
900
      LABEL USING "#,MD.DE";I
910
      NEXT I
920
      PAUSE
930
      OUTPUT KBD; CHR$(255); CHR$(75); ! Clear alpha screen
940
      GRAPHICS OFF
                                      ! Clear graphics screen
950
      END
```

5.4.6 Program 14 Test Configuration

Figure 5-6 shows the test configuration for Program 14 listed below. Unit #1 is used to sweep V_{GS} , while Unit #2 sweeps V_{DS} and measures I_D . Unit #3 applies a user-defined substrate bias to the device under test. Common source characteristics are generated by data taken when the program is run.

5.4.7 Example Program 14: Commonsource Characteristics with Source Measure Unit Substrate Bias

Program 14 below demonstrates common-source characteristic test programming with substrate bias. Follow the steps below to use this program.

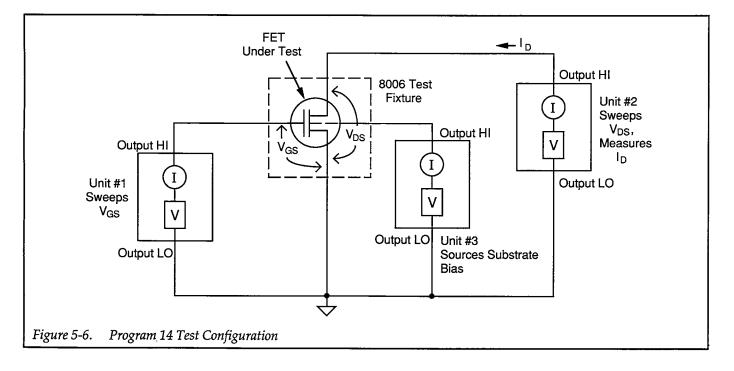
- 1. With the power off, connect all three Source Measure Units to the IEEE-488 bus of the computer.
- 2. Connect all three units to the test fixture using suitable triax cables (see Figure 5-1 for details on test connections).
- 3. Turn on all three units, and allow them to warm up for at least two hours for rated accuracy. Verify that the primary address of Unit #1 is set to 16, the pri-

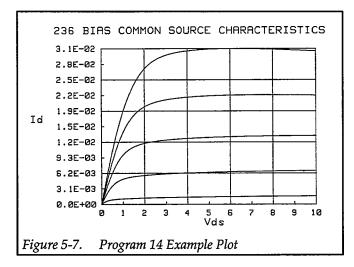
mary address of Unit #2 is at 17, and the primary address of Unit #3 is set to 18.

- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines from Program 14 below into the computer.
- 6. Place a packaged device containing N-channel, depletion-mode FETs in the appropriate test fixture socket (the devices should have characteristics similar to the 2N4392 JFET used for other examples in this section). Install the correct jumpers (including substrate bias connections), then close the test fixture lid.
- 7. RUN the program in the usual fashion. Enter the desired value of substrate bias when prompted to do so.
- 8. The unit will then step through V_{GS} values between -2V and 0V using 0.5V steps. At each step, V_{DS} will be stepped between 0V and 10V at 0.1V increments. At each increment, I_D will be measured. Once data are collected, a plot of I_D vs. V_{DS} for each V_{GS} value will be displayed.
- 9. To return to BASIC from the graph, press CONT.

5.4.8 Typical Program 14 Results

Figure 5-7 shows a typical plot generated by example Program 14.





5.4.9 Program 14 Description

For the description below, refer to the flowchart in Figure 5-8 and the Program 14 listing.

Initially, the reading array is defined for five sweeps with 101 points each (lines 30 and 40). After all three Source Measure Units are returned to default conditions (line 50), Unit #1, which sweeps V_{GS} , is configured as follows (lines 80-170):

- Source V, sweep mode
- 1mA compliance, 1mA range
- Local sense
- Get trigger, one trigger per source cycle, output trigger at end of delay
- Start V_{GS} voltage: -2V
- Stop V_{GS} voltage: 0V
- Step V_{GS} voltage: 0.5V
- Delay: 100msec
- Staircase sweep

Next, Unit #2, which sweeps V_{DS} and measures I_D , is set up to operate in the following manner (lines 200-310):

- Source V, sweep mode
- Local sensing
- 100mA compliance, autorange measure
- Source and measure data format, no prefix, sweep data
- SRQ on sweep done
- External trigger, continuous
- Line cycle integration
- Suppress enabled
- Start V_{DS} voltage: 0V
- Stop V_{DS} voltage: 10V

- Step V_{DS} voltage: 0.1V
- Delay: 100msec
- Staircase sweep

Finally, Unit #3, which provides substrate bias, is programmed as follows (lines 330-390):

- Source V, dc mode
- Local sensing
- 10mA compliance, autorange measure
- Trigger on GET, continuous
- Dc output, voltage determined by user input

After the operator signal to begin, (lines 400 and 410), all three Source Measure Units are armed and placed into operate (lines 420-440). Unit #3 is then triggered (line 450), and the program enters the main program loop to perform five I_D vs. V_{DS} sweeps, one for each of five V_{GS} values (line 460).

Unit #1 is GET triggered to initiate each sweep, at which point it sets V_{GS} to the present value in its sweep list. At the end of the programmed delay period, Unit #1 triggers Unit #2 to begin its sweep via the external trigger jacks. Unit #2 then cycles through its sweep list, setting V_{DS} to the required values, and measuring I_D at each step along the way.

Meanwhile, the program waits in a loop for Unit #2 to finish its sweep (lines 490 and 500), as indicated by an SRQ. When Unit #2 finishes each sweep, it generates the SRQ, and the program falls through the loop. The sweep data are then transmitted to the computer (lines 520-540), with V_{DS} placed into array elements (I,J,1), and I_D values stored in array elements (I,J,2). The program then loops back for the next sweep until all five sweeps have been performed (line 550).

Next, all three units are placed in standby (lines 560-580), and, after operator signal to continue (lines 570-580), the maximum and minimum I_D values are determined (lines 620-690). Finally, the data are plotted (lines 710-1050), with I_D along the Y axis, and V_{DS} along the X axis.

5.4.10 Modifying Program 14

For different sweeps, the Vgstart, Vgstop, Vgstep, Vdstart, Vdstop, and Vdstep values can be changed as required. For different sweep lengths, array size and loop counter values must be adjusted accordingly.

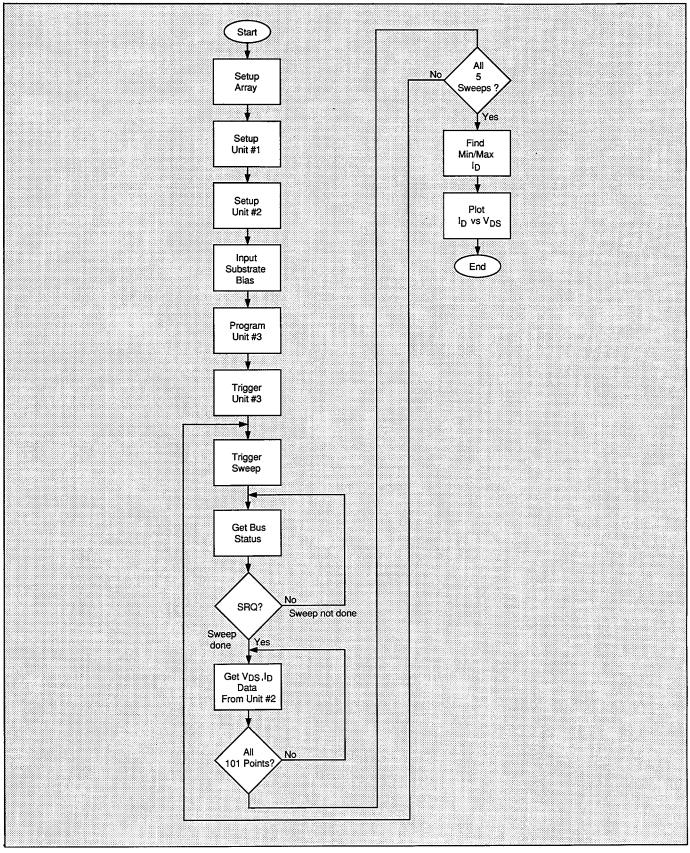


Figure 5-8. Program 14 Flowchart

10 REM COMMON SOURCE CHARACTERISTIC TEST PROGRAM REV. 1.3 (Program 14) 20 REM INCLUDES SUBSTRATE BIAS PROGRAMMING FOR Unit 3 30 OPTION BASE 1 ! First array subscript is 1 40 DIM Reading(5,101,2) | Dimension reading array (5 swps,100 pts) 50 ! Clear instruments CLEAR 7 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 60 70 80 REMOTE 716 ! Put Unit 1 in remote 90 OUTPUT 716; "F0,1X" ! Source V, sweep mode OUTPUT 716; "L1E-3,7X" 1 1mA compliance, 1mA range 100 OUTPUT 716; "00X" ! Local sense 110 OUTPUT 716; "T1,1,2,0X" ! GET trigger cycle,out trig end of delay 120 125 OUTPUT 716; "B0,0,0X" ! Program Ø bias value ! Define -2V start Vgs voltage 130 Vostart=-2 ! Define ØV stop Vgs voltage 140 Vqstop=0 150 ! Define 0.5V step Vgs voltage Vgstep=.5 160 D1v = 100! Define 100msec Unit delay 170 OUTPUT 716; "Q1, "; Vgstart; ", "; Vgstop; ", "; Vgstep; ", 0, "; Dly; "X" ! Pgm swp 180 190 REMOTE 717 ! Put Unit 2 in remote OUTPUT 717; "F0,1X" 200 ! Source V, sweep mode 210 OUTPUT 717; "OØX" ! Local sensing 220 OUTPUT 717; "L100E-3,0X" ! 100mA compliance, autorange measure 230 OUTPUT 717; "G5,2,1X" ! Source,measure,no prefix,sweep data 240 OUTPUT 717; "M2,X" ! SRQ on sweep done 250 OUTPUT 717; "T3,0,0,0X" ! Trigger on external, continuous 260 OUTPUT 717; "S2X" ! Line cycle integration OUTPUT 717;"B0,0,0X" 265 ! Program Ø bias value 270 OUTPUT 717; "Z1X" ! Enable suppress ! Define ØV start Vds 280 Vdstart=0 ! Define 10V stop Vds 290 Vdstop=10 ! Define 0.1V step Vds 300 Vdstep=.1 OUTPUT 717;"Q1,";Vdstart;",";Vdstop;",";Vdstep;",0,";Dly;"X" ! Pgm swp 310 320 ! Put Unit 3 in remote 330 REMOTE 718 OUTPUT 718; "F0,0X" 340 ! Source V, DC mode OUTPUT 718;"00X" 350 ! Local sensing OUTPUT 718; "L1E-3,7X" 360 1 1mA compliance, 1mA range OUTPUT 718;"T1,0,0,0X" 370 ! Trigger on GET, continuous INPUT "Enter substrate bias", Vsub! Input desired substrate bias voltage 380 OUTPUT 718; "B"; Vsub; ",0,0X" | Program substrate bias 390 400 PRINT "Close lid, press CONT to begin test" 410 PAUSE 420 OUTPUT 716; "RINIX" ! Arm Unit 1 trigger, turn on output ! Arm Unit 2 trigger, turn on output OUTPUT 717; "RINIX" 430 440 OUTPUT 718; "RIN1X" ! Arm Unit 3 trigger, turn on output 450 TRIGGER 718 ! Trigger Unit 3 460 FOR I=1 TO 5 ! Loop for five Vgs curves PRINT "Generating sweep"; I 470 480 TRIGGER 716 ! Trigger Unit 1 to start sweep ! Get IEEE-488 bus status 490 STATUS 7,7;Stat 500 IF NOT BIT(Stat, 10) THEN 490 ! Wait for Unit 2 SRQ on sweep done

510 ! Serial poll Unit 2 to clear SRQ Stat=SPOLL(717) 520 FOR J=1 TO 101 ! Loop for all 101 readings 530 ENTER 717;Reading(I,J,1),Reading(I,J,2) ! Get reading data from Unit 2 540 NEXT J ! Loop back for next reading 550 NEXT I I Loop back for next Vos value 560 OUTPUT 716; "NØX" ! Turn off Unit 1 output 570 OUTPUT 717; "NØX" ! Turn off Unit 2 output 580 OUTPUT 718; "NØX" | Turn off Unit 3 output 590 PRINT "Press CONT to display graph" PRINT "Press CONT while in graph to return to BASIC" 600 610 PAUSE 620 Ymin=MAXREAL ! Find minimum and maximum Id value 630 Ymax=-MAXREAL FOR I=1 TO 5 640 650 FOR J=1 TO 101 660 IF Reading(I,J,2)<Ymin THEN Ymin=Reading(I,J,2) 670 IF Reading(I,J,2)>Ymax THEN Ymax=Reading(I,J,2) 680 NEXT J NEXT I 690 700 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 710 GINIT ! Initialize graphics 720 PLOTTER IS CRT, "INTERNAL" ! Define plot to CRT 730 GRAPHICS ON ! Turn on graphics 740 MOVE 10,90 ! Title graph 750 LABEL "236 BIAS COMMON SOURCE CHARACTERISTICS" 760 MOVE 70,10 ! Label X axis 770 LABEL "Vds" 780 ! Label Y axis MOVE 0,53 LABEL "Id" 790 800 VIEWPORT 30,120,20,85 ! Define soft clip limits 810 WINDOW Vdstart, Vdstop, Ymin, Ymax ! Scale graph 820 Y1=(Ymax-Ymin)/10 ! Compute Y axis increment X1=(Vdstop-Vdstart)/10 830 ! Compute X axis increment 840 GRID 2*X1,2*Y1,Vdstart,Ymin | Draw grid 850 AXES X1,Y1,Vdstart,Ymin ! Add some tick marks 860 FOR I=1 TO 5 ! Loop for all five curves 870 FOR J=1 TO 101 ! Loop for all 101 points per curve 880 PLOT Reading(I,J,1), Reading(I,J,2) ! Plot point 890 ! Plot next point NEXT J 900 PENUP 910 NEXT I ! Plot next curve 920 CSIZE 4 | Define character size 930 LORG 6 ! Center characters 940 CLIP OFF ! Turn off soft clipping 950 FOR I=Vdstart TO Vdstop+.01*X1 STEP X1 ! Number X axis 960 MOVE I, Ymin-(Y1/4) 970 LABEL USING "#,K";I 980 NEXT I 990 FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis 1000 MOVE Vdstart-(1.3*X1),I+(.3*Y1)

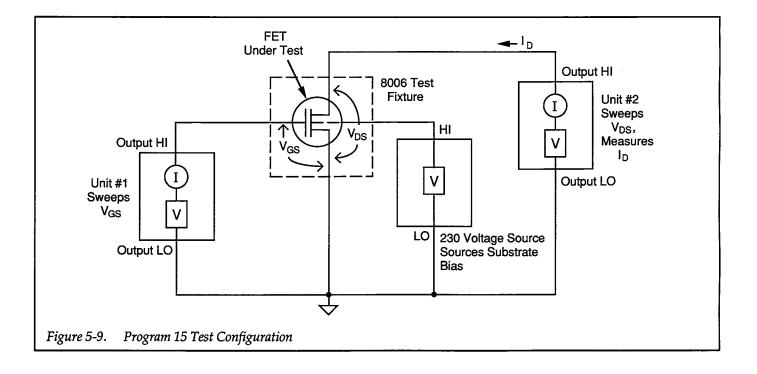
1010 LABEL USING "#,MD.DE";I
1020 NEXT I
1030 PAUSE
1040 OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear alpha screen
1050 GRAPHICS OFF ! Clear graphics screen
1060 END

5.5 VOLTAGE SOURCE SUBSTRATE BIASING

The following paragraphs discuss using a Model 230 Programmable Voltage Source to bias the substrate. Once again, the example programs included in this paragraph are modified versions of the common-source and common-emitter characteristic test programs presented earlier in this manual.

5.5.1 Program 15 Test Configuration

Figure 5-9 shows the test configuration for Program 15 listed below. Unit #1 is used to sweep V_{CS} . Unit #2 sweeps V_{DS} , and the instrument also measures I_D . The Model 230 Voltage Source applies a substrate bias (defined by the user) to the device under test.



5.5.2 Example Program 15: Commonsource Characteristics with Voltage Source Substrate Bias

Program 15 below demonstrates common-source characteristic test programming with substrate bias applied by a separate voltage source. Proceed as outlined below.

- 1. With the power off, connect both Source Measure Units and the voltage source to the IEEE-488 bus of the computer.
- Connect both units to the test fixture using suitable triax cables. Also, connect the voltage source output to the binding posts (or use BNC connections for shielding). See Figure 5-2 for details on test connections.
- 3. Turn on all three instruments, and allow them to warm up for at least two hours for rated accuracy. Verify that the primary address of Unit #1 is set to 16, the primary address of Unit #2 is set to 17, and that the primary address of the voltage source is set to 13.
- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines from Program 15 below into the computer.
- 6. Place a device containing an N-channel, depletionmode FET in the appropriate test fixture socket (FET characteristics should be similar to those of the 2N4392 JFET used for other examples in this section). Install the correct jumpers (including substrate bias connections), then close the test fixture lid.
- RUN the program in the usual fashion. Enter the desired value of substrate bias when prompted to do so.
- 8. The computer will then step through V_{GS} values between -2V and 0V using 0.5V steps. At each step, V_{DS} will be stepped between 0V and 10V at 0.1V increments. At each increment, I_D will be measured. Once data are collected, a plot of I_D vs. V_{DS} for each V_{GS} value will be displayed.
- 9. To return to BASIC from the graph, press CONT.

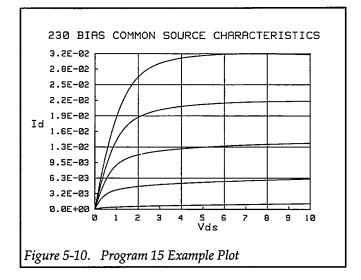
5.5.3 Typical Program 15 Results

A typical plot generated by Program 15 is shown in Figure 5-10.

5.5.4 Program 15 Description

For the description below, refer to the flowchart in Figure 5-11 and the Program 15 listing also shown below.

First, the reading array is defined for five sweeps with 101 points each (lines 30 and 40). After all three instru-



ments are returned to default conditions (line 50), Unit #1, which sweeps V_{GS}, is configured as follows (lines 80-170):

- Source V, sweep mode
- 1mA compliance, 1mA range
- Local sense
- Get trigger, one trigger per source cycle, output trigger at end of delay
- Start V_{GS} voltage: -2V
- Stop V_{GS} voltage: 0V
- Step V_{GS} voltage: 0.5V
- Delay: 100msec
- Staircase sweep

Next, Unit #2, which sweeps V_{DS} and measures I_D , is set up to operate in the following manner (lines 190-310):

- Source V, sweep mode
- Local sensing
- 100mA compliance, autorange measure
- Source and measure data format, no prefix, sweep data
- SRQ on sweep done
- External trigger, continuous
- Line cycle integration
- Suppress enabled
- Start V_{DS} voltage: 0V
- Stop V_{DS} voltage: 10V
- Step V_{DS} voltage: 0.1V
- Delay: 100msec
- Staircase sweep

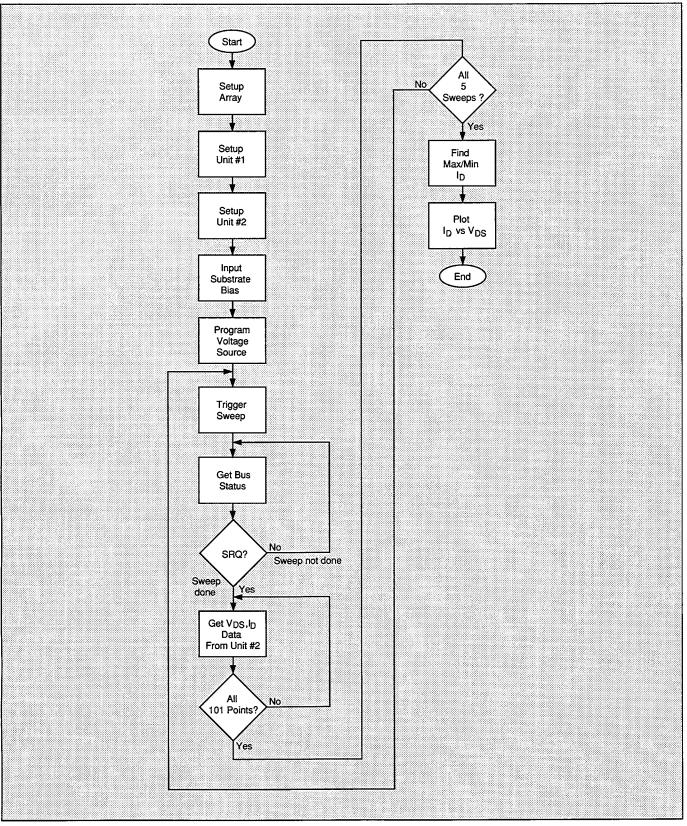


Figure 5-11. Program 15 Flowchart

Finally, the Model 230 Voltage Source, which provides substrate bias, is programmed with the user-input substrate bias voltage (lines 330-350).

After the operator signal to begin, (lines 360 and 370), both Source Measure Units are armed and placed into operate (lines 380 and 390). The voltage source output is turned on (line 400), and the program enters the main program loop to perform five I_D vs. V_{DS} sweeps, one for each of five V_{CS} values (line 410).

Unit #1 is GET triggered to initiate each sweep, at which point it sets V_{GS} to the present value in its sweep list. At the end of the programmed delay period, Unit #1 triggers Unit #2 to begin its sweep via the external trigger jacks. Unit #2 then cycles through its sweep list, setting V_{DS} to the required values, and measuring I_D at each step along the way.

At the same time, the program waits in a loop for Unit #2 to finish its sweep (lines 440 and 450), as indicated by an

SRQ. When Unit #2 finishes each sweep, it generates the SRQ, and the program falls through the loop. The sweep data are then transmitted to the computer (lines 470-490), with V_{DS} placed into array elements (I,J,1), and I_D values stored in array elements (I,J,2). The program then loops back for the next sweep until all five sweeps have been performed (line 500).

Next, both units and the voltage source are placed in standby (lines 510-530), and, after operator signal to continue (lines 540 and 550), the maximum and minimum I_D values are determined (lines 70-640). Finally, the data are plotted (lines 660-1000), with I_D along the Y axis, and V_{DS} along the X axis.

5.5.5 Modifying Program 15

For different sweeps, the Vgstart, Vgstop, Vgstep, Vdstart, Vdstop, and Vdstep values can be changed as required. For different sweep lengths, array size and loop counter values must be adjusted accordingly.

10 REM COMMON SOURCE CHARACTERISTIC TEST PROGRAM REV. 1.3 (Program 15) 20 REM INCLUDES SUBSTRATE BIAS PROGRAMMING FOR 230 VOLTAGE SOURCE 30 ! First array subscript is 1 OPTION BASE 1 DIM Reading(5,101,2) ! Dimension reading array (5 swps,101 pts) 40 50 CLEAR 7 ! Clear instruments OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear screen 60 70 80 REMOTE 716 ! Put Unit 1 in remote OUTPUT 716; "F0,1X" I Source V, sweep mode 90 100 OUTPUT 716; "L1E-3,7X" | 1mA compliance, 1mA range 110 OUTPUT 716; "OØX" ! Local sense 120 OUTPUT 716; "T1,1,2,0X" ! GET trigger cycle,out trig end of delay 125 OUTPUT 716; "B0,0,0X" ! Program Ø bias value 130 ! Define -2V start Vgs voltage Vostart=-2 ! Define ØV stop Vgs voltage 140 Vgstop=0 150 ! Define 0.5V step Vgs voltage Vgstep=.5 ! Define 100msec Unit delay 160 D1y=100 170 OUTPUT 716;"Q1,";Vgstart;",";Vgstop;",";Vgstep;",0,";Dly;"X" ! Pgm swp 180 ! Put Unit 2 in remote 190 REMOTE 717 200 OUTPUT 717; "F0,1X" ! Source V, sweep mode OUTPUT 717;"OØX" 210 ! Local sensing ! 100mA compliance,autorange measure 220 OUTPUT 717; "L100E-3,0X" OUTPUT 717; "G5,2,1X" ! Source,measure,no prefix,sweep data 230 ! SRQ on sweep done 240 OUTPUT 717; "M2,X" OUTPUT 717; "T3,0,0,0X" 250 ! Trigger on external, continuous OUTPUT 717; "S2X" ! Line cycle integration 260 OUTPUT 717; "B0,0,0X" 265 ! Program Ø bias value 270 | Enable suppress OUTPUT 717; "Z1X" ! Define ØV start Vds 280 Vdstart=0 ! Define 10V stop Vds 290 Vdstop=10 1 Define 0.1V step Vds 300 Vdstep=.1 310 OUTPUT 717;"Q1,";Vdstart;",";Vdstop;",";Vdstep;",0,";Dly;"X" ! Pgm swp 320 REM ******** 230 voltage source setup (provides substrate bias) ******** ! Put 230 in remote 330 REMOTE 713 INPUT "Enter substrate bias", Vsub! Input desired substrate bias voltage 340 OUTPUT 713; "V"; Vsub; "X" 350 ! Program substrate bias PRINT "Close lid, press CONT to begin test" 360 370 PAUSE ! Arm Unit 1 trigger, turn on output 380 OUTPUT 716; "RINIX" ! Arm Unit 2 trigger, turn on output 390 OUTPUT 717; "RINIX" OUTPUT 713; "F1X" ! Turn on 230 output 400 410 FOR I=1 TO 5 ! Loop for five Vgs curves 420 PRINT "Generating sweep"; I ! Trigger Unit 1 to start sweep 430 TRIGGER 716 ! Get IEEE-488 bus status STATUS 7,7;Stat 440 ! Wait for Unit 2 SRQ on sweep done 450 IF NOT BIT(Stat,10) THEN 440 Stat=SPOLL(717) ! Serial poll Unit 2 to clear SRQ 460 ! Loop for all 101 readings 470 FOR J=1 TO 101 ENTER 717;Reading(I,J,1),Reading(I,J,2) ! Get reading data from Unit 2 480 ! Loop back for next reading 490 NEXT J NEXT I 500 ! Loop back for next Vqs value | Turn off Unit 1 output 510 OUTPUT 716; "NØX"

520 OUTPUT 717; "NØX" ! Turn off Unit 2 output OUTPUT 713; "FØX" ! Turn off 230 output 530 PRINT "Press CONT to display graph" 540 550 PRINT "Press CONT while in graph to return to BASIC" 560 PAUSE Ymin=MAXREAL ! Find minimum and maximum Id value 570 Ymax=-MAXREAL 580 FOR I=1 TO 5 590 600 FOR J=1 TO 101 610 IF Reading(I,J,2)<Ymin THEN Ymin=Reading(I,J,2) IF Reading(I,J,2)>Ymax THEN Ymax=Reading(I,J,2) 620 NEXT J 630 640 NEXT I 650 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 660 GINIT ! Initialize graphics PLOTTER IS CRT, "INTERNAL" ! Define plot to CRT 670 680 GRAPHICS ON ! Turn on graphics 690 MOVE 10,50 ! Title graph 700 LABEL "230 BIAS COMMON SOURCE CHARACTERISTICS" ! Label X axis 710 MOVE 70,10 LABEL "Vds" 720 MOVE 0,53 ! Label Y axis 730 LABEL "Id" 740 750 VIEWPORT 30,120,20,85 ! Define soft clip limits WINDOW Vdstart,Vdstop,Ymin,Ymax ! Scale graph 760 770 Y1=(Ymax-Ymin)/10 I Compute Y axis increment X1=(Vdstop-Vdstart)/10 780 I Compute X axis increment 790 GRID 2*X1,2*Y1,Vdstart,Ymin | Draw grid 800 AXES X1,Y1,Vdstart,Ymin ! Add some tick marks 810 FOR I=1 TO 5 | Loop for all five curves 820 FOR J=1 TO 101 ! Loop for all 101 points per curve PLOT Reading(I,J,1),Reading(I,J,2) ! Plot point 830 340 ! Plot next point NEXT J 850 PENUP 860 NEXT I ! Plot next curve ! Define character size 870 CSIZE 4 880 LORG 6 ! Center characters CLIP OFF ! Turn off soft clipping 890 900 FOR I=Vdstart TO Vdstop+.01*X1 STEP X1! Number X axis 910 MOVE I, Ymin-(Y1/4) 920 LABEL USING "#,K";I 930 NEXT I FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis 940 950 MOVE Vdstart-(1.3*X1),I+(.3*Y1) LABEL USING "#,MD.DE";I 960 970 NEXT I 980 PAUSE 990 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear alpha screen 1000 GRAPHICS OFF ! Clear graphics screen 1010 END

5.5.6 Program 16 Test Configuration

Figure 5-12 shows the test configuration for Program 16 listed below. Unit #1 is used to sweep I_B , while Unit #2 sweeps V_{CE} and measures I_C . The voltage source applies a user-programmed substrate bias to the device under test.

5.5.7 Example Program 16: Commonemitter Characteristics with Voltage Source Substrate Bias

Program 16 below demonstrates common-emitter characteristic test programming with substrate bias. Proceed as follows:

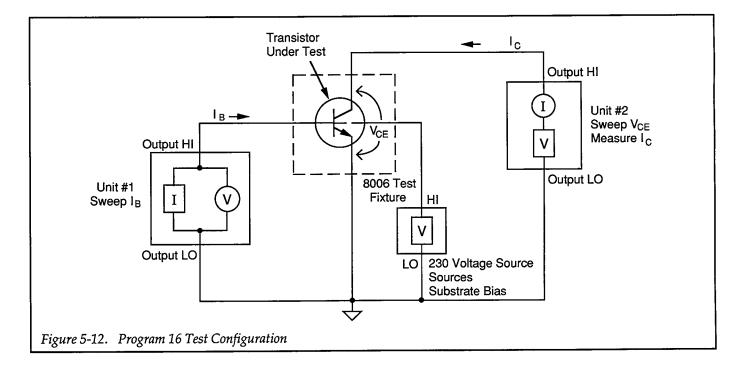
- 1. With the power off, connect both Source Measure Units and the voltage source to the IEEE-488 bus of the computer.
- 2. Connect both units to the test fixture using suitable triax cables, and connect the voltage source to the binding posts using patch cords (or use coax cable and BNC connections for shielding). See Figure 5-2 for details on test connections.
- 3. Turn on all three instruments, and allow them to warm up for at least two hours for rated accuracy. Verify that the primary address of Unit #1 is set to 16,

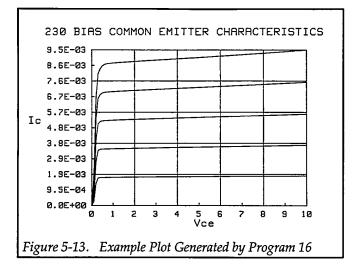
the primary address of Unit #2 is set to 17, and the primary address of the Model 230 Voltage Source is set to 13.

- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines from Program 16 below into the computer.
- 6. Place a device containing an NPN bipolar transistor in the appropriate test fixture socket (the device should have characteristics similar to a 2N3904 or 2N5089, which are used for other examples in this section). Install the correct jumpers (including substrate bias connections), then close the test fixture lid.
- 7. RUN the program in the usual fashion. Enter the desired value of substrate bias when prompted to do so.
- 8. The computer will then step through I_B values between 10µA and 50µA using 10µA steps. At each step, V_{CE} will be stepped between 0V and 10V at 0.1V increments. At each increment, I_C will be measured. Once data are collected, a plot of I_C vs. V_{CE} for each I_B value will be displayed.
- 9. To return to BASIC from the graph, press CONT.

5.5.8 Typical Program 16 Results

Figure 5-13 shows a typical plot generated by example Program 16.





5.5.9 Program 16 Description

For the description below, refer to the flowchart in Figure 5-14 as well as the Program 16 listing below.

Initially, the reading array is defined for five sweeps with 101 points each (lines 30 and 40). After all three instruments are returned to default conditions (line 50), Unit #1, which sweeps I_{B} , is configured as follows (lines 80-170):

- Source I, sweep mode
- 1V compliance, 1.1V range
- Local sense
- Get trigger, one trigger per source cycle, output trigger at end of delay
- Start I_B current: 10μA
- Stop I_B current: 50μA
- Step I_B current: 10μA
- Delay: 100msec
- Staircase sweep

Next, Unit #2, which sweeps V_{CE} and measures I_c , is set up to operate in the following manner (lines 190-310):

- Source V, sweep mode
- Local sensing
- 100mA compliance, autorange measure
- Source and measure data format, no prefix, sweep data
- SRQ on sweep done
- External trigger, continuous
- Line cycle integration

- Suppress enabled
- Start V_{CE} voltage: 0V
- Stop V_{CE} voltage: 10V
- Step V_{CE} voltage: 0.1V
- Delay: 100msec
- Staircase sweep

Finally, the voltage source, which provides substrate bias, is programmed with the user-input voltage value (lines 320-350).

After the operator signal to begin, (lines 360 and 370), both Source Measure Units are armed and placed into operate (lines 380 and 390). The voltage source is placed into operate (line 400), and the program enters the main program loop to perform five I_C vs. V_{CE} sweeps, one for each of five I_B values (line 410).

Unit #1 is GET triggered to initiate each sweep (line 430), at which point it sets I_B to the present value in its sweep list. At the end of the programmed delay period, Unit #1 triggers Unit #2 to begin its sweep via the external trigger jacks. Unit #2 then cycles through its sweep list, setting V_{CE} to the required values, and measuring I_C at each step along the way.

At the same time, the program waits in a loop for Unit #2 to finish its sweep (lines 440 and 450), as indicated by an SRQ. When Unit #2 finishes each sweep, it generates the SRQ, and the program falls through the loop. The sweep data are then transmitted to the computer (lines 470-490), with V_{CE} values placed into array elements (I,J,1), and I_C values stored in array elements (I,J,2). The program then loops back for the next sweep until all five sweeps have been performed (line 500).

Next, both units and the voltage source are placed in standby (lines 510-530), and, after operator signal to continue (lines 540-560), the maximum and minimum I_C values are determined (lines 570-640). Finally, the data are plotted (lines 660-1000), with I_C along the Y axis, and V_{CE} along the X axis.

5.5.10 Modifying Program 16

For different sweeps, the Istart, Istop, Istep, Vstart, Vstop, and Vstep values can be changed as required. For different sweep lengths, array size and loop counter values must be adjusted accordingly.

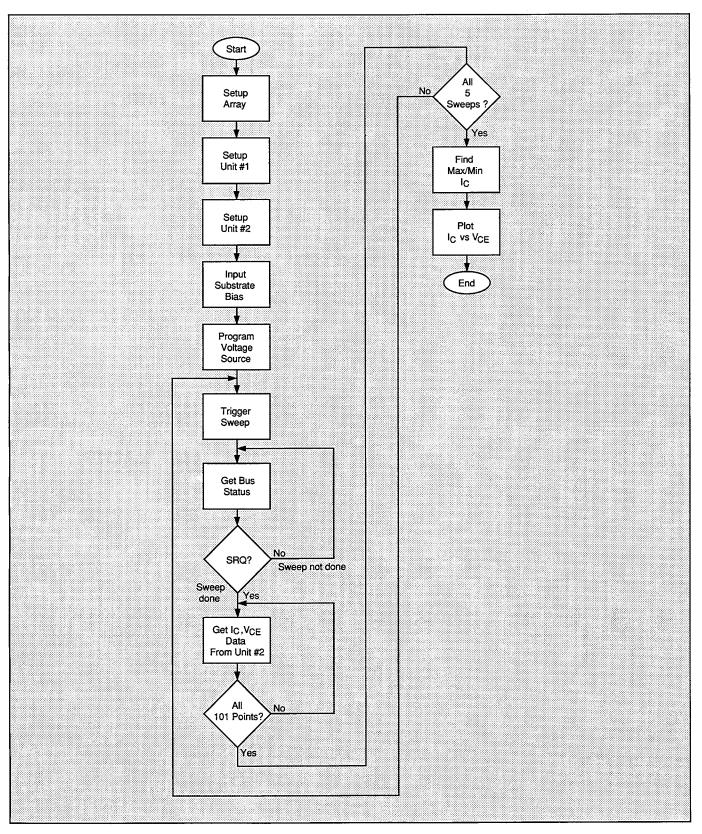


Figure 5-14. Program 16 Flowchart

10			
20	REM INCLUDES SUBSTRATE BIAS PRO	GRAMMING FOR 230 VOLTAGE SOURCE	
30		! First array subscript is 1	
40		! Dimension reading array (5 swps,101pts)	
50		! Clear instruments	
	OUTPUT KBD;CHR\$(255);CHR\$(75);		
60			
70		Ib) ************************************	
80		! Put Unit 1 in remote	
90		! Source I, sweep mode	
100	OUTPUT 716;"L1,1X"	! 1V compliance, 1.1V range	
110	OUTPUT 716;"00X"	! Local sense	
120	OUTPUT 716;"T1,1,2,0X"	! GET trigger cycle,out trig end of delay	
125		! Program Ø bias value	
130		! Define 10uA start Ib current	
140		! Define 50uA stop Ib current	
150		! Define 10uA step 15 current	
160			
1		! Define 100msec Unit delay	
170		op;",";Istep;",0,";Dly;"X" ! Program sweep	
180		Vce, measures Ic) **************	
190		! Put Unit 2 in remote	
200	OUTPUT 717;"F0,1X"	! Source V, sweep mode	
210	OUTPUT 717;"OØX"	Local sensing	
220	OUTPUT 717;"L100E-3,0X"	! 100mA compliance,autorange measure	
230		! Source,measure,no prefix,sweep data	
240	• •	! SRQ on sweep done	
250		! Trigger on external	
260		! Line cycle integration	
265		! Program Ø bias value	
270		! Enable suppress	
280		! Define ØV start Vce	
290		! Define 10V stop Vce	
300	Vstep=.1	! Define 0.1V step Vce	
310	OUTPUT 717;"Q1,";Vstart;",";Vst	op;",";Vstep;",0,";Dly;"X" ! Program sweep	
320	REM ****** 230 voltage source setup (provides substrate bias) ***********		
330		! Put 230 in remote	
340		ub! Input desired substrate bias voltage	
350		! Program 230 with substrate bias	
360	PRINT "Close lid, press CONT to	-	
370	•		
		1 App Upit 1 their paper type	
380		! Arm Unit 1 trigger, turn on output	
390		! Arm Unit 2 trigger, turn on output	
400		! Turn on 230 output	
410		! Loop for five Ib curves	
420	PRINT "Generating sweep";I		
430	TRIGGER 716	! Trigger Unit to start sweep	
440		! Get IEEE-488 bus status	
450		! Wait for Unit 2 SRQ on sweep done	
450	•	! Serial poll Unit 2 to clear SRQ	
470		! Loop for all 101 readings	
480		g(I,J,2)! Get reading data from Unit 2	
490		! Loop back for next reading	
500		! Loop back for next Ib value	
510	OUTPUT 716;"NØX"	! Turn off Unit 1 output	

520 OUTPUT 717; "NØX" ! Turn off Unit 2 output 530 OUTPUT 713; "FØX" ! Turn off 230 output 540 PRINT "Press CONT to display graph" 550 PRINT "Press CONT while in graph to return to BASIC" 560 PAUSE 570 Ymin=MAXREAL Find minimum and maximum Ic value 580 Ymax=-MAXREAL 590 FOR I=1 TO 5 600 FOR J=1 TO 101 610 IF Reading(I,J,2)<Ymin THEN Ymin=Reading(I,J,2) 620 IF Reading(I,J,2)>Ymax THEN Ymax=Reading(I,J,2) 630 NEXT J 640 NEXT I 650 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 660 ! Initialize graphics GINIT PLOTTER IS CRT, "INTERNAL" ! Define plot to CRT 67Ø 680 ! Turn on graphics GRAPHICS ON 690 ! Title graph MOVE 10,90 700 LABEL "230 BIAS COMMON EMITTER CHARACTERISTICS" ! Label X axis 710 MOVE 70,10 LABEL "Vce" 720 730 MOVE 0,53 ! Label Y axis LABEL "Ic" 740 750 ! Define soft clip limits VIEWPORT 30,120,20,85 WINDOW Vstart,Vstop,Ymin,Ymax ! Scale graph 760 ! Compute Y axis increment 770 Y1=(Ymax-Ymin)/10 ! Compute X axis increment 780 X1=(Vstop-Vstart)/10 790 GRID 2*X1,2*Y1,Vstart,Ymin ! Draw grid ! Add tick marks 800 AXES X1,Y1,Vstart,Ymin 810 FOR I=1 TO 5 ! Loop for all five curves ! Loop for all 101 points per curve 820 FOR J=1 TO 101 830 PLOT Reading(I,J,1), Reading(I,J,2) ! Plot point ! Plot next point 840 NEXT J 850 PENUP 860 NEXT I ! Plot next curve | Define character size 870 CSIZE 4 880 LORG 6 ! Center characters ! Turn off soft clipping 890 CLIP OFF FOR I=Vstart TO Vstop+.01*X1 STEP X1 ! Number X axis 900 910 MOVE I, Ymin-(Y1/4) 920 LABEL USING "#,K";I 930 NEXT I 940 FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis 950 MOVE Vstart-(1.3*X1),I+(.3*Y1) 960 LABEL USING "#,MD.DE";I 970 NEXT I 980 PAUSE OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear alpha screen 990 ! Clear graphics screen 1000 GRAPHICS OFF 1010 END

SECTION 6 Using Source Measure Units with Other Instruments

6.1 INTRODUCTION

An all-Source Measure Unit test system is preferable for many applications, because of the versatility of the instruments. In some cases however, it may be desirable to replace one of the Source Measure Units with a current source, voltage source, or electrometer, either because those instruments are readily available, or because they have capabilities not available in the Source Measure Unit. In the following paragraphs three such possible applications are discussed: (1) using a Model 220 Current Source in conjunction with an Source Measure Unit to test common-emitter characteristics, (2) using a Model 617 Electrometer along with a Source Measure Unit to perform common-source tests, and (3) using a Source Measure Unit with a Model 228A Voltage/Current Source to test power transistor current gain.

6.2 USING A SOURCE MEASURE UNIT WITH A CURRENT SOURCE

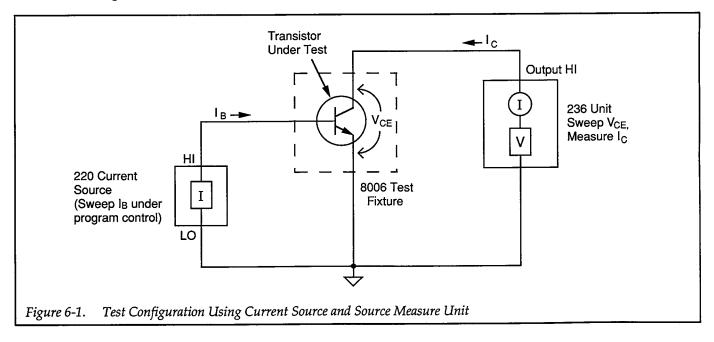
A current source can be substituted for a Source Measure Unit when testing for common-emitter characteristics, as shown in Figure 6-1. Here, a Model 220 Current Source is used to supply the base current, I_B , with the I_B sweep performed under program control, while the Source Measure Unit sweeps V_{CE} and measures I_C just as before.

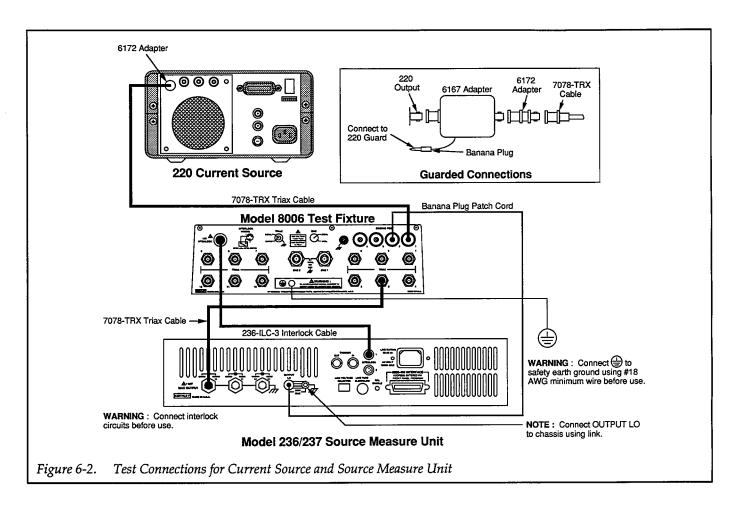
6.2.1 Test Connections

Figure 6-2 shows the test connections for the commonemitter tests using the current source and Source Measure Unit. Model 7078-TRX triax cables are used to make connections between the instruments and test fixture. Note, however, that a Model 6172 2-slot male to 3-lug female triax adapter will be necessary to connect the 3-slot triax cable to the Model 220, which is equipped with a 2-lug triax input connector.

WARNING

Connect interlock circuits before use. Connect the fixture screw to safety earth ground using #18 AWG minimum wire before use. Turn off all power before connecting or disconnecting wires or cables.





6.2.2 Measurement Considerations

As shown in Figure 6-2, the unguarded configuration for current source connections is used. For very critical measurements, use a Model 6167 Guarded Adapter. The Model 6167 connects directly to the OUTPUT jack on the Model 220 Current Source, and it includes a switch for selection of guarded and unguarded operation. See the inset of Figure 6-2 for guarded connections.

6.2.3 Program 17: Common-emitter Characteristics Using Current Source and Source Measure Unit

Program 17 below can be used to run common-emitter characteristic tests on small-signal NPN transistors using a current source and Source Measure Unit. In order to run the program, follow the steps below.

1. With the power off, connect both the Model 220 Current Source and the Model 236 Source Measure Unit to the IEEE-488 interface of the computer.

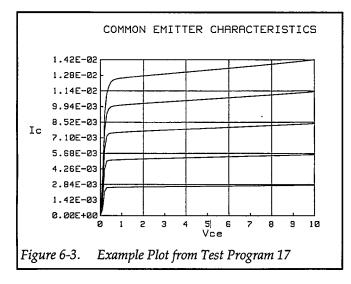
- 2. Connect the test fixture to the unit and current source using appropriate triax cables (see Figure 6-2).
- 3. Turn on both instruments, and allow them to warm up for two hours for rated accuracy. Make sure the primary address of the Model 236 is set to 16 and that the primary address of the Model 220 is set to 12.
- 4. Turn on the computer, and boot up BASIC.
- 5. Enter the lines below into the computer.
- 6. Install a small-signal NPN silicon transistor such as a 2N3904 or 2N5089 in the appropriate transistor socket of the test fixture. Be certain that the jumpers are properly installed, then close the test fixture lid.
- 7. RUN the program in the usual manner. The computer will program both instruments and run the common-emitter characteristic test on the device. The base current will be stepped under program control between 10μ A and 50μ A in 10μ A increments, and the value of V_{CE} will be swept between 0V and 10V in 0.1V increments. A fixed reading delay for the Source Measure Unit of 100msec is also incorporated into the program. A fixed delay of 100msec after each programmed I_B value is also included.
- 8. Once the sweeps have been completed, you will be prompted to press CONT to generate a plot of the

data. A simple I_C vs. V_{CE} plot will then be displayed on the computer CRT, with separate curves for each I_B value.

9. To return to BASIC from the graph, press CONT.

6.2.4 Typical Program 17 Results

Figure 6-3 shows typical results generated by example Program 17. A 2N3904 NPN transistor was used to generate these test results.



6.2.5 Program 17 Description

For the following program description, refer to the program listing below and the flowchart shown in Figure 6-4.

Initially, the reading array is dimensioned (line 40) as a three-element array that will hold five sweeps of 101 points each, with two readings for each point. Next, both instruments are returned to default conditions by a DCL command (line 50), and the Model 236, which sweeps V_{CE} and measures I_c , is programmed as follows (lines 80-210):

- Source V, sweep mode
- Local sensing
- 100mA compliance, autorange measure
- Source measure data format with no prefix, sweep data
- SRQ on sweep done
- Trigger on GET, one sweep per trigger
- Line cycle integration

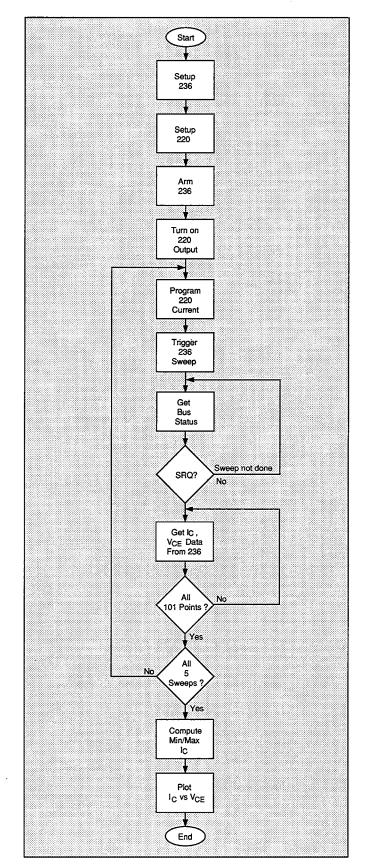


Figure 6-4. Program 17 Flowchart

- Suppress enabled
- Start V_{CE} voltage: 0V
- Stop V_{CE} voltage: 10V
- Step V_{CE} voltage: 0.1V
- Delay: 100msec
- Staircase sweep (limits determined by start, stop, and step voltage)

Following Model 236 setup, the Model 220 current source is programmed with a 10V compliance value (line 230), and the start, stop, and step current values are defined as 10μ A, 50μ A, and 10μ A respectively (lines 240-260).

Once the two instruments are ready, the Model 236 trigger is armed and the units are placed into operate (lines 290 and 300). After the array index value is declared (line 310), the main programming loop is then entered to generate the five I_B curve sweeps (line 320). At the beginning of the main loop, the base current is programmed (line 340), and, after a 100msec delay, the unit is triggered to begin its sweep (line 360). In order to synchronize the program with each sweep, the program enters a loop to wait for the unit to generate an SRQ (lines 370 and 380) when it has finished a sweep. Once each sweep has finished, the unit is serial polled to clear the SRQ line (line 390), and the data are read into the reading array (line 400). Array element (K,J,1) stores source (V_{CE}) information, and array element (K,J,2) stores measured data (I_C) information. Once all the data pertaining to the present sweep are read, the program increments the array index (line 430), and loops back to program the current source for the next sweep at the subsequent I_B value (line 440).

In order to properly scale the plot, the maximum and minimum I_C values must be determined. This operation is performed in lines 500-570 of the program. Next, the data are plotted (lines 590-930). Note that the X axis of the graph is scaled by the Vstart and Vstop parameters (line 690), while the the Y axis is scaled by the maximum and minimum I_C values.

6.2.6 Modifying Program 17

As written, the sweep limits and increments are set to fixed values. For I_B , the start, stop, and step values are $10\mu A$, $50\mu A$, and $10\mu A$ respectively, and the start, stop, and step V_{CE} values are 0V, 10V, and 0.1V respectively. Again, you can modify the program as required, or include INPUT statements to allow operator input of these parameters. For sweep lengths other than 101 points, additional modifications such as array dimension and loop counter must also be made.

10 REM COMMON EMITTER CHARACTERISTIC TEST PROGRAM REV. 1.3 (Program 17) 20 REM USING 220 CURRENT SOURCE TO SWEEP BASE CURRENT 30 OPTION BASE 1 ! First array subscript is 1 40 DIM Reading(5,101,2) ! Dimension reading array (5 swps,101 pts) 50 CLEAR 7 ! Clear Unit and current source 60 OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear screen 70 80 REMOTE 716 | Put 236 in remote 90 OUTPUT 716; "F0.1X" ! Source V, sweep mode OUTPUT 716; "OØX" 100 ! Local sensing OUTPUT 716;"L100E-3,0X" 110 | 100mA compliance,autorange measure OUTPUT 716;"65,2,1X" 120 ! Source,measure,no prefix,sweep data OUTPUT 716; "M2,X" I SRQ on sweep done 130 OUTPUT 716;"T1,0,0,0X" ! Trigger on GET,continuous 140 150 OUTPUT 716; "S2X" | Line cycle integration 155 OUTPUT 716; "B0,0,0X" | Program Ø bias value 160 OUTPUT 716; "Z1X" ! Enable suppress 170 ! Define ØV start Vce Vstart=0 180 Vstop=10 ! Define 10V stop Vce ! Define Ø.1V step Vce 190 Vstep=.1 ! 100msec Unit delay 200 Dly=100 OUTPUT 716; "Q1, "; Vstart; ", "; Vstop; ", "; Vstep; ", 0, "; Dly; "X" ! Program sweep 210 220 REM ****** 220 setup (sweeps Ib under program control) ******** OUTPUT 712; "V10X" 230 ! Program 10V compliance 240 Istart=1.0E-5 ! Define 10uA start current 250 Istop=5.0E-5 ! Define 50uA stop current 260 ! Define 10uA step current Istep=1.0E-5 270 PRINT "Close lid, press CONT to begin test" 280 PAUSE 290 OUTPUT 716; "RINIX" 1 Arm 236 trigger turn on output 300 OUTPUT 712; "F1X" ! Turn on 220 output 310 ! Define array index K = 1FOR I=Istart TO Istop STEP Istep ! Loop for all Ib curves 320 330 PRINT "Generating sweep with"; I; "current" 340 OUTPUT 712;"I";I;"X" | Program 220 current ! Wait 100msec for settling 350 WAIT .1 360 TRIGGER 716 | Trigger 236 to start sweep 370 STATUS 7,7;Stat ! Get IEEE-488 bus status 380 IF NOT BIT(Stat,10) THEN 370 ! Wait for 236 SRQ on sweep done 390 Stat=SPOLL(716) ! Serial poll 236 to clear SRQ 400 FOR J=1 TO 101 ! Loop for all 101 readings ENTER 716;Reading(K,J,1),Reading(K,J,2)! Get Vce and Ic data from 236 410 420 NEXT J ! Loop back for next reading 430 K = K + 1! Increment array index 440 NEXT I ! Loop back for next Ib value OUTPUT 716; "NØX" ! Turn off 236 output 450 ! Turn off 220 output 450 OUTPUT 712; "FØX" 470 PRINT "Press CONT to display graph" 480 PRINT "Press CONT while in graph to return to BASIC" 490 PAUSE 500 Ymin=MAXREAL ! Find minimum and maximum Ic value

510 Ymax=-MAXREAL 520 FOR I=1 TO 5 530 FOR J=1 TO 101 540 IF Reading(I,J,2)<Ymin THEN Ymin=Reading(I,J,2) 550 IF Reading(I,J,Z)>Ymax THEN Ymax=Reading(I,J,Z) 560 NEXT J 570 NEXT I 580 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 590 ! Initialize graphics GINIT 600 PLOTTER IS CRT, "INTERNAL" ! Define plot to CRT 610 GRAPHICS ON ! Turn on graphics 620 MOVE 30,95 ! Title graph 630 LABEL "COMMON EMITTER CHARACTERISTICS" 640 MOVE 70,10 ! Label X axis LABEL "Vce" 650 660 MOVE 0,53 | Label Y axis LABEL "Ic" 670 680 VIEWPORT 30,120,20,85 ! Define soft clip limits 690 WINDOW Vstart, Vstop, Ymin, Ymax ! Scale graph Y1=(Ymax-Ymin)/10 700 ! Compute Y axis increment 710 X1=(Vstop-Vstart)/10 720 GRID 2*X1,2*Y1,Vstart,Ymin | Draw grid 730 AXES X1,Y1,Vstart,Ymin ! Add some tick marks 740 FOR I=1 TO 5 ! Loop for all five curves 750 FOR J=1 TO 101 ! Loop for all 101 points per curve 760 PLOT Reading(I,J,1), Reading(I,J,2) ! Plot point 770 NEXT J | Plot next point 780 PENUP 790 NEXT I ! Plot next curve 800 CSIZE 4 ! Define character size 810 LORG 6 ! Center character 820 CLIP OFF I Turn off soft clipping FOR I=Vstart TO Vstop+.01*Vstep STEP X1 ! Number X axis 830 840 MOVE I, Ymin-(Y1/4) 850 LABEL USING "#,K";I 860 NEXT I 870 FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis 880 MOVE Vstart-(1.3*X1),I+(.3*Y1) 890 LABEL USING "#,MD.DDE";I 900 NEXT I 910 PAUSE 920 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Turn off alpha display 930 GRAPHICS OFF ! Turn off graphics display 940 END

6.3 USING AN ELECTROMETER WITH A SOURCE MEASURE UNIT

A Model 617 Electrometer/Source can be used in place of a Source Measure Unit for many tests including common-source tests on FETs. The voltage source section can be used to supply the necessary V_{DS} voltages, while the electrometer section can be used to measure the source current.

The following paragraphs discuss the overall test configuration, test connections, and also list a sample program for making such tests with these instruments.

WARNING

There are no provisions for using a safety interlock with the Model 617 Electrometer/ Source. To avoid a possible shock hazard, always leave the test fixture lid closed when hazardous voltages are present. Also connect the test fixture screw to safety earth ground using #18 AWG minimum wire before use. Turn off all power before connecting or disconnecting wires or cables.

6.3.1 Test Configuration

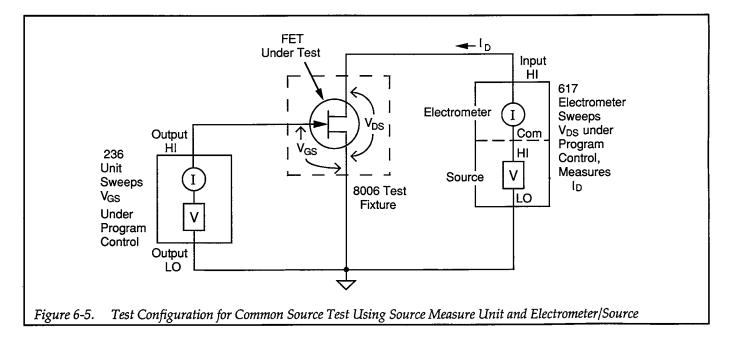
Figure 6-5 shows the test configuration for the commonsource tests using one Source Measure Unit and the electrometer/source. The unit sweeps V_{GS} , while the voltage source of the Model 617 sweeps V_{DS} , and the electrometer section measures I_D . For this programming example, a small-signal, N-channel JFET such as a 2N4392 is recommended.

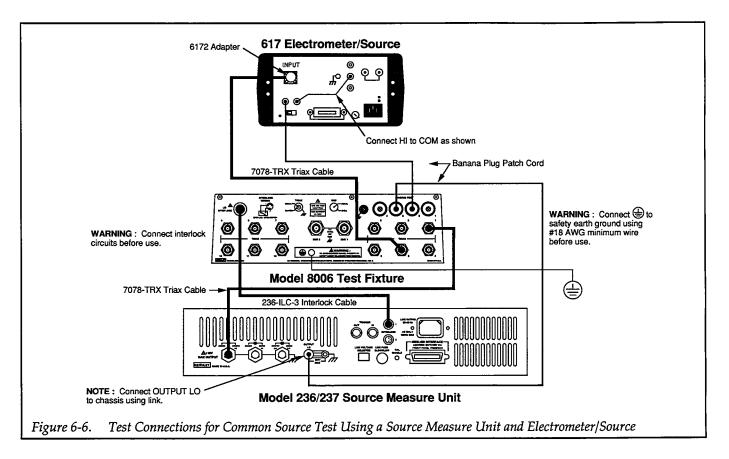
6.3.2 Test Connections

Figure 6-6 shows the test connections for the commonsource tests using the electrometer/source and Source Measure Unit. Model 7078-TRX triax cables are used to make connections between the instruments and test fixture. Again, a Model 6172 2-slot male to 3-lug female triax adapter will be necessary to connect the 3-slot triax cable to the Model 617, which is equipped with a 2-lug triax input connector. Finally, connect the voltage source LO jack to one of the binding posts on the test fixture, and connect voltage source HI to the COM jack on the rear panel of the Model 617.

6.3.3 Measurement Considerations

The maximum output current of the voltage source in the Model 617 is 2mA. Thus, tests should obviously be limited to 2mA or less. The Model 617 will not be damaged by attempting to source larger currents because it is current limited, but any test results will be affected by the current limitation. Note that there are no provisions in the test program for flagging over compliance. If an over-compliance condition occurs (as indicated on the front panel), it will be necessary to change the V_{GS} test parameters to reduce the test current.





6.3.4 Program 18: Common-source Characteristics Using Source Measure Unit and Electrometer/ Source

Program 18 below outlines general programming techniques for measuring common-source characteristics using a Source Measure Unit to sweep V_{GS} , and an electrometer/source to sweep V_{DS} and measure I_D. Follow the steps outlined below to use this program.

- 1. With the power off, connect the Model 236 and the Model 617 to the IEEE-488 bus of the computer.
- 2. Connect the unit and electrometer to the test fixture using suitable triax cables (see Figure 6-6 for details on test connections).
- 3. Turn on both instruments, and allow them to warm up for at least two hours for rated accuracy. Verify that the primary address of the Source Measure Unit is set to 16; the primary address of the Model 617 Electrometer/Source should be set to 27.
- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines from Program 18 below into the computer.

- 6. Place a small-signal N-channel JFET such as a 2N4392 in the appropriate transistor socket. Install the correct jumpers, then close the test fixture lid.
- 7. RUN the program in the usual fashion. The computer will step through V_{GS} values between -2V and -1.9V using 0.025V steps. At each step, V_{DS} will be programmed between 0V and 10V at 1V increments. At each increment, I_D will be measured. Once data are collected, a plot of I_D vs. V_{DS} for each V_{GS} value will be displayed.

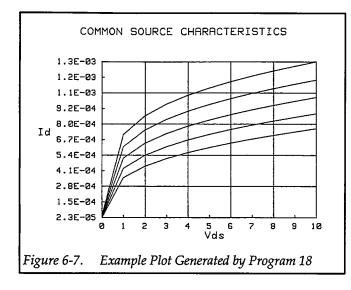
NOTE

It may be necessary to change the Vgstart, Vgstop, and Vgstep parameters in the program to keep a Model 617 over-compliance condition from occurring (>2mA).

8. To return to BASIC from the graph, press CONT.

6.3.5 Typical Program 18 Results

Figure 6-7 shows a typical plot generated by example Program 18. A 2N4392 N-channel JFET was used to generate these curves.



6.3.6 Program 18 Description

For the following description, refer to the Program 18 listing and the flowchart shown in Figure 6-8.

Initially, the array is set up for five sweeps of 11 data points each (lines 30 and 40), and both instruments are returned to default conditions (line 50). Next, the Model 236, which sweeps V_{GS} , is programmed as follows (lines 80-160):

- Source V, dc mode
- 1mA compliance, 1mA range
- Local sense
- GET trigger
- Delay: 100msec

In addition, the start, stop, and step V_{GS} voltages are defined as -2V, -1.9V, and 0.025V respectively (lines 130-150) for later programming as part of each V_{GS} program loop.

Following Model 236 setup, the Model 617, which sweeps V_{DS} and measures I_D , is configured as follows (lines 180-210):

- Amps function, 2mA range
- Zero correct on
- Data format without prefix

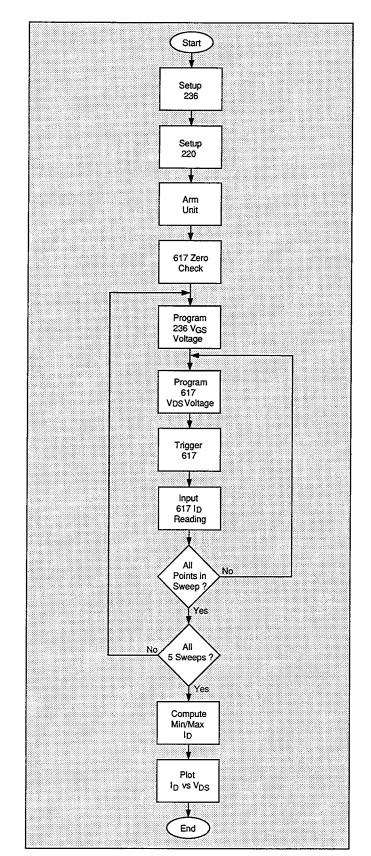


Figure 6-8. Program 18 Flowchart

Also, the start, stop, and step V_{DS} voltage values are defined as 0V, 10V, and 1V respectively (lines 220-240).

Following setup of both instruments, the operator is prompted to begin the test (lines 250 and 260), and the Model 236 is armed and placed into operate (line 270). Next, zero check on the Model 617 is turned off, and the unit is placed into operate (lines 280 and 290). The program then enters a loop to perform I_D vs. V_{DS} sweeps, one sweep for each value of V_{GS} (line 310).

At the start of each loop, the Model 236 is programmed with the present V_{GS} value (line 320), and the unit is triggered (line 340). The program then enters the second, nested loop (line 360) to sweep through all V_{DS} values. At the start of this loop, the Model 617 voltage source is programmed with the present V_{DS} value (line 370). After a two-second delay (line 380), the program then requests the current data point from the electrometer (line 390), and then takes the absolute value of the current reading. Note that V_{DS} data from the array index counter are placed into array elements (K,L,1), and measured I_D data are placed into array elements (K,L,2). After each data point has been input, the program loops back to perform the next point (line 430). Once all points in the current sweep have been completed, the program loops back to generate the next sweep (line 450). After all five sweeps

are completed, both instruments are placed into standby, and zero check on the Model 617 is enabled (lines 460 and 470).

Next, an array search is performed to determine the maximum and minimum measured values of I_D (lines 510-580). Finally, the data are plotted with I_D along the Y axis, and V_{DS} along the X axis (lines 600-940). Note that the graph is scaled according to the maximum and minimum V_{DS} values (X axis), and the maximum and minimum I_D values (Y axis).

6.3.7 Modifying Program 18

For other V_{GS} values, simply modify the Vgstart, Vgstop, and Vgstep variables as required (or use INPUT statements). For values that result in more or less than five sweeps, additional modifications to array size and corresponding loop counters must also be made.

Similarly, V_{DS} can be swept over a different range by changing the Vdstart, Vdstop, and Vdstep variables to the desired values (or, again add INPUT statements). The same general considerations regarding program modifications for array size and loop counter values also apply.

10 REM COMMON SOURCE CHARACTERISTIC TEST PROGRAM REV. 1.3 (Program 18) 20 REM USES 617 ELECTROMETER TO SOURCE DRAIN VOLTAGE, MEASURE DRAIN CURRENT 30 OPTION BASE 1 ! First array subscript is 1 40 DIM Reading(5,11,2) ! Dimension reading array (5 swps,11 pts) 50 CLEAR 7 ! Clear Unit and current source 60 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 70 80 REMOTE 716 OUTPUT 716; "FØ,ØX" | Put 236 in remote 90 ! Source V, DC mode OUTPUT 716; "L1E-3,7X" 100 ! 1mA compliance, 1mA range 110 OUTPUT 716;"OØX" ! Local sense 120 OUTPUT 716;"T1,0,0,0X" ! GET trigger 125 OUTPUT 716;"B0,0,0X" ! Program Ø bias value 130 Vostart=-2.0 ! Define -2V start Vgs voltage 140 Vastop=-1.9 ! Define -1V stop Vgs voltage 150 Vgstep=.025 | Define 0.025V step Vgs voltage 160 D1 = 100! Define 100msec Unit delay 170 REM ***** 617 setup (sweeps Vds, measures Id: 2mA maximum!) ***** 180 REMOTE 727 ! Put 617 in remote OUTPUT 727;"F1XR1ØX" 190 ! Amps, 2mA range 200 OUTPUT 727;"Z1X" ! Zero correct instrument 210 OUTPUT 727;"G1X" ! Reading without prefix 220 Vdstart=0 ! Define ØV start Vds 230 Vdstop=10 ! Define 10V stop Vds 240 Vdstep=1 | Define 1V step Vds PRINT "Close lid, press CONT to begin test" 250 260 PAUSE 270 OUTPUT 716; "RINIX" ! Arm 236 trigger,turn on output 280 OUTPUT 727;"CØX" | Turn off 617 zero check 290 OUTPUT 727; "01X" | Turn on 617 voltage source 300 K=1 310 FOR I=Vgstart TO Vgstop STEP Vgstep ! Loop for all Vgs curves OUTPUT 716; "B"; I; ",0, "; Dly; "X" ! Program 236 for Vgs voltage value 320 330 PRINT "Generating sweep with ";I;"V" 340 TRIGGER 716 | Trigger 236 Unit 350 ! Declare array index counter L=1 360 FOR J=Vdstart TO Vdstop STEP Vdstep ! Loop for all Vds values 370 OUTPUT 727;"V";J;"X" ! Program 617 voltage 380 WAIT 2 ! Wait 2 sec settling time 390 ENTER 727;Reading(K,L,2) ! Get Id data from 617 400 Reading(K,L,2)=ABS(Reading(K,L,2))! Take absolute value 410 Reading(K,L,1)=J ! Put Vds value in array 420 L=L+1 430 NEXT J ! Loop back for next reading 440 K = K + 1! Increment array index 450 NEXT I ! Loop back for next Vgs value 460 OUTPUT 727;"OØXC1X" ! Turn off 617 output, enable zero check 470 OUTPUT 716; "NØX" ! Turn off 236 output 480 PRINT "Press CONT to display graph" PRINT "Press CONT while in graph to return to BASIC" 490 500 PAUSE

510 Ymin=MAXREAL ! Find minimum and maximum Id value 520 Ymax=-MAXREAL FOR I=1 TO 5 530 540 FOR J=1 TO 11 550 IF Reading(I,J,2)<Ymin THEN Ymin=Reading(I,J,2) 560 IF Reading(I,J,2)>Ymax THEN Ymax=Reading(I,J,2) 570 NEXT J 580 NEXT I 590 OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear screen 600 GINIT | Initialize graphics 610 PLOTTER IS CRT, "INTERNAL" ! Define plot to CRT 620 GRAPHICS ON ! Turn on graphics 630 MOVE 20,95 ! Title graph 640 LABEL "COMMON SOURCE CHARACTERISTICS" 650 MOVE 70,10 | Label X axis 660 LABEL "Vds" 670 MOVE 3,53 ! Label Y axis 680 LABEL "Id" 690 VIEWPORT 30,120,20,85 ! Define soft clip limits 700 WINDOW Vdstart, Vdstop, Ymin, Ymax ! Scale graph 710 Y1=(Ymax-Ymin)/10 Compute Y axis increment 720 X1=(Vdstop-Vdstart)/10 ! Compute X axis increment 730 GRID 2*X1,2*Y1,Vdstart,Ymin ! Draw grid 740 AXES X1,Y1,Vdstart,Ymin ! Add some tick marks 750 FOR I=1 TO 5 I Loop for all five curves 760 FOR J=1 TO 11 ! Loop for all 11 points per curve 770 PLOT Reading(I,J,1),Reading(I,J,2) ! Plot point 780 NEXT J ! Plot next point 790 PENUP 800 NEXT I ! Plot next curve 810 ! Define character size CSIZE 4 820 LORG 6 ! Center characters 830 CLIP OFF ! Turn off soft clip 840 FOR I=Vdstart TO Vdstop+.01*X1 STEP X1 ! Number X axis 850 MOVE I, Ymin-(Y1/4) 860 LABEL USING "#,K";I 870 NEXT I 880 FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis 890 MOVE Vdstart-(1.3*X1),I+(.3*Y1) 900 LABEL USING "#,MD.DE";I 910 NEXT I 920 PAUSE 930 OUTPUT KBD;CHR\$(255);CHR\$(75); / Clear alpha screen 940 GRAPHICS OFF | Clear graphics screen 950 END

6.4 POWER TRANSISTOR TESTING

The power levels required for power transistor testing are often above the capabilities of a Model 236 or 237 Source Measure Unit. In such cases, a Model 228A Voltage/Current Source can be used in place of a Source Measure Unit. The Model 228A can provide a maximum of 101V at 1.01A (or 10.1V maximum at 10.1A), for a power level approximately ten times that of the Models 236 and 237.

The same general tests that are run on small-signal transistors can also be run on power transistors. Typical examples include current gain tests and common-emitter characteristics. In this paragraph, we will demonstrate current gain tests on power transistors.

6.4.1 Test Configuration

Figure 6-9 shows the general configuration for current gain tests of high-power transistors. The Model 236 Source Measure Unit sources the base current, and the Model 228A Voltage/Current Source supplies V_{CE} , and it also measures I_C . The current gain, β , is computed from the I_C and I_B values.

6.4.2 Test Connections

Figure 6-10 shows the test connections for the power transistor current gain tests using the Source Measure Unit and voltage/current source. Model 7078-TRX triax

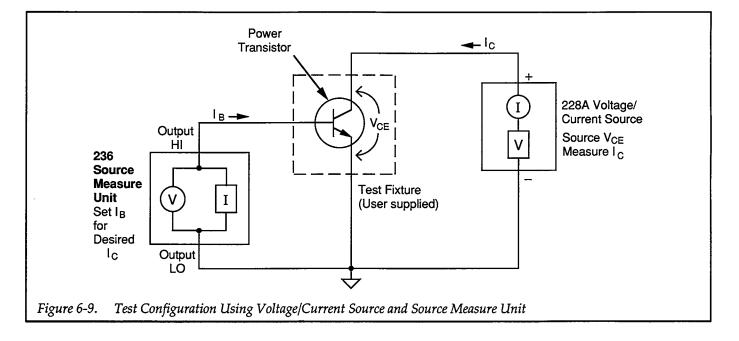
cables are used to make connections between the unit and user-supplied fixture (assuming that the test fixture is equipped with triax connectors). Model 228A connections can be made by wiring the quick disconnect connector directly to the user supplied test fixture; binding posts or screw terminals should be adequate for this application. Be sure to use wiring appropriate for the current and voltage levels involved (101V insulation, 1.01A currentcarrying capability).

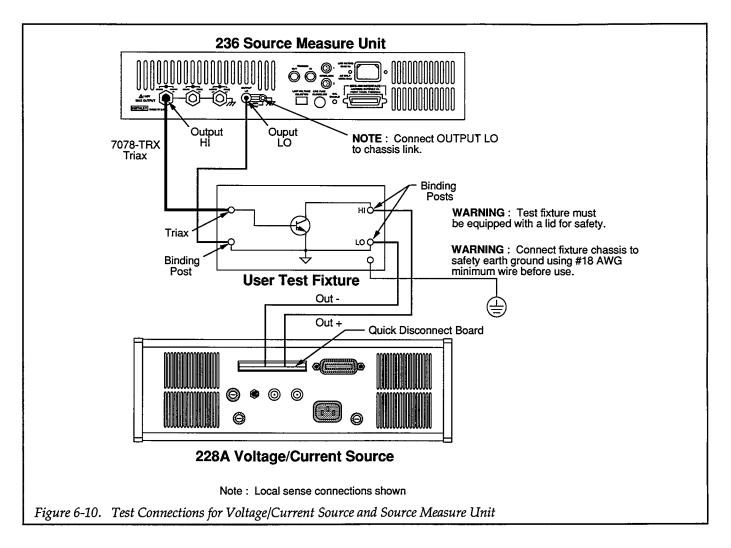
WARNING

Hazardous voltages may be present at the test fixture. Since the Model 228A does not have provisions for using an interlock circuit, be especially careful when using this test configuration. Always be certain to close the test fixture lid before applying power to the circuit under test. Connect fixture chassis to safety earth ground using #18AWG minimum wire before use. Turn off all power before connecting or disconnecting wires or cables.

NOTE

The leads on many power transistors are too large for the transistor sockets on the Model 8006 test fixture. For that reason, and because of the power levels involved, the use of a Model 8006 Test Fixture for power transistor testing is not recommended.





6.4.3 Measurement Considerations

This test configuration is intended for testing power transistors. Because of the higher offset currents that may be present, this setup should not be used for making critical, low-current measurements. Use the test configuration discussed in Section 3 for current-gain tests using lower current values.

6.4.4 Program 19: Power Transistor Current Gain

Program 19 below can be used to test current gain of power transistors using a Model 236 Source Measure Unit and a Model 228A Voltage/Current Source. As outlined previously, the maximum power level that can be supplied by the Model 228A is approximately 100W.

In order to run the program, follow the steps below.

- 1. With the power off, connect both the Model 228A Voltage/Current Source and the Model 236 Source Measure Unit to the IEEE-488 interface of the computer.
- 2. Connect the test fixture to the Source Measure Unit and voltage/current source using appropriate cables and wires (see Figure 6-10).
- 3. Turn on both instruments, and allow the units to warm up for rated accuracy. The Model 236 requires two hours warm-up, and the Model 228A requires 10 minutes warm-up. Make sure the primary address of the Model 236 is set to 16 and that the primary address of the Model 228A is set to 11.
- 4. Turn on the computer, and boot up BASIC.
- 5. Enter the lines below into the computer.
- 6. Install an NPN power transistor such as an MJE240 in the appropriate transistor socket of the test fixture, then close the test fixture lid.
- 7. RUN the program in the usual manner. The computer will prompt you to type in the the minimum and maximum I_B search values, the target value for I_C , and the V_{CE} value for the test. Keep in mind the ap-

proximate current gain as well as the 100mA Source Measure Unit current limitation when entering the base current value.

8. Once the instruments are programmed, the program will search for the optimum I_B value to perform the test at an I_C value to within 5% of the target, and display the current gain of the device. If the number of iterations has been exceeded, or if the Model 228A is found to be over compliance, a message will be displayed. If the number of iterations are exceeded, try running the program again with a closer range of I_B values.

6.4.5 Typical Program 19 Results

A typical power transistor current gain is lower than for small-signal devices. For the recommended transistor used in this test, a typical current gain would be about 25, but that will vary somewhat depending on the test parameters.

6.4.6 Program 19 Description

For the following program description, refer to the program listing below and the flowchart shown in Figure 6-11.

Initially, the reading array is dimensioned (line 30), and the iteration variables are defined (lines 40 and 50). Both instruments are returned to default conditions by a DCL command (line 60), and the Model 236, which sources I_{B} , is programmed as follows (lines 90-130):

- Source I, dc mode
- Local sensing
- 1V compliance, 1.1V range
- Source data format with no prefix, dc data
- Trigger on GET

The minimum and maximum I_B values, and the target I_C values are then entered (lines 140-170), and the Model 228A voltage current source, which sources V_{CE} and measures I_C , is programmed for the volts/amps data format with prefix (line 200), 1A current compliance (line 210), and the unit is programmed to output the V_{CE} voltage value (line 230).

Next, the programmed voltage is checked for a hazardous level, and an appropriate warning is displayed if the

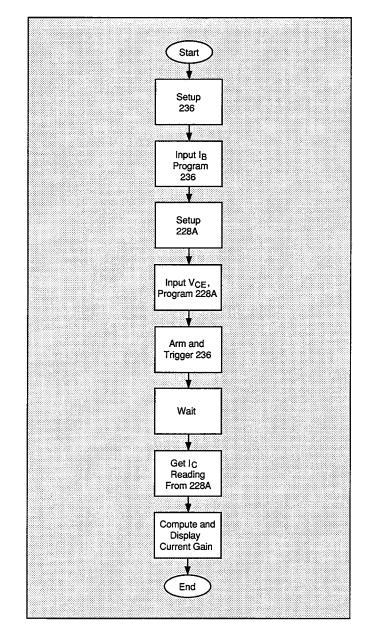


Figure 6-11. Program 19 Flowchart

voltage will exceed 30V (lines 240-270). The user is then prompted to close the test fixture lid and begin the test (lines 280 and 290).

Once the two instruments are programmed, the Source Measure Unit trigger is armed and the units are placed into operate (lines 300 and 310). The Source Measure Unit is triggered (line 330), and, the iteration counter is incremented and checked to see if the maximum number of iterations has been exceeded. If so, a message is displayed, and the program halts. The Model 236 is then programmed with the present value of I_B (line 410), and, after the programmed delay period (line 420), the reading string is obtained from the instrument (line 430), and the string is then checked to see if an over-compliance condition has occurred (lines 440-490). If an over-compliance condition is found, a message to that effect is displayed, the instruments are cleared, and the program halts.

The string is then converted to a numeric (line 500), and the I_C value is checked against the target (lines 510-600). If the I_C value is not within $\pm 5\%$ of the target, the program calculates a new I_B value and then loops back to run the test again. Once the target is reached, the Models 228A and 236 are placed into standby (lines 610 and 620, and the current gain is calculated and displayed (line 630).

6.4.7 Modifying Program 19

The current limit of the Model 228A is set to 1A by the program. This current value will allow you to use voltages up to 101V. If larger currents (up to 10.1A) are required, modify line 210 of the program accordingly. Note however, that for currents above 1.01A, the output voltage of the Model 228A is limited to 10.01V.

The tolerance for the I_C target search is set to $\pm 5\%$, but this value can be changed to a tighter value, if desired. Note, however, that it will probably be necessary to increase the number of iterations if the target range is decreased.

REM POWER TRANSISTOR CURRENT GAIN TEST PROGRAM REV. 1.3 (Program 19) 10 20 REM USES 236 SOURCE MEASURE UNIT AND 228A VOLTAGE/CURRENT SOURCE ! Dimension reading string 30 DIM Reading\$[100] ! Define number of iterations 40 Iterations=20 50 N=0 ! Iteration counter 60 CLEAR 7 ! Clear 236 and 228A source 70 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 80 90 REMOTE 716 ! Put 236 in remote OUTPUT 716; "F1,0X" ! Source I, DC mode 100 OUTPUT 716; "L1,1X" 110 1 1V compliance, 1.1V range 120 OUTPUT 716;"00X" ! Local sense OUTPUT 716; "T1,0,0,0X" ! GET trigger, continuous 130 135 OUTPUT 716; "B0,0,0X" | Program Ø bias value INPUT "Enter maximum base current", Ib1 ! Input maximum Ib value 140 INPUT "Enter minimum base current", Ib2 ! Input minimum Ib value 150 160 Ib=(Ib1-Ib2)/2+Ib2 ! Compute start Ib value 170 INPUT "Enter target Ic", Itarget! Input target Ic value 180 REMOTE 711 ! Put 228A in remote 190 OUTPUT 711; "G4X" ! Select volts, amps data format 200 OUTPUT 711; "I1X" 210 ! 1A compliance 220 INPUT "Enter Vce",Vce | Input Vce OUTPUT 711;"V";Vce;"X" ! Program 228A voltage value IF ABS(Vce)>30 THEN ! Check for dangerous voltage 230 240 PRINT "Hazardous voltage will be applied to device during test" 250 260 BEEP 270 END IF 280 PRINT "Close test fixture lid, press 'CONT" 290 PAUSE 300 OUTPUT 716; "RIN1X" ! Arm 236 trigger, turn on output 310 OUTPUT 711; "F1X" ! Turn on 228A output 320 PRINT "Measuring..." 330 | Trigger 236 TRIGGER 716 ! Increment iteration counter 340 N=N+1! Check for maximum iterations 350 IF N>Iterations THEN 360 CLEAR 7 370 BEEP 380 PRINT "Iterations exceeded"; Iterations 390 STOP 400 END IF 410 OUTPUT 716; "B"; Ib; ",0,0X" | Program 236 current value ! Wait one second settling time 420 WAIT 1 ENTER 711;Reading\$ 430 | Get reading from 228A IF Reading\$[1,1]="0" THEN ! Check for over compliance 440 450 CLEAR 7 460 BEEP 470 PRINT "228A is over compliance" 480 STOP 490 END IF 500

```
510
     IF Ic>1.05*Itarget THEN | Check for Ic > target
520
    Ib1=Ib
    Ib=Ib-(1b-Ib2)/10
530
540
     GOTO 340
     END IF
550
560
     IF Ic<.95*Itarget THEN | Check for Ic < target
570
    ІЬ2=ІЬ
580
     Ib=Ib+(Ib1-Ib)/10
590
     GOTO 340
     END IF
600
     OUTPUT 716;"NØX"
OUTPUT 711;"FØX"
610
                                 ! Turn off 236 output
                                 ! Turn off 228A output
620
     PRINT "Current gain=";Ic/Ib ! Display current gain
630
640
     END
```

SECTION 7 Adding Switching Capabilities to a Source Measure Unit Test System

7.1 INTRODUCTION

Adding switching equipment to a Source Measure Unit test system can greatly enhance the capabilities of such a system. Two examples of how switching can increase versatility are (1) using a scanner to switch multiple DUTs, and (2) using a matrix card to allow switching flexibility to any node in the system. Each of these general switching configurations is discussed in the following paragraphs.

For the sake of brevity, many aspects of using a switching system have not been included here. For more detailed information on switching, request the <u>Switching Handbook</u>, which is available from Keithley Instruments, Inc. Contact your Keithley representative or the factory for more information.

7.2 SCANNER SWITCHING OF MULTIPLE DUTS

The following paragraphs discuss methods for switching multiple DUTs to a single set of Source Measure Units in a test system using a scanner. For this application, we will assume that dc current gain tests on 10 transistors in a given test fixture are to be performed.

7.2.1 System Configuration

Figure 7-1 shows the overall system configuration for the scanner/Source Measure Unit switching system. In addition to the Source Measure Units, which perform the stimulus and measurement, the system includes a Model 705 Scanner with two Model 7058 Low Current Scanner Cards to add the switching functions. For this application with the equipment shown, a total of 10 DUTs can be tested on an automated basis.

The test fixture could be custom-built, or several Model 8006 test fixtures could be used.

7.2.2 Test Configuration

Figure 7-2 shows the test configuration for this application. The equipment configuration is similar to that used for the current gain tests discussed earlier in this section except for addition of switching circuits. Note that singlepole switching on the base and collector circuits is used in order to minimize switching complexity. Keep in mind this configuration precludes the use of remote sensing; if remote sensing is required, two additional poles of switching for each DUT will be necessary.

7.2.3 Equipment Connections

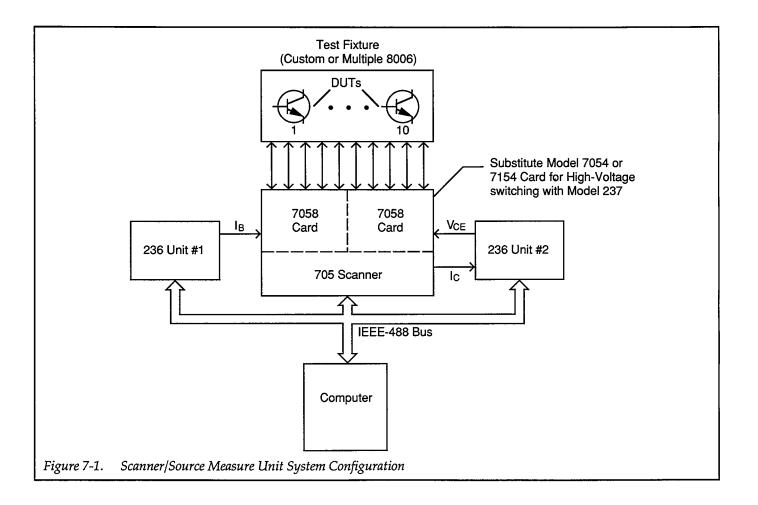
Figure 7-3 shows the equipment connections for the multiple-device current gain tests. For the sake of simplicity, only one set of connections for a single device located in a Model 8006 test fixture are shown. In order to test multiple devices, additional test fixtures are required, or you could use your own custom-built design to house all ten devices in a single fixture. Note that Model 6172 2-slot male to 3-lug female adapters will be necessary to connect the 3-slot triax cables to the scanner card jacks, which are equipped with 2-lug female triax connectors.

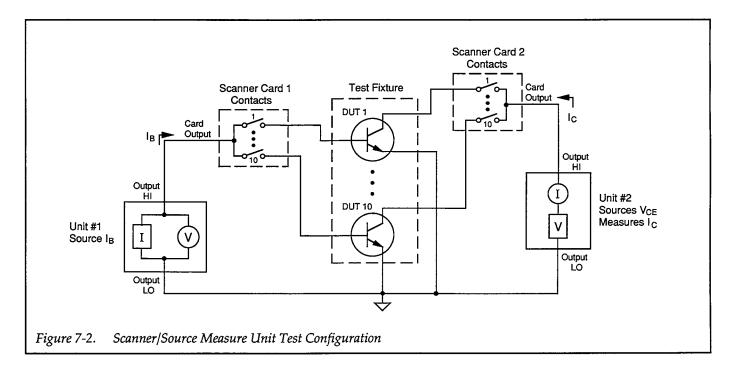
WARNING

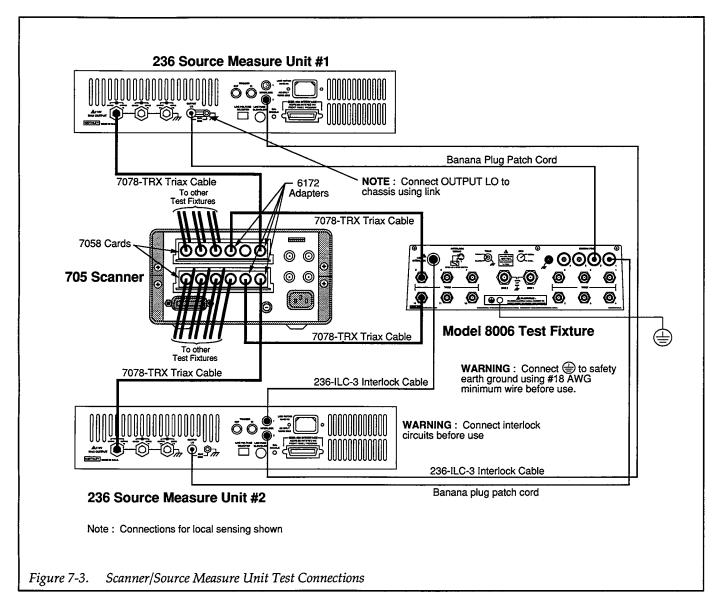
Connect interlock circuits before use. Connect fixture to safety earth ground using #18 AWG minimum wire before use. If a custom fixture is used, it must be totally enclosed for safety, and the fixture chassis must be connected to safety earth ground using #18 AWG minimum wire before use. Turn off all power before connecting or disconnecting wires or cables

7.2.4 Measurement Considerations

Adding switching to any test system brings the added consideration of how such switching will affect the measurements. For low currents, the offset current of the card can become a consideration because such offsets can af-







fect measurement accuracy. The Model 7058 card used for this application has a specified offset current of 1pA which should not be a factor in most cases; however, for currents below 1nA, the offset current could affect the accuracy of your measurements. Note that guard is carried through on the inner shield to minimize these effects.

Similarly, the effects of switching can result in errors if sufficient time is not allowed for the circuit to settle before measurements. While such effects are particularly pronounced for high-impedance circuits, they can also be seen in lower-impedance circuits, although usually to a lesser degree. To allow the circuit to settle to less than 1% of final value, the settling time should be at least 5RC, where R and C are the effective circuit resistance and capacitance respectively. Allow a settling time of 7RC for settling to within 0.1% of final value.

The path isolation of the card can also come into play when testing high-impedance circuits. The path isolation resistance effectively forms a voltage divider with the resistance of the DUT. In general, path isolation resistance should be at least 100 to 1000 times the source resistance so as to have minimal effect on the measurements.

Be sure to remove the channel jumpers to avoid shorting the source. Also, for high-voltage switching with a Model 237, substitute a Model 7054 or 7154 High-voltage Scanner Card.

7.2.5 Program 20: Dc Current Gain of Multiple DUTs

Use Program 20 below to perform dc current gain tests on 10 bipolar transistors. Proceed as follows:

- 1. With the power off, connect both Model 236 Source Measure Units and the Model 705 Scanner to the IEEE-488 bus of the computer.
- 2. Connect the test fixture(s) and both Source Measure Units to the two scanner cards using appropriate triax cables (see Figure 7-3 for details on test connections). With the scanner power still off, install both Model 7058 Scanner Cards in the scanner after making test connections.
- 3. Turn on both Source Measure Units, and allow them to warm up for at least two hours for rated accuracy. Be sure that the primary address of Unit #1 is set to 16, and that the primary address of Unit #2 is set to 17. Also turn on the Model 705 Scanner, and verify that its primary address is set to 18.
- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines below into the computer
- 6. Install 10 small-signal silicon transistors to be tested in the desired test fixture sockets (transistors should have characteristics similar to a 2N3904 or 2N5089). Install the required jumpers for all devices, then close the test fixture lid.
- 7. RUN the program, and follow the prompts on the screen. You will be prompted to enter 10 base current values (one for each of the 10 devices) and then the desired value of V_{CE}. When entering the base currents, keep the approximate current gains of the devices in mind so as not to saturate them. Note that no iterative search algorithm is included in this example program for the sake of simplicity.
- 8. Once the parameters are entered, the instruments will be programmed accordingly, and the collector current of each device will be measured. The dc current gain of each device will then be displayed on the computer CRT after all transistors are tested.

7.2.6 Typical Program 20 Results

A typical current gain for a 2N5089 would be about 500. Note however, that the current gain of the device could be as low as 300 or as high as 900.

7.2.7 Program 20 Description

For the following description, refer to the flowchart shown in Figure 7-4 and the Program 20 listing shown below.

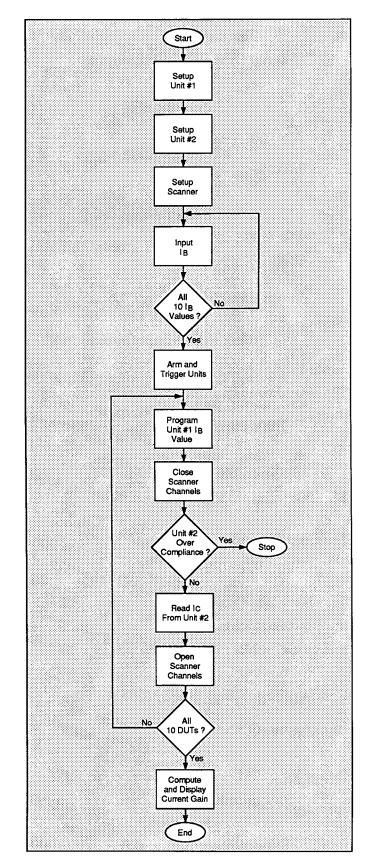


Figure 7-4. Program 20 Flowchart

After both units and the scanner are returned to default conditions (line 20), two storage arrays for I_B and I_C values are defined (line 40). Next, Unit #1, which sources I_B , is set up as follows (lines 60-100):

- Source I, dc mode
- 1V compliance, 1.1V range
- Local sense
- GET trigger, continuous

Following Unit #1 setup, Unit #2, which sources V_{CE} and measures I_c, is configured as follows (lines 130-210):

- Source V, dc mode
- Local sense
- 10mA compliance, autorange measure
- Source only data format, no prefix, dc data output
- Trigger on GET, continuous
- Line cycle integration
- Dc voltage, value determined by user-input VCE value

Next, the scanner is placed in the one-pole mode (line 230), and a program loop allows the operator to input all 10 I_B values for the test (lines 240-270). Once the operator signals to continue the program (lines 280 and 290), both Source Measure Unit triggers are armed and the units are placed into operate (lines 300 and 310). Next, the units are triggered (lines 330 and 340), and the program enters the main loop to test all 10 devices (line 350).

At the start of the loop, Unit #1 is programmed with the I_B current value, and the the scanner channels for the present device are closed (lines 370 and 380). After a one-second delay, the status byte is then obtained from Unit #2 (line 400), and bit 7 in the status byte is then checked (lines 410-440) to see if it is set. If so, Unit #2 is over compliance, the operator is then notified, and the program is halted.

Assuming no error, the value of I_C for the current device is requested and placed into the I_C array (line 460), and the scanner channels are then opened (lines 470 and 480). The program then loops back to test the next device (line 490).

After all 10 devices are tested, both Source Measure Units are placed into standby (lines 500 and 510), and the dc current gain for each of the 10 devices is calculated and displayed (lines 520-540).

7.2.8 Modifying Program 20

As written, the program assumes that 10 devices are to be tested, each with a different I_B current value. For a different number of devices, simply modify the loop counter values as required. To test all devices with the same value of I_B , change the program to input only one I_B value, and program Unit #1 with that value alone.

10 REM DC CURRENT GAIN WITH SCANNING TEST PROGRAM REV. 1.3 (Program 20) 20 CLEAR 7 ! Clear both Units and scanner OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear screen 30 40 DIM Ib(10), Ic(10) | Dimension Ib and Ic storage arrays 50 60 | Put Unit 1 in remote REMOTE 716 OUTPUT 716; "F1,0X" 70 ! Source I, DC mode 80 OUTPUT 716; "L1,1X" ! IV compliance, 1.1V range 90 OUTPUT 716; "OØX" ! Local sense 100 OUTPUT 716; "T1,0,0,0X" | GET trigger, continuous 110 D1v=100 | Define 100msec Unit delay 120 130 REMOTE 717 ! Put Unit 2 in remote OUTPUT 717; "F0.0X" 140 1 Source V, DC mode 150 OUTPUT 717; "OØM128,ØX" I Local sensing, SRQ OUTPUT 717; "L10E-3,0X" 160 1 10mA compliance, autorange measure 170 OUTPUT 717; "G4,2,0X" ! Measure, no prefix, DC data 180 OUTPUT 717; "T1,0,0,0X" ! Trigger on GET, continuous OUTPUT 717; "S2ZØX" 190 ! Line cycle integration, suppress off 200 INPUT "Enter Vce",Vce ! Input Vce 210 OUTPUT 717; "B"; Vce; ",0, "; Dly; "X" ! Program DC, autorange, delay 220 REMOTE 718 | Put 705 scanner in remote 230 OUTPUT 718; "A1X" ! Select 1-pole mode 240 FOR I=1 TO 10 ! Loop for all 10 Ib values 250 DISP "Enter device"; I; "current"; ! Prompt for Ib value 260 INPUT Ib(I) ! Input Ib value 270 NEXT I ! Loop back for next Ib value 280 PRINT "Close lid(s), press CONT to begin test" 290 PAUSE 300 OUTPUT 716; "RINIX" ! Arm Unit 1 trigger, turn on output 310 OUTPUT 717; "RINIX" ! Arm Unit 2 trigger, turn on output 320 PRINT "Measuring..." 330 TRIGGER 716 1 Trigger Unit 1 TRIGGER 717 340 1 Trigger Unit 2 350 FOR I=1 TO 10 ! Loop to test all 10 devices 360 OUTPUT 716; "B"; Ib(I); ",0,"; Dly; "X" ! Program Unit 1 with Ib value 370 OUTPUT 718; "C"; I; "X" ! Close scanner channel I 380 OUTPUT 718; "C"; I+10; "X" ! Close scanner channel I+10 390 WAIT D1y/1000+1 ! Wait for settling 400 Stat=SPOLL(717) ! Serial poll Unit 2 410 IF BIT(Stat,7) THEN ! Check for over compliance 420 BEEP 430 PRINT "Unit is over current compliance on device #";I 440 STOP 450 END IF 460 ENTER 717; Ic(I) 1 Get Ic reading from Unit 2 470 OUTPUT 718; "N"; I; "X" 1 Open scanner channel I 480 OUTPUT 718; "N"; I+10; "X" ! Open scanner channel I+10 490 NEXT I I Loop back to test next device

```
500
      OUTPUT 716; "NØX"
                                       ! Turn off Unit 1 output
510
      OUTPUT 717; "NØX"
                                       ! Turn off Unit 2 output
520
      FOR I=1 TO 10
                                       ! Loop for all 10 current gains
530
      PRINT "Device #";I;"current gain=";Ic(I)/Ib(I) ! Display current gain
540
      NEXT I
                                       ! Loop back and display next gain
550
      END
```

7.3 RESISTIVITY TESTING USING MATRIX SWITCHING IN A SOURCE MEASURE UNIT TEST SYSTEM

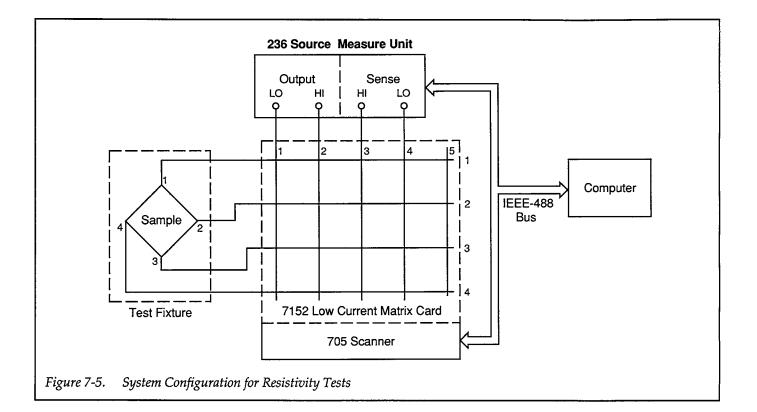
One example that demonstrates matrix switching benefits is resistivity tests on semiconductors. The following paragraphs discuss such resistivity tests using a Source Measure Unit/matrix switching system.

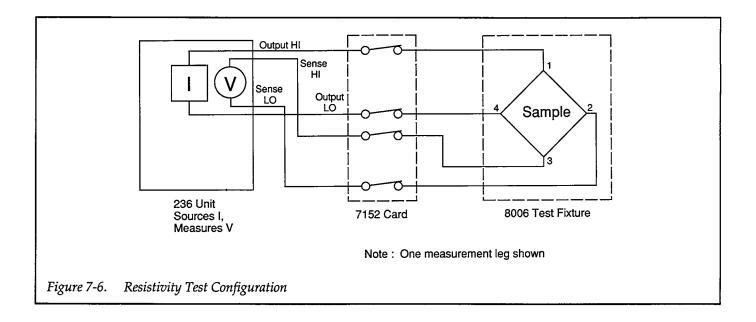
7.3.1 System Configuration

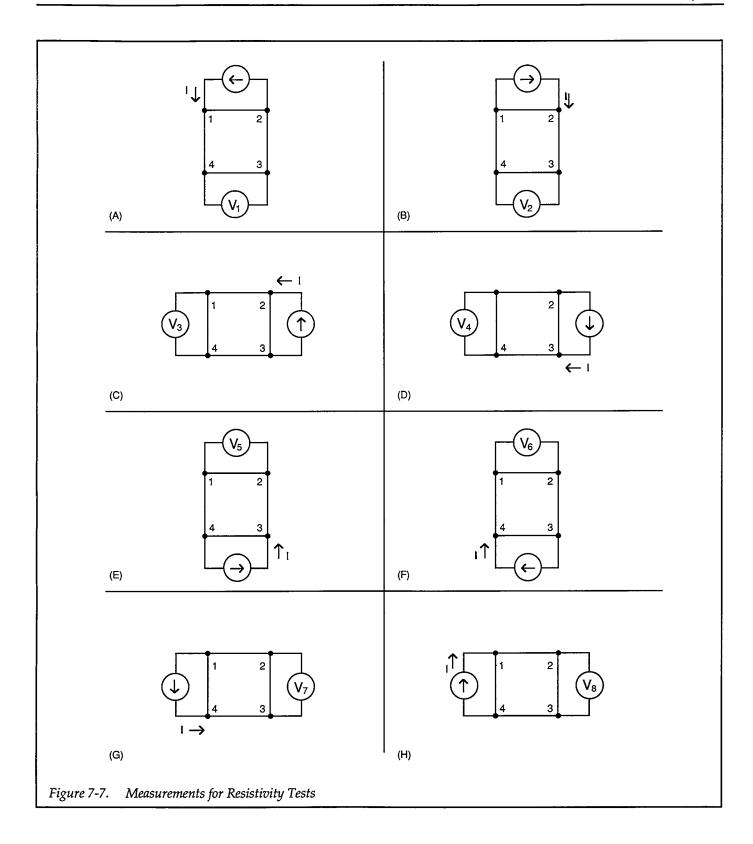
Figure 7-5 shows a typical system configuration for performing resistivity tests using a Source Measure Unit. In addition to the Source Measure Unit, the system includes a Model 705 Scanner, Model 7152 Low Current Matrix Card, and a Model 8006 test fixture to house the device under test. With the test configuration shown in Figure 7-5, only one 4-terminal sample can be tested at any given time. However, additional Model 7152 cards can expand columns or rows, allowing more than one sample to be tested by a single test procedure.

7.3.2 Test Configuration

Figure 7-6 shows a typical resistivity test configuration for a single leg measurement of one sample. Here, the current source of the Source Measure Unit sources a current between two terminals of the sample, while the voltmeter section of the unit measures the voltage across two of the opposite terminals. Generally, eight such measurements are made, as shown in Figure 7-7.







7.3.3 Resistivity Calculations

Resistivity is calculated from the voltage measurements as follows:

$$\sigma_{A} = \frac{1.1331 f_{A} t_{S} (V_{2} + V_{4} - V_{1} - V_{3})}{I}$$

$$\sigma_{\rm B} = \frac{1.1331 \, {\rm f}_{\rm B} {\rm t}_{\rm S} ({\rm V}_6 + {\rm V}_8 - {\rm V}_5 - {\rm V}_7)}{{\rm I}}$$

Where: σA and σB are the resistivities in Ω -cm t_s is the sample thickness in cm V₁ through V₈ are the voltages measured by the Model 236 I is the current sourced by the Model 236 in amperes f_A and f_B are geometrical factors based on sample symmetry (f_A = f_B = 1 for perfect symmetry)

Once σA and σB are known, the average resistivity, σAVG , can be computed as follows:

$$\sigma_{AVG} = \frac{\sigma_A + \sigma_B}{2}$$

7.3.4 Test Connections

Figure 7-8 shows the test connections for the resistivity tests. The Model 8006 test fixture should be connected directly to the ROW IN or ROW OUT jacks on the Model 7152 Low Current Matrix Card using an optional Model 7152-TRX-10 cable assembly. Connect the Model 236 to the COL IN or COL OUT jacks of the matrix card, again using a Model 7152-TRX-10 cable assembly. For the OUT-PUT HI, SENSE HI, and SENSE LO jacks, you can simply connect the triax cables to the corresponding jacks. For the OUTPUT LO connection, however, it will be necessary to use BNC/banana (Pomona Model 1899) and 3-lug female triax to male BNC (Pomona Model 5299) adapters.

WARNING

When a Model 236/237 is programmed for remote sensing, hazardous voltage may be present on the SENSE and OUTPUT terminals when the unit is in operate regardless of the programmed voltage or current. To avoid a possible shock hazard, always turn off all power before connecting or disconnecting cables to the Source Measure Unit or the associated test fixture. Connect interlock circuits before use. Connect fixture screw to safety earth ground using #18 AWG minimum wire before use.

7.3.5 Measurement Considerations

The same general considerations discussed in paragraph 7.2 for the scanner card also apply to matrix card measurements. The offset current (<1pA for the Model 7152) comes into play for very low current measurements. The required settling time depends on the impedance levels involved (should be >5RC), and the path isolation can affect the accuracy of high-impedance measurements.

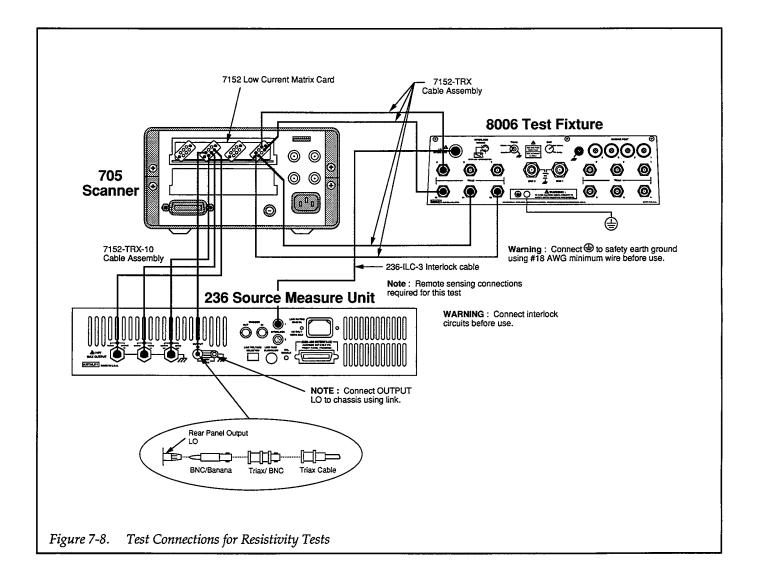
NOTE

In this application, the sense and source leads are connected to separate points on the DUT, which will result in a potential between OUT-PUT HI and SENSE HI, and OUTPUT LO and SENSE LO. Note that the maximum voltage between the OUTPUT and SENSE leads is limited (see specifications). Reduce test current if necessary to keep the voltages below specified limits.

7.3.6 Program 21: Resistivity Tests Using a Switching Matrix and Source Measure Unit

Program 21 demonstrates programming techniques for controlling a switching matrix and Source Measure Unit to perform resistivity tests. The basic procedure for using this program is as follows:

- 1. With the power off, connect the Model 236 Source Measure Unit and the Model 705 Scanner to the IEEE-488 bus of the computer. Also, install the Model 7152 Card in slot 1 of the Model 707 mainframe.
- 2. Connect the test fixture and the Source Measure Unit to the matrix card using the specified triax cables (see Figure 7-8 and the discussion above for details on test connections).
- 3. Turn on the Model 236, and allow it to warm up for at least two hours for rated accuracy. Be sure that the primary address of the Source Measure Unit is set to 16. Also, turn on the Model 705, and make certain that its primary address is set to 17.



- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines below into the computer
- 6. Connect the sample to be tested to the appropriate socket terminals on the test fixture, and also install the necessary test fixture jumpers. Use the general configuration shown in Figure 7-6 as a guide to test connections. Close the test fixture lid after making connections.
- 7. RUN the program, and follow the prompts on the screen. You will be prompted to enter the desired sample current value and then the sample thickness, which should be entered in centimeters. When enter-

ing the current, keep the approximate DUT resistance values in mind so as not to create an over voltage compliance condition. Also, you must not exceed the maximum voltage between output and sense leads of the Source Measure Unit.

- 8. Once the parameters are entered, the test will begin. The program will program the Source Measure Unit, and then begin the tests by closing crosspoints. A total of eight measurements will be taken and stored in an array.
- 9. Once the testing has been completed, the resistivity values will be calculated and displayed.

7.3.7 Program 21 Description

Refer to the Program 21 listing below and the flowchart shown in Figure 7-9 for the following description.

At the start of the program, both the Source Measure Unit and the scanner are returned to default conditions (line 20), and the reading array and command string are dimensioned (line 40). Next, the Model 236, which sources the test current and measures the sample voltage, is programmed as follows (lines 60-120):

- Source I, dc mode
- 10V compliance, autorange measure
- Remote sensing
- Measure only data format with no prefix, dc data output
- Continuous trigger on GET
- Line cycle integration

The Model 705 is then placed in remote (line 140), and the scanner is placed into matrix mode (line 150). Next, the operator is prompted to input the desired test current, at which point the Source Measure Unit is programmed with the current value (lines 160 and 170). The operator is then prompted for the sample thickness (line 180), and the program waits for the operator's signal to begin (lines 190 and 200).

Once the operator starts the test, the Model 236 is armed (line 210), and the unit is then triggered (line 220). The program then enters a loop (line 230) to test the sample with a total of eight readings. As part of each loop, the Model 705 command string is read from the DATA statements at the end of the program (line 240), the unit is then programmed to close the desired crosspoints (line 250), and the Model 236 is placed in operate. After a two-second delay for settling (line 270), a voltage reading is requested from the Model 236 and placed into an array (line 280). The Model 236 is placed in standby, and the crosspoints are then opened by reading the next command string (line 300) and then programming the Model 705 accordingly (line 310). The program then loops back for the next measurement (line 320).

Finally, the program computes both σ_A and σ_B (lines 340 and 350), and it then calculates and displays the average resistivity, σ_{AVG} (line 370). Note that the Model 705 com-

mand strings are located in DATA statements at the end of the program (lines 400-550)

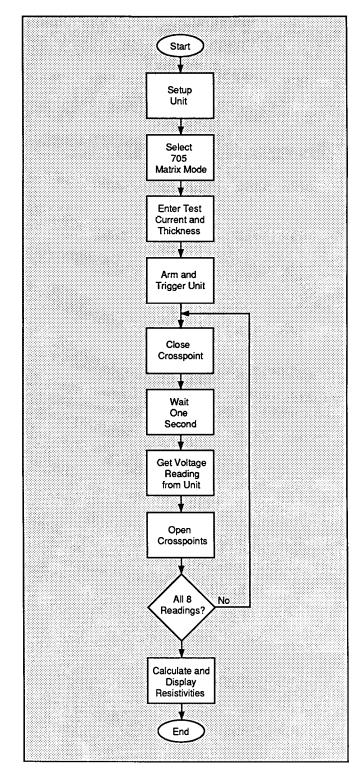


Figure 7-9. Program 21 Flowchart

CAUTION

When the Model 236/237 is in remote sensing, the output voltage will float up to maximum if the sense leads are open and the unit is in operate. To avoid possible switch card damage, always close the appropriate relays before placing the Model 236/237 in operate, and place the unit in standby before opening relays..

REM RESISTIVITY TEST PROGRAM REV 1.3 (Program 21) 10 | Clear Unit and scanner 20 CLEAR 7 OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear screen 30 40 DIM V(8),Cmd\$[25] ! Dimension reading array, command string 50 60 REMOTE 716 ! Put 236 in remote OUTPUT 716; "F1.0X" ! Source I, DC mode 70 OUTPUT 716; "L10,0X" 1 10V compliance, autorange measure 80 OUTPUT 716; "01X" 90 ! Remote sense OUTPUT 716;"G4,2,0X" ! Measure data, no prefix, DC data 100 OUTPUT 716; "T1,0,0,0X" ! Continuous trigger on GET 110 120 OUTPUT 716; "S2ZØX" ! Line cycle integration, suppress off 130 140 REMOTE 717 ! Put 705 in remote 150 OUTPUT 717; "A0X" ! Select matrix mode INPUT "Enter test current", Itest ! Input desired test current 160 OUTPUT 716;"B";Itest;",0,1000X" 170 | Program 236 test current INPUT "Enter sample thickness (cm)", Ts ! Input sample thickness 180 PRINT "Close lid, press CONT to begin" 190 200 PAUSE 210 OUTPUT 716; "R1X" ! Arm 236, 220 TRIGGER 716 | Trigger 236 FOR I=1 TO 8 ! Loop for all eight measurements 230 ! Read 705 command string 240 READ Cmd\$! Close crosspoints 250 OUTPUT 717;Cmd\$ | Put 236 in operate 260 OUTPUT 716; "NIX" 270 ! Wait two seconds for settling WAIT 2 I Get voltage reading from 236 280 ENTER 716;V(I) OUTPUT 716;"N000X" ! Put 236 in standby,local sense 290 | Read 705 command string 300 READ Cmd\$! Open crosspoints 310 OUTPUT 717;Cmd\$ 320 NEXT I ! Loop back for next reading OUTPUT 716; "NØX" 330 ! Put 236 in standby Pa=(1.1331*Ts*(V(2)+V(4)-V(1)-V(3)))/Itest ! Compute Pa 340 Pb=(1.1331*Ts*(V(6)+V(8)-V(5)-V(7)))/Itest ! Compute Pb 350 PRINT "Pa=";Pa 1 Display Pa 360 370 PRINT "Pb=";Pb ! Display Pb 380 PRINT "Device average resistivity=";(Pa+Pb)/2 | Display resistivity

390 REM DATA STATEMENTS CONTAINING 705 COMMAND STRINGS 400 DATA "C01:2C02:1C03:3C04:4X" 410 DATA "NØ1:2N02:1N03:3N04:4X" DATA "C02:2C01:1C03:3C04:4X" 420 430 DATA "NØ2:2NØ1:1NØ3:3NØ4:4X" 440 DATA "C02:2C01:3C04:4C04:1X" 450 DATA "N02:2N01:3N04:4N04:1X" 460 DATA "C02:3C01:2C03:4C04:1X" 470 DATA "N02:3N01:2N03:4N04:1X" 480 DATA "C02:3C01:4C03:1C04:2X" 490 DATA "N02:3N01:4N03:1N04:2X" 500 DATA "C02:4C01:3C03:1C04:2X" DATA "N02:4N01:3N03:1N04:2X" 510 520 DATA "C02:4C01:1C03:2C04:3X" DATA "N02:4N01:1N03:2N04:3X" 530 540 DATA "C02:1C01:4C03:2C04:3X" 550 DATA "N02:1N01:4N03:2N04:3X" 560 END

7.4 SOURCE MEASURE UNIT MATRIX SWITCHING SYSTEM

The small matrix switching system discussed in the last paragraph has adequate capabilities for many applications. However, many applications call for a larger switching matrix. In the following paragraphs, we will discuss using Source Measure Units with a Model 7072 Semiconductor Matrix Card and a Model 707.

7.4.1 System Configuration

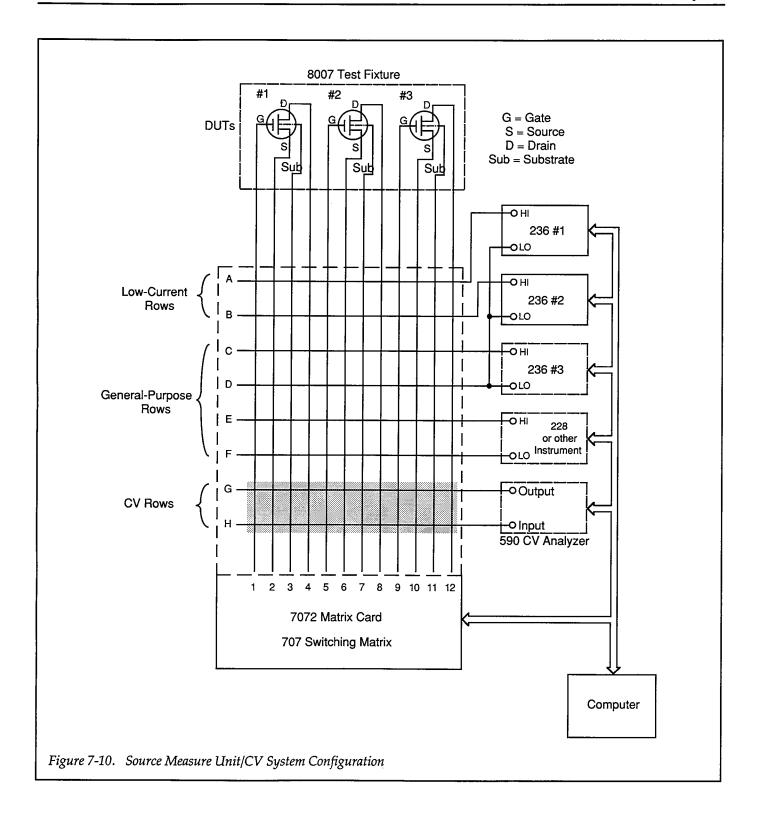
Figure 7-10 shows a typical configuration for the Source Measure Unit/matrix switching system. In addition to two Source Measure Units, the system also includes a Model 590 CV Analyzer, which can perform CV (capacitance-voltage) tests on semiconductors at 100kHz or 1MHz. Resulting CV curves can yield important information about semiconductors such as doping profile and depletion depth. NOTE

Only Model 236 Units #1 and #2 are used for the applications example in this section in order to keep the program as simple as possible.

Switching for the system is performed by a Model 7072 Semiconductor Matrix Card installed within a Model 707 Switching Matrix. Each card is organized as an 8×12 matrix as shown.

The system can easily be expanded by adding more matrix cards in the mainframe. A total of six matrix cards can be installed in one mainframe, with easy internal row expansion (adding more columns to the matrix). For example, six cards would result in an 8×72 matrix, yielding 72-pin test capability with only one mainframe.

The test fixture used in this system is a Model 8007 Semiconductor Test Fixture, although a Model 8006 Test Fixture could be used as well. The Model 8007 is intended primarily for use with the Model 7072 card, and it includes 24-pin and 48-pin DIP sockets. The unit has 72-pin test capabilities, allowing it to support up to six Model 7072 cards.



7.4.2 Test Connections

Figure 7-11 details the test connections for the example in this paragraph. Note that local sensing is used for both Source Measure Units. The Source Measure Units are connected to the matrix card using Model 7078-TRX triax cables and insulated wire (LO to LO). Note that adapters must be used to connect the triax cable to the OUTPUT LO banana jack of Unit #2, as shown in Figure 7-12.

If suitable adapters are available, you could use banana plug patch cords for LO instead of triax cables.

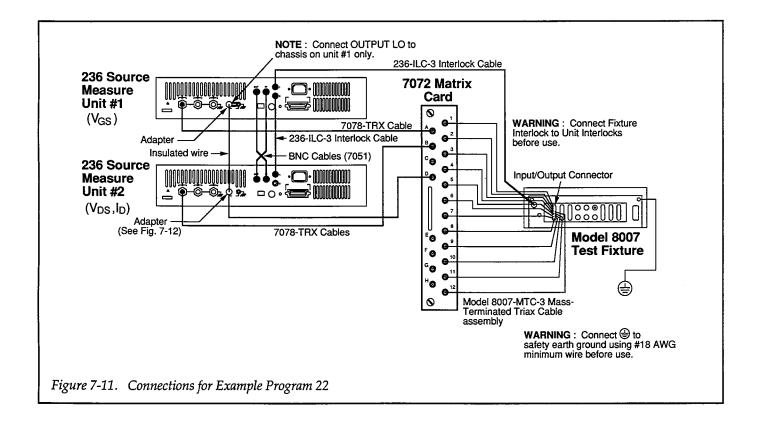
WARNING

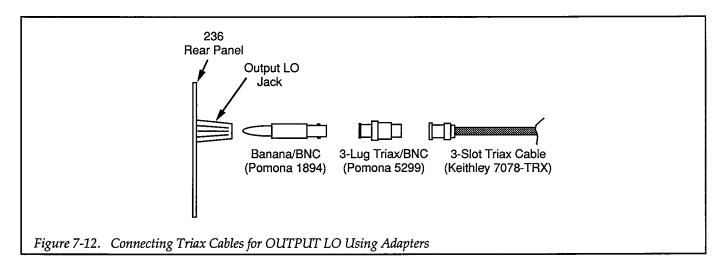
Connect interlock circuits before use. Connect the fixture \bigoplus screw to safety earth ground using #18 AWG minimum wire before use. Turn off all power before connecting or disconnecting wires or cables. The Model 8007 test fixture is connected to the matrix card using the Model 8007-MTC-3 Mass-Terminated Cable Assembly. A Model 8006 can be used instead; connections to Model 8006 triax connectors can be made using Model 7078-TRX triax cables.

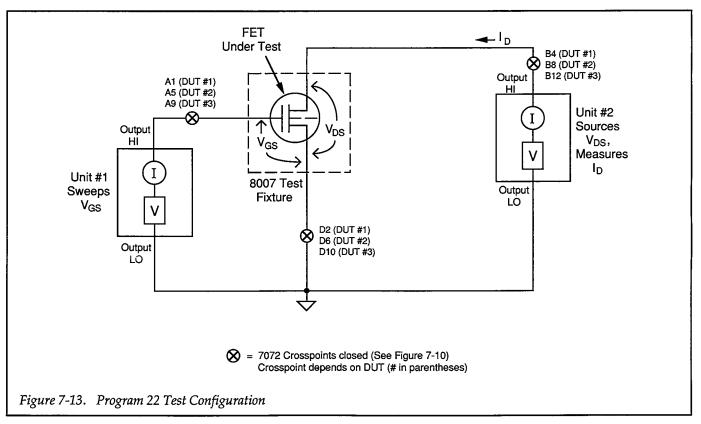
7.4.3 Test Configuration

Figure 7-13 shows the test configuration for example Program 22 included in this paragraph. The test to be performed is a g_{fs} vs. V_{GS} test on three FET devices. Unit #1 sweeps V_{GS} , and Unit #2 sources V_{DS} and measures I_D . Note that the Model 590 CV Analyzer and Source Measure Unit #3 shown in Figure 7-11 are not used in this example in order to keep the program as simple as possible.

Refer to Section 4 for a complete description of how transconductance is computed.







7.4.4 Measurement Considerations

Note that not all rows in the Model 7072 have the same capabilities: rows A and B are low-current rows (<1pA offset), rows C-F are general-purpose rows (<20pA offset), and rows G and H are designated as CV rows.

Similarly, not all rows have the same path isolation specifications. Rows A and B have the highest path isolation $(>10^{13}\Omega)$, while rows C through H have a path isolation that is an order of magnitude lower $(>10^{12}\Omega)$.

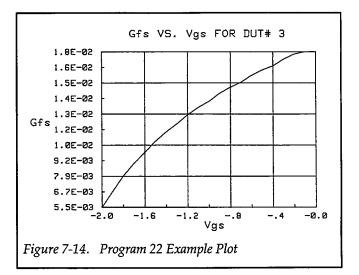
7.4.5 Example Program 22: Transconductance Test Using Switching Matrix

Use Program 22 below to generate a typical g_{fs} vs. V_{GS} plot for one of three FET devices as controlled by the switching matrix.

- 1. With the power off, connect both Source Measure Units and the switching mainframe to the IEEE-488 bus of the computer. Also install the Model 7072 card in slot 1 of the switching matrix.
- 2. Connect the units and the test fixture to the matrix card using suitable triax cables (see Figure 7-11 and Figure 7-13 for details on test connections and system configuration).
- 3. Turn on both Source Measure Units, and allow them to warm up for at least two hours for rated accuracy. Verify that the primary address of Unit #1 is set to 16 and that the primary address of Unit #2 is set to 17. Also turn on the Model 707 and verify that its primary address is set to 18.
- 4. Turn on the computer, then boot up BASIC.
- 5. Enter the lines from Program 22 below into the computer.
- 6. Place the device to be tested in the desired test fixture socket, then close the test fixture lid (the device should have characteristics similar to the 2N4392 used for other examples in this section).
- 7. RUN the program in the usual fashion, then choose the device to test when prompted to do so (1-3).
- 8. Continue the program to test all three devices. For the selected DUT, the program will step through V_{GS} values between -2V and 0V using 0.1V steps. At each increment, I_D will be measured using a fixed 10V V_{DS} value. Once data are collected, a plot of g_{fS} vs. V_{GS} for the selected device will be displayed on the computer CRT. To test the remaining two devices, rerun the program.
- 9. To return to BASIC from the graph of the DUT, press CONT.

7.4.6 Typical Program 22 Results

Figure 7-14 shows a typical g_{fs} vs. V_{GS} plot as generated by the example program.



7.4.7 Program 22 Description

Refer to the program listing below and the flowchart in Figure 7-15 for the following description of Program 22.

Initially, the data arrays are defined (lines 30-50) to hold 20 or 21 reading points. Note that two arrays are used in this program. The reading array will hold data obtained from the test instruments, while the plot array will hold computed g_{fs} and V_{GS} values to be plotted. Next, the command string is dimensioned (line 60).

After the instruments are returned to default conditions (line 70), Unit #1, which sweeps V_{GS} , is programmed as follows (lines 100-210):

- Source V, sweep mode
- 1mA compliance, 1mA range
- Local sense
- Source only data format, no prefix, sweep data output
- External trigger, one trigger per step, output trigger on end of measurement
- SRQ on sweep done
- Start V_{GS} voltage: –2V
- Stop V_{GS} voltage: 0V
- Step V_{GS} voltage: 0.1V
- Delay: 100msec
- Staircase sweep

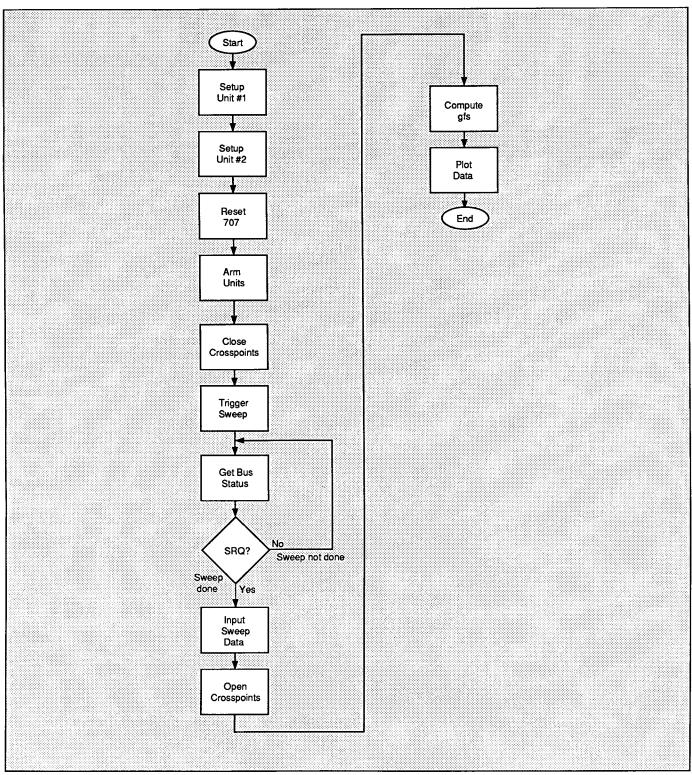


Figure 7-15. Program 22 Flowchart

Unit #2, which sources V_{DS} and measures I_D , is then configured in the following manner (lines 220-320):

- Source V, sweep mode
- Local sense
- 100mA compliance, autorange measure
- Measure only data format, no prefix, sweep data output
- External trigger, trigger source, output trigger on end of measurement
- Line cycle integration
- Constant sweep, 10V constant V_{DS} value, 21 points

Finally, the Model 707 is placed into remote and reset to ensure that all crosspoints are open (lines 340 and 350), and the DUT to be tested is selected (lines 360-440).

After operator signal (lines 450 and 460), both Source Measure Units are armed and placed into operate (lines 470-480), and the Model 707 is programmed to close the desired crosspoints (line 500). After a one-second delay for settling (line 510), Unit #2 is then triggered to start the sweep by using the immediate trigger command (line 520). Once Unit #2 is triggered, it sets V_{DS} to the programmed value, and it then triggers Unit #1 (using external triggering). Unit #1 then sets V_{GS} to the present value in its sweep list. Following the prescribed delay period, Unit #2 measures I_D and then goes on to the next point in

the sweep. The process repeats until all points in the sweep have been taken.

While the sweep is being performed, the program waits in a loop for Unit #2 to generate an SRQ on sweep done (lines 530 and 540). Once the SRQ occurs, the data are read into the reading array (lines 560-590), and the Model 707 is programmed to open the presently-closed crosspoints (line 600). The Source Measure Units are then placed into standby (lines 610-620).

Next, we encounter the part of the program where the transconductance values are calculated (lines 670-720). First, the V_{GS} values are simply transferred from the (I,1) elements of the reading array to the (I,1) elements of the plot array (line 680). Next, ΔV_{GS} values are computed by subtracting the (I,1) values from the (I+1,1) values (line 690), and ΔI_D values are similarly computed by subtracting (I,2) values from (I+1,2) values (line 700). Finally, each transconductance value is computed from ΔI_D and ΔV_{GS} and stored in the corresponding element of the plot array (line 710).

The maximum and minimum transconductance values are then determined for Y axis scaling (lines 750-780), and the data are plotted with $g_{\rm fs}$ along the Y axis and $V_{\rm GS}$ along the X axis (lines 800-1110).

REM TRANSCONDUCTANCE-GATE VOLTAGE TEST PROGRAM REV. 1.3 (Program 22) 10 20 REM INCLUDES CONTROL OF 707 SWITCHING MATRIX 30 OPTION BASE 1 ! First array subscript is 1 DIM Reading(21,2) ! Dimension reading array (21 pts) 40 50 DIM Plot_array(20,2) ! Dimension plot array (20 pts) 60 ! Dimension command string 0IM Cmd\$[25] 70 CLEAR 7 ! Clear both Units OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 80 90 100 REMOTE 716 ! Put Unit 1 in remote OUTPUT 716; "FØ, 1X" ! Source V, sweep mode 110 OUTPUT 716; "L1E-3,7X" 120 I 1mA compliance, 1mA range 130 OUTPUT 716; "OØX" ! Local sense OUTPUT 716;"G1,2,1" 140 ! Output source, no prefix, sweep data OUTPUT 716;"T3,1,4,0X" 150 ! External trigger, out trig end of measure 160 OUTPUT 716; "M2,X" ! SRQ on sweep done OUTPUT 716; "B0,0,0X" 165 ! Program Ø bias value 170 Vostart=-2.0 ! Define -2V start Vos voltage ! Define ØV stop Vgs voltage 180 Vgstop=0 190 Vgstep=.1 ! Define 0.1V step Vgs voltage ! Define 100msec Unit delay 200 D1y=100 OUTPUT 716; "Q1, "; Vgstart; ", "; Vgstop; ", "; Vgstep; ", 0, "; D1y; "X" ! Pgm swp 210 220 230 REMOTE 717 ! Put Unit 2 in remote OUTPUT 717; "FØ.1X" ! Source V, sweep mode 240 250 OUTPUT 717;"00X" ! Local sensing OUTPUT 717; "L100E-3,0X" ! 100mA compliance,autorange measure 260 270 OUTPUT 717; "G4,2,1X" ! Measure, no prefix, sweep data OUTPUT 717; "T3,1,4,0X" ! Trig ext,start source,out end of meas 280 OUTPUT 717; "S2ZØX" 290 ! Line cycle integration, suppress off 295 OUTPUT 717; "B0,0,0X" ! Program Ø bias value 300 D1y = 100310 Vds=10 ! Define 10V Vds OUTPUT 717; "Q0,"; Vds; ",0,"; Dly; ",21X" ! Constant sweep,21 points 320 330 ! Put 707 in remote 340 REMOTE 718 OUTPUT 718; "RØX" ! Reset 707 350 INPUT "Select DUT to test (1-3)", Dut ! Select DUT to test 360 370 SELECT Dut 380 CASE 1 390 Cmd\$="A1,B4,D2" 400 CASE 2 410 Cmd\$="A5,B8,D6" 420 CASE 3 430 Cmd\$="A9,B12,D10" 440 END SELECT 450 PRINT "Close lid, press CONT to begin test" 460 PAUSE OUTPUT 716; "RINIX" 470 ! Arm Unit 1 trigger, turn on output 480 OUTPUT 717; "RIN1X" ! Arm Unit 2 trigger, turn on output PRINT "Generating sweep..." 490 500 OUTPUT 718; "C"; Cmd\$; "X" ! Close crosspoints

```
WAIT 1
510
                                      ! Wait one second for settling
520
      OUTPUT 716; "HØX"
                                       ! Trigger Unit 1 to start sweep
530
      STATUS 7,7;Stat
                                      ! Get IEEE-488 bus status
540
      IF NOT BIT(Stat,10) THEN 530
                                      ! Wait for SRQ on sweep done
550
      Stat=SPOLL(716)
                                      ! Serial poll Unit 1 to clear SRQ
560
      FOR I=1 TO 21
                                       ! Loop for all 21 readings
570
      ENTER 716;Reading(I,1)
                                       1 Get Vgs data from Unit 1
580
      ENTER 717; Reading(I,2)
                                      1 Get Id data from Unit 2
590
                                      ! Loop back for next data point
      NEXT I
600
      OUTPUT 718; "N"; Cmd$; "X"
                                       ! Open crosspoints
      OUTPUT 716; "NØX"
                                      ! Turn off Unit 1 output
610
620
      OUTPUT 717; "NØX"
                                      ! Turn off Unit 2 output
630
      PRINT "Press CONT to display graph of selected DUT"
640
      PRINT "Press CONT while in graph to return to BASIC"
650
      PAUSE
660
      REM COMPUTE TRANSCONDUCTANCE AND STORE IN PLOT ARRAY
670
      FOR I=1 TO 20
                                      ! Loop for all ofs points
680
      Plot_array(I,1)=Reading(I,1) ! Store Vgs in plot array
690
      Delta_vgs=ABS(Reading(I+1,1)-Reading(I,1)) ! Compute delta Vgs
700
      Delta_id=ABS(Reading(I+1,2)-Reading(I,2)) ! Compute delta Id
710
      Plot_array(I,2)=Delta_id/Delta_vgs
                                                   ! Compute gfs
720
      NEXT I
                                      ! Loop back for next point
730
      Ymin=MAXREAL
                                      ! Find minimum and maximum gfs value
740
      Ymax=-MAXREAL
750
      FOR I=1 TO 20
760
      IF Plot_array(I,2)<Ymin THEN Ymin=Plot_array(I,2)</pre>
770
      IF Plot_array(I,2)>Ymax THEN Ymax=Plot_array(I,2)
780
      NEXT I
790
      OUTPUT KBD; CHR$(255); CHR$(75); ! Clear screen
800
      GINIT
                                       ! Initialize graphics
810
      PLOTTER IS CRT, "INTERNAL"
                                      ! Define plot to CRT
820
      GRAPHICS ON
                                      ! Turn on graphics
830
      MOVE 40.90
                                      ! Title graph
840
      LABEL "Gfs VS. Vgs FOR DUT#";Dut
850
                                      ! Label X axis
      MOVE 70,10
860
      LABEL "Vgs"
870
                                      ! Label Y axis
      MOVE 0,53
880
      LABEL "Gfs"
890
      VIEWPORT 30,120,20,85
                                      ! Define soft clip limits
900
      WINDOW Vgstart, Vgstop, Ymin, Ymax ! Scale graph
910
                                      ! Compute Y axis increment
      Y1=(Ymax-Ymin)/10
920
      X1=(Vgstop-Vgstart)/10
                                      ! Compute X axis increment
930
                                      ! Draw grid
      GRID 2*X1,2*Y1,Vgstart,Ymin
                                      ! Add some tick marks
940
      AXES X1,Y1,Vgstart,Ymin
950
                                      ! Plot data
      FOR I=1 TO 20
960
      PLOT Plot_array(I,1),Plot_array(I,2) ! Plot point
970
      NEXT I
                                      | Define character size
980
      CSIZE 4
990
      LORG 6
                                      I Center characters
     CLIP OFF
1000
                                      ! Turn off soft clipping
```

```
1010 FOR I=Vgstart TO Vgstop+.01*X1 STEP 2*X1 ! Number X axis
1020
     MOVE I, Ymin-(Y1/4)
1030 LABEL USING "#,MD.D";I
1040 NEXT I
     FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis
1050
1060
     MOVE Vgstart-(1.3*X1),I+(.3*Y1)
1070 LABEL USING "#,D.DE";I
1080 NEXT I
1090
     PAUSE
     OUTPUT KBD;CHR$(255);CHR$(75); ! Clear alpha screen
1100
1110
     GRAPHICS OFF
                                    ! Clear graphics screen
1120 END
```

SECTION 8 Optimizing Measurement Speed

8.1 INTRODUCTION

Often, the speed of a measurement is of primary importance, especially where a large number of points or sweeps are involved. There are a number of factors which can affect the overall speed of any tests you make using a Source Measure Unit test system. In the following paragraphs, we will discuss the most important speed-related factors and give several example programs that demonstrate programming techniques for optimizing measurement speed.

8.2 FACTORS AFFECTING MEASUREMENT SPEED

The most important factors that will have an effect on overall speed are: integration rate, points per sweep, filtering, delay period, autoranging, and data format. Each of these factors is briefly discussed below.

8.2.1 Integration Rate

For fastest measurements, choose the S0 rate, which will result in the shortest integration period. Note, however, that resolution will be 4-1/2 digits, and noise will increase in comparison to the longer integration periods.

8.2.2 Points Per Sweep

The number of points per sweep will affect both the actual measurement time, as well as length of time it takes to process and transmit the sweep data over the IEEE-488 bus. For maximum throughput, program the unit for as few points per sweep as possible, while still fulfilling the test requirements.

8.2.3 Filtering

Adding filtering with the P command will increase measurement time because of the increased number of conversions averaged per reading. Some compromise between the amount of tolerable noise and measurement speed may be in order. If filtering is required to minimize noise, choose the minimum number of averaged conversions possible.

8.2.4 Delay Period

The programmed delay period between source and measurement will also affect the measurement speed. Note, however, that the delay period must be sufficiently long for the test circuit to settle, or inaccurate measurements will result. One way to determine the optimum delay period is to gradually decrease the delay from some arbitrarily-long value until a change in measurement values is noted. Increase the delay slightly from this point until the change is no longer present.

8.2.5 Autoranging

Autoranging will slow down a sweep in many cases because of the finite time period it takes for the instrument to change ranges during a sweep. For that reason, you should choose an appropriate manual range for both source and measure if measurement speed is of primary importance. Obviously, you must select a range that is high enough to handle the largest value to be sourced or measured. Also, some degradation in accuracy and resolution may occur when manual ranging is used.

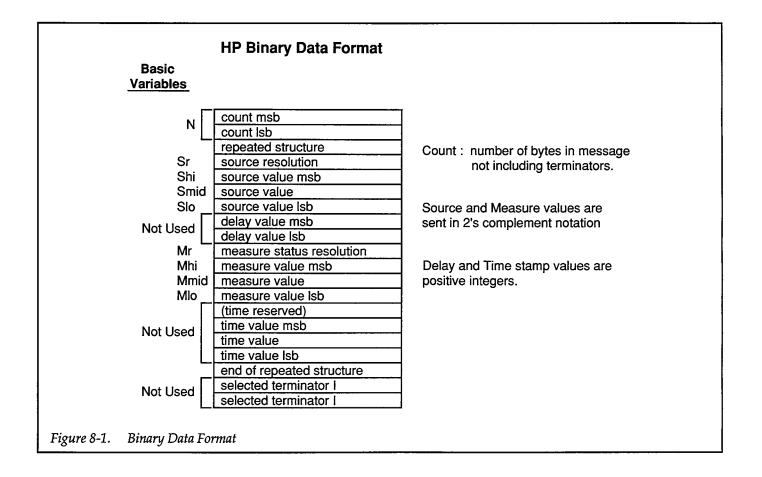
8.2.6 Data Format

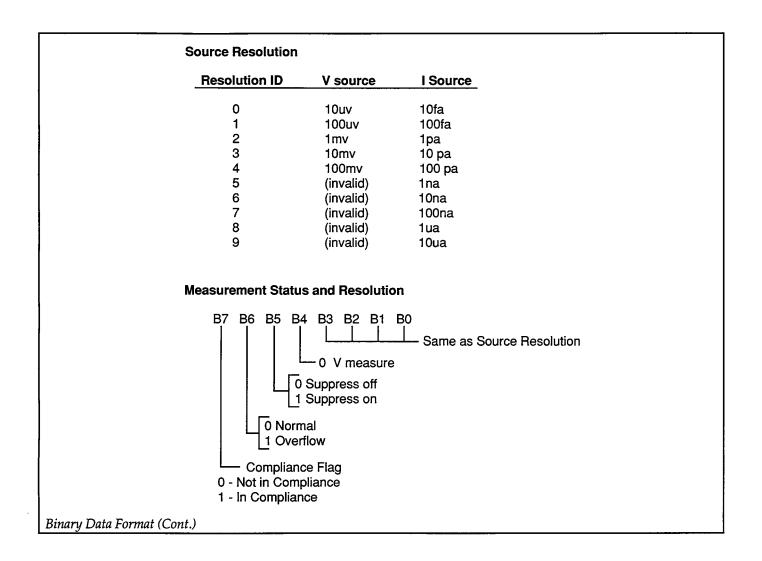
The data format affects the speed of data transfer over the IEEE-488 bus. The binary data format results in faster transmission than the ASCII data format because fewer bytes must be transmitted, and because less data processing is on the part of the instrument is required. For that reason, you should use the binary data format whenever possible if speed is of primary importance.

Figure 8-1 shows the HP binary data format used by the Model 236/237. The initial two bytes contain the count of the total bytes being sent, not including terminators. The repeated structure includes bytes for source, delay, measure, and time stamp values. Note that the data format should be programmed to eliminate those bytes not re-

quired for your particular application. In the example programs in this section, for example, only source and measure are required, so the instrument is programmed not to send delay and time values.

With the applications programs in this section, these binary values are placed into specific BASIC variables. These variables are also shown in Figure 8-1. Finally, note that the terminator bytes should be suppressed when using the binary data format by using the Y4 command. The controller should normally be programmed to terminate the input using some other method such as END or possibly by using the byte count information.





8.2.7 Controller Speed Considerations

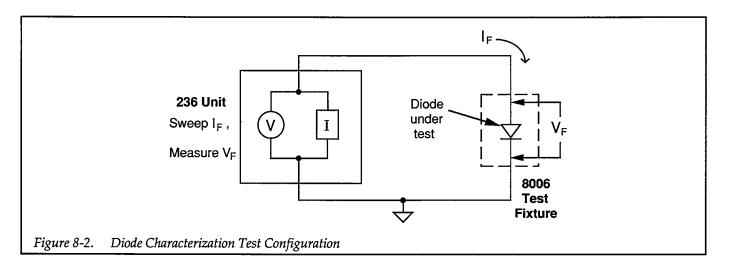
The controller speed will affect key areas of overall test performance such as the data transfer itself or any number-crunching operations required. The HP controllers used for these applications examples use either DMA or fast-handshake transfer methods (when using TRANS-FER), which should result in a substantial improvement in speed. However, because of the use of the interpretive BASIC language, the full speed increase potential may not be realized because of the relatively inefficient binary-to-decimal conversion process. However, those with compiled languages such as compiled BASIC or C should be able to take full advantage of increase in speed due to binary transfer.

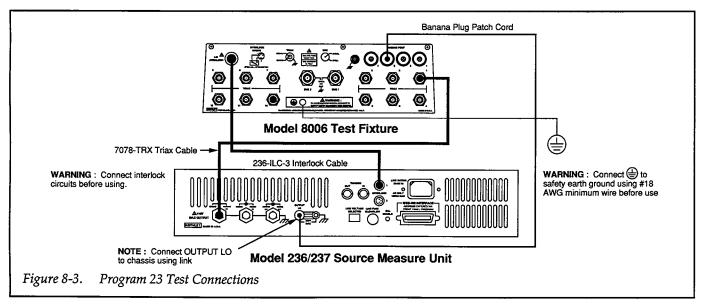
8.3 DIODE TEST USING BINARY DATA FORMAT

Program 23 below demonstrates the basic techniques for using binary data transfer. This program is essentially the same as the diode test program (Program 3) presented in paragraph 2.6, with modifications to perform binary data transfer.

8.3.1 Test Configuration

Figure 8-2 shows the test configuration for the diode characterization test. The Model 236 is used to source the forward current, I_F , through the diode under test, and it also measures the forward voltage, V_F , across the device.





 I_{F} is swept across the desired range of values, and V_{F} is measured at each current.

8.3.2 Test Connections

Figure 8-3 shows test connections for Program 23.

WARNING

Connect interlock circuits before use. Connect the fixture screw to safety earth ground using #18 AWG minimum wire before use. Turn off all power before connecting or disconnecting wires or cables.

8.3.3 Example Program 23: Diode Characterization Using Binary Transfer

Program 23 below demonstrates the basic programming techniques for running the diode characterization test with binary transfer.

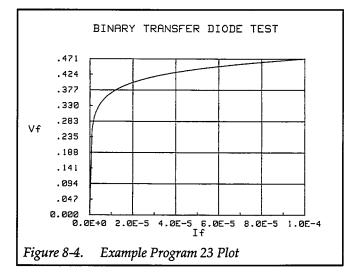
Follow the steps below to use this program.

- 1. With the power off, connect the Model 236 to the IEEE-488 interface of the computer.
- 2. Connect the test fixture to the Source Measure Unit using appropriate cables (see Figure 8-33).
- 3. Turn on the Model 236, and allow the unit to warm up for two hours for rated accuracy. Make sure the primary address of the unit is set to 16.

- 4. Turn on the computer, and boot up BASIC.
- 5. Enter the lines below into the computer.
- 6. Install a small-signal silicon diode such as a 1N914 or 1N4148 in the appropriate axial socket of the test fixture. Be certain that the jumpers are properly installed, then close the test fixture lid.
- 7. RUN the program in the usual manner. Enter the desired delay period when prompted to do so. Keep in mind that the delay period should be long enough to allow the device to settle properly before each measurement.
- 8. The computer will program the unit and run the diode test using currents between $0\mu A$ and $100\mu A$ in $1\mu A$ increments.
- 9. Once the sweep has been completed, you will be prompted to press CONT to generate a plot of the data. A simple $V_F vs. I_F plot$ will then be displayed on the computer CRT.
- 10. To return to BASIC from the graph, press CONT.

8.3.4 Typical Program 23 Results

Figure 8-4 shows typical results obtained using example Program 3. These results are for a 1N4148 silicon diode.



8.3.5 **Program 23 Description**

For the following description, refer to the program listing and the flowchart shown in Figure 8-5.

Initially, the OPTION BASE statement is used to declare that all array subscripts begin with 1 rather than 0 (line 20), and the reading array is then dimensioned for 101 points with two readings each (line 30). The I/O path

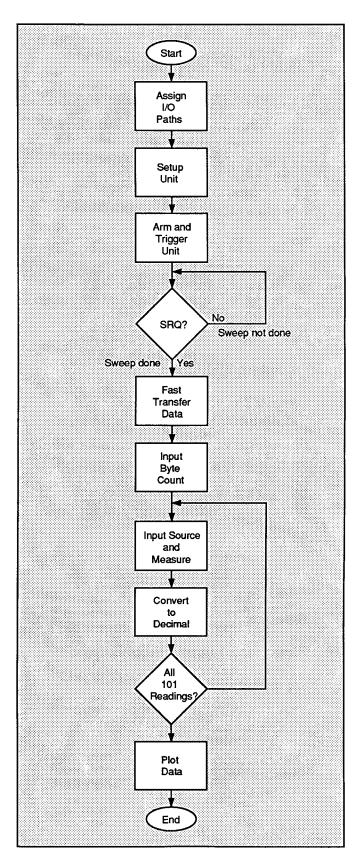


Figure 8-5. Program 23 Flowchart

name is then assigned to address 716 (line 40), and the transfer buffer is declared (line 50). Next, the Source Measure Unit is cleared and placed in remote (lines 60 and 70), and the unit is initialized as follows (lines 90-160):

- Source I, sweep mode
- Local sense, continuous trigger on GET
- 1V compliance, 1.1V range
- Source and measure binary data format, one sweep per talk
- SRQ on sweep done
- Suppress enabled
- Terminator off
- Shortest integration period
- Filter off
- Start current: 0µA
- Stop current: 100µA
- Step current: 1µA

After setup, the operator is prompted to input the desired delay (line 190), and sweep is then programmed using the 100μ A source range (line 200). The operator is then prompted to signal the start of the test (lines 210 and 220). Following the operator signal, the trigger is armed (line 230), and the unit is placed into operate and triggered (lines 240 and 250). Following the trigger, the program enters a loop where it repeatedly checks the SRQ line on the bus to determine when the sweep is finished (lines 270 and 280).

When the unit finishes the sweep, it sets the SRQ line true, and the program falls out of the loop. The status byte is then read (line 290) to clear the SRQ, and the unit is placed in standby (line 300).

At this point, high-speed data transfer is performed by using the TRANSFER statement (line 310). Note that we are using the END and WAIT options with the TRANS-FER statement. The END option dictates termination on EOI, while the WAIT option suspends program execution until transfer is complete. After statement execution, all bytes of the sweep data reside in the @Buf buffer of the computer.

The first two bytes requested after transfer are the byte count bytes, which are placed into variable N with the aid of the "W" image statement (line 320). Although this program does not use the byte count, the bytes still must be read from the buffer in order to update the buffer point-

ers. In many cases, you may find these bytes useful in determining how many bytes to input from the Source Measure Unit.

Next a loop is entered (line 330) to input and process all data bytes into the proper arrays. First, eight bytes are placed into variables using the appropriate image for byte values (line 340). These variables are defined as follows:

Sr (Source Resolution): This variable holds information on the the source resolution.

Shi (Source High): This variable contains the most-significant byte of the source value.

Smid (Source Middle Byte): This variable corresponds to the middle byte value of the source.

Slo (Source Low): This variable holds the least significant byte of the source value.

Mr (Measure Resolution): This variable contains the measurement resolution, compliance flag, and overflow information.

Mhi (Measure High): This variable includes the most-significant byte of the measure value.

Mmid (Measure middle value): This variable holds the middle byte of the measure value.

Mlo (Measure Low): This variable contains the least-significant byte of the measure value.

The important part of the binary-to-decimal conversion process in located in lines 340-390. First, the measure and source value high bytes are checked to see if they are negative, by testing bit 7 of the respective high bytes (lines 350 and 360). If either byte is negative, it is sign extended to properly convert negative values. Although there should be no negative values in this application, it is possible that some small negative offset or noise could occur.

Next, the measure resolution byte is masked so that its value represents only the resolution (line 370). The measure data is converted from binary to decimal (line 380), and the source value is converted using the same method (line 390).

After conversion, the source value, which is the forward current, is located in element (I,1) of the reading array,

and the measured voltage is in element (I,2) of the reading array. The minimum and maximum measured voltage values are then found (lines 410-460); these values are used to scale the Y axis of the plot. Plotting is performed (lines 510-800), with $V_{\rm F}$ along the Y axis, and $I_{\rm F}$ along the X axis.

10 REM BINARY TRANSFER DIODE CHARACTERIZATION PROGRAM REV. 1.3 (Program 23) | First array subscript is 1 20 OPTION BASE 1 30 DIM Reading(101,2) ! Dimension reading array 40 ASSIGN @D236 TO 716 ! Assign I/O path to 236 50 ASSIGN @Buf TO BUFFER [3000] ! Assign I/O path to BUFFER | Clear 236 60 CLEAR 7 ! Put 236 in remote 70 REMOTE 716 80 OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear screen 90 OUTPUT 716; "F1,1X" I Source I, sweep mode 100 OUTPUT 716; "OOT1,0,0,0X" ! Local sense, trigger on GET OUTPUT 716; "L1,1X" 110 1 1V compliance, 1.1V range ! Source,measure,binary data 120 OUTPUT 716; "65,3,2X" 130 OUTPUT 716; "M2,X" I SRQ on sweep done OUTPUT 716; "Z1X" ! Enable suppress 140 OUTPUT 716;"Y4S0P0X" 150 I Terminator off, fast rate, filter off OUTPUT 715; "B0,0,0X" 155 | Program Ø bias value 160 ! Define OuA start current Istart=0 170 | Define 100uA stop current Istop=1.00E-4 180 Istep=1.0E-6 ! Define luA step current INPUT "Enter delay (msec)",Dly ! Input delay value 190 OUTPUT 716; "Q1, "; Istart; ", "; Istop; ", "; Istep; ", Ø, "; Dly; "X" ! Program sweep 200 210 PRINT "Close lid, press CONT to begin" 220 PAUSE ! Wait to continue 230 OUTPUT 716;"R1X" ! Arm trigger 240 OUTPUT 716; "NIX" I Turn on 236 output 250 ! Trigger 236 to start sweep TRIGGER 716 260 PRINT "Waiting for sweep to end" STATUS 7,7:Stat 270 ! Get IEEE-488 bus status 280 IF NOT BIT(Stat,10) THEN 270 ! Wait for SRQ on sweep done 290 Stat=SPOLL(716) ! Serial poll 236 to clear SRQ 300 ! Turn off 236 output OUTPUT 716; "NØX" 310 TRANSFER @D236 TO @Buf;END,WAIT ! Transfer from 236 to computer 320 ! Input reading count ENTER @Buf USING "%,W";N 330 FOR I=1 TO 101 ! Loop for all readings 340 ENTER @Buf USING "%, B, B, B, B, B, B, B, B, Sr, Shi, Smid, Slo, Mr, Mhi, Mmid, Mlo 350 IF BIT(Mhi,7) THEN Mhi≈BINEOR(Mhi,-256) ! Sign extend measure high byte IF BIT(Shi,7) THEN Shi=BINEOR(Shi,-256) ! Sign extend source high byte 360 370 Mr=BINAND(Mr,15) ! Mask off range bits 380 Reading(I,2)=(65536*Mhi+256*Mmid+Mlo)*1.E-5*10^Mr ! Convert measure 390 Reading(I,1)=(65536*Shi+256*Smid+Slo)*1.E-14*10^Sr ! Convert source 400 NEXT I ! Loop back for next reading 410 Ymin=MAXREAL | Find minimum and maximum voltage 420 Ymax=-MAXREAL 430 FOR I=1 TO 101 440 IF Reading(I,2)<Ymin THEN Ymin=Reading(I,2) 450 IF Reading(I,2)>Ymax THEN Ymax=Reading(I,2) 460 NEXT I 470 PRINT "Press CONT to display graph" 480 PRINT "Press CONT while in graph to return to BASIC" 490 PAUSE 500 OUTPUT KBD;CHR\$(255);CHR\$(75); | Clear CRT

```
510
      GINIT
                                          ! Initialize graphics
      PLOTTER IS CRT, "INTERNAL"
                                          ! Define plot to CRT
520
530
      GRAPHICS ON
                                          ! Turn on graphics
540
      MOVE 30,95
                                          ! Title graph
550
      LABEL "BINARY TRANSFER DIODE TEST"
560
                                          ! Label X axis
      MOVE 70,10
570
      LABEL "If"
580
      MOVE 0,53
                                          ! Label Y axis
590
      LABEL "Vf"
600
      VIEWPORT 30,120,20,85
                                          ! Define soft clip limits
610
      WINDOW Istart, Istop, Ymin, Ymax
                                          i Scale graph
                                          I Compute X axis increment
620
      X1=(Istop-Istart)/10
630
      Y1=(Ymax-Ymin)/10
                                          ! Compute Y axis increment
640
      GRID X1*2, Y1*2, Istart, Ymin
                                          | Draw orid
650
      AXES X1,Y1,Istart,Ymin
                                          ! Add some tick marks
660
      PLOT Reading(*)
                                          | Plot data
670
                                          | Define character size
      CSIZE 4
      LORG 6
                                          ! Center characters
680
      CLIP OFF
690
                                          ! Turn off soft clipping
700
      FOR I=Istart TO Istop+.01*Istep STEP 2*X1 ! Number X axis
710
      MOVE I, Ymin-(Y1/4)
720
      LABEL USING "#,D.DESZ";I
730
      NEXT I
740
      FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis
750
      MOVE Istart-(1.3*X1), I+(.3*Y1)
760
      LABEL USING "#,MDD.DDD"; I
770
      NEXT I
780
      PAUSE
790
      OUTPUT KBD;CHR$(255);CHR$(75);
                                         ! Turn off alpha display
                                          ! Turn off graphics display
800
      GRAPHICS OFF
810
      END
```

8.4 COMMON-EMITTER CHARACTER-ISTICS USING BINARY DATA TRANSFER

Program 24 shown below is essentially the same program as discussed in Section 3 (Program 4) with modifications necessary to use binary data transfer. The following paragraphs give an overview of this program and how to run it.

8.4.1 Test Configuration

Figure 8-6 shows the test configuration for the commonemitter characteristic tests. Unit #1 sweeps I_B across the desired range, and Unit #2 sweeps V_{CE} and measures I_C . Note that an NPN transistor is shown as part of the test configuration. A small-signal NPN transistor with an approximate current gain of 500 (2N5089) is recommended for use with the test program below.

8.4.2 Test Connections

Figure 8-7 shows the test connections for Program 24.

WARNING Connect interlock circuit before use. Connect fixture screw to safety earth ground using #18 AWG minimum wire before use. Turn off all power before connecting or disconnecting wires or cables.

8.4.3 Measurement Considerations

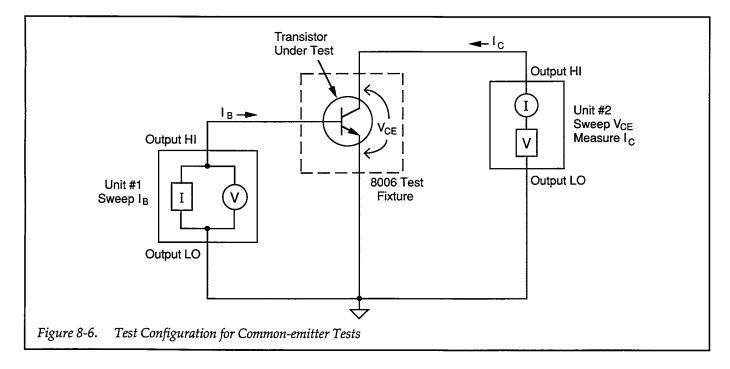
The selected delay period should be sufficiently long to allow the device to completely settle before each measurement. Also, it may be necessary to change the programmed current values to optimize the tests for a particular device.

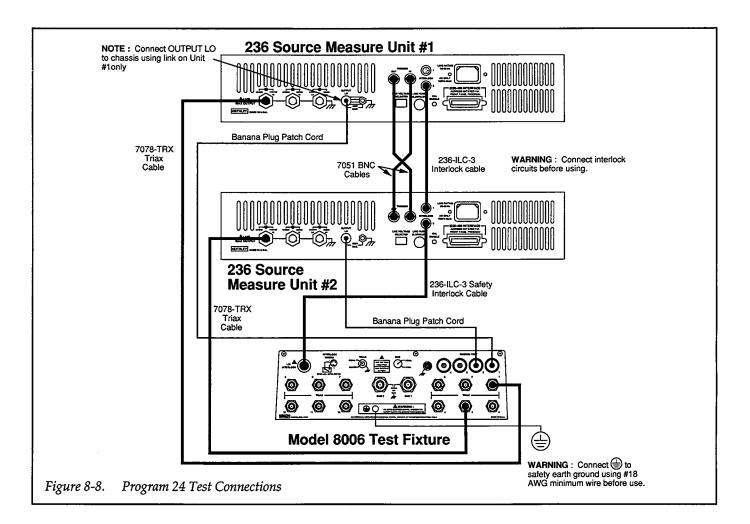
8.4.4 Program 24: Common-emitter Characteristics Using Binary Transfer

Program 24 below can be used to run common-emitter characteristic tests on small-signal NPN transistors using binary transfer to read data.

In order to run the program, follow the steps below.

- 1. With the power off, connect both Model 236 Source Measure Units to the IEEE-488 interface of the computer.
- 2. Connect the test fixture to both Source Measure Units using appropriate triax cables (see Figure 8-7).
- 3. Turn on both Model 236 Source Measure Units, and allow the units to warm up for two hours for rated



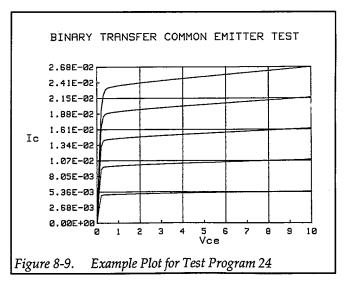


accuracy. Make sure the primary address of Unit #1 is set to 16 and that the primary address of Unit #2 is set to 17.

- 4. Turn on the computer, and boot up BASIC.
- 5. Enter the lines below into the computer.
- 6. Install a small-signal NPN silicon transistor such as a 2N5089 in the appropriate transistor socket of the test fixture. Be certain that the jumpers are properly installed, then close the test fixture lid.
- 7. RUN the program in the usual manner, and type in the desired delay period when prompted to do so. The computer will program both Source Measure Units and run the common-emitter characteristic test on the device. The base current will be swept between 10μ A and 50μ A in 10μ A increments, and the value of V_{CE} will be swept between 0V and 10V in 0.1V increments.
- 8. Once the sweeps have been completed, you will be prompted to press CONT to generate a plot of the data. A simple I_C vs. V_{CE} plot will then be displayed on the computer CRT, with separate curves for each I_B value.
- 9. To return to BASIC from the graph, press CONT.

8.4.5 Typical Program 24 Results

Figure 8-9 shows typical results generated by example Program 4. A 2N5089 NPN silicon transistor was used to generate these test results.



8.4.6 Program 24 Description

For the following program description, refer to the program listing below and the flowchart shown in Figure 8-9.

Initially, the reading array is dimensioned (line 30) as a three-element array that will hold five sweeps of 101 points each, with two readings for each point. The I/O path and transfer buffers are then assigned (lines 40 and 50), and, both Source Measure Units are returned to default conditions by a DCL command (line 60). Unit #1, which sweeps I_B , is set up as follows (lines 90-180):

- Source I, sweep mode
- 1V compliance, 1.1V range
- Local sense
- Trigger on GET, one step per trigger, output trigger at end of delay
- Start I_B current: 10μA
- Stop I_B current: 50µA
- Step I_B current: 10μA
- Delay: user-programmed
- Staircase sweep (limits determined by start, stop, and step current)

Following Unit #1 setup, Unit #2, which sweeps V_{CE} and measures I_{C} , is programmed as follows (lines 200-320):

- Source V, sweep mode
- Local sensing
- 100mA compliance, 100mA range
- Source measure binary data format, complete sweep per talk
- SRQ on sweep done
- Suppress enabled
- Terminator off
- Fastest integration rate
- Filter off
- Trigger on external, one sweep per trigger
- Start V_{CE} voltage: 0V
- Stop V_{CE} voltage: 10V
- Step V_{CE} voltage: 0.1V
- Staircase sweep (limits determined by start, stop, and step voltage)

Once the two units are ready to go, both unit triggers are armed and the units are placed into operate (lines 350 and

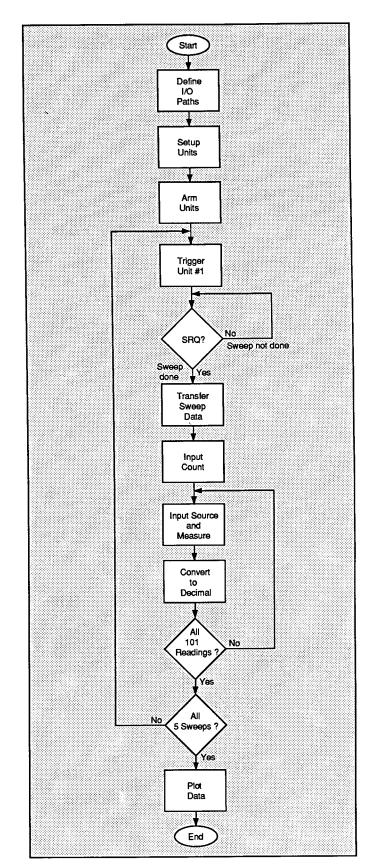


Figure 8-9. Program 24 Flowchart

360). The main programming loop is then entered to generate the five I_B curve sweeps (line 370).

To initiate each I_B curve sweep, Unit #1 is triggered over the bus by the IEEE GET command (line 390). This trigger causes Unit #1 to output the next programmed I_B current step. Following the programmed delay period, Unit #1 outputs a trigger pulse, which triggers Unit #2 to begin its sweep through all programmed V_{CE} values. At each V_{CE} value, Unit #2 measures I_C , and stores the data until the sweep is done.

In order to synchronize the program with each sweep, the program enters a loop to wait for Unit #2 to generate an SRQ (lines 400 and 410) when it has finished a sweep. Once each sweep has finished, Unit #2 is serial polled to clear the SRQ line (line 420).

At this point, the high-speed data transfer is performed by using the TRANSFER statement (line 430), again using the END and WAIT options with the TRANSFER statement. The first two bytes requested after transfer are the byte count bytes, which are placed into variable N with the aid of the "W" image statement (line 430). Once again, these bytes are not used by the program, but they still must be read from the buffer in order to update the buffer pointers.

Next a loop is entered (line 450) to input and process all data bytes into the proper arrays. First, eight bytes are placed into variables using the appropriate image for byte values (line 460). These variables are defined as follows:

Sr (Source Resolution): This variable contains information on the the source resolution.

Shi (Source High): This variable contains the most-significant byte of the source value.

Smid (Source Middle): This variable contains the middle byte of the source value.

Slo (Source Low): This variable holds the least significant byte of the source value.

Mr (Measure Resolution): This variable contains the measurement resolution, compliance flag, and overflow information.

Mhi (Measure High): This variable holds the most-significant byte of the measure value.

Mmid (Measure Middle Value): This variable contains the middle byte of the measure value.

Mlo (Measure Low): This variable contains the least-significant byte of the measure value.

After the information is transferred to the respective variables, bit 7 of Mhi and Shi are checked to determine if the values are negative. If so, the respective bytes are sign extended to convert to negative (lines 480 and 490). We are assuming that any negative values are the result of offsets or noise because all normal measured values are assumed to be positive.

The measure and source values are then converted to decimal (lines 500-510). After conversion, the source value is located in element (I,1) of the reading array, and the measured current is in element (I,2) of the reading array. The minimum and maximum measured collector current values are then found (lines 590-690), and data are then plotted (lines 680-1020).

REM BINARY TRANSFER COMMON EMITTER PROGRAM REV. 1.3 (Program 24) 10 20 OPTION BASE 1 ! First array subscript is 1 ! Dimension reading array (5 swps,101 pts) 30 DIM Reading(5,101,2) ASSIGN @D236 TO 717 ! Assign I/O path to Unit 2 40 50 ASSIGN @Buf TO BUFFER [2500] ! Assign I/O path to BUFFER ! Clear both Units 60 CLEAR 7 70 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 80 90 REMOTE 716 ! Put Unit 1 in remote OUTPUT 716; "F1,1X" 100 ! Source I, sweep mode OUTPUT 716; "L1,1X" 110 1 1V compliance, 1.1V range 120 OUTPUT 716;"00X" ! Local sense OUTPUT 716; "T1,1,2,0X" 130 ! GET trigger cycle,out trig end of delay | Program Ø bias value 135 OUTPUT 716;"B0,0,0X" ! Define 10uA start Ib current 140 Istart=1.0E-5 ! Define 50uA stop Ib current 150 Istop=5.0E-5 ! Define 10uA step Ib current 160 Istep=1.0E-5 INPUT "Enter delay (msec)", Dly ! Input delay for both Units 170 OUTPUT 716;"Q1,";Istart;",";Istop;",";Istep;",0,";Dly;"X" ! Program sweep 180 190 200 REMOTE 717 ! Put Unit 2 in remote 210 OUTPUT 717; "F0,1X" 1 Source V, sweep mode OUTPUT 717;"00X" ! Local sensing 220 230 OUTPUT 717; "L100E-3,9X" ! 100mA compliance,100mA range OUTPUT 717;"G5,3,2X" 240 ! Source, measure, binary, sweep data OUTPUT 717; "M2,X" ! SRQ on sweep done 250 255 OUTPUT 717; "B0,0,0X" | Program Ø bias value OUTPUT 717; "Z1X" ! Enable suppress 260 270 OUTPUT 717; "T3,0,0,0X" ! Trigger on external OUTPUT 717; "Y4S0P0X" ! Terminator off, fastest rate, no filtering 280 290 Vstart=0 ! Define ØV start Vce 300 Vstop=10 ! Define 10V stop Vce ! Define 0.1V step Vce 310 Vstep=.1 OUTPUT 717; "Q1, "; Vstart; ", "; Vstop; ", "; Vstep; ", 0, "; Dly; "X" ! Program sweep 320 PRINT "Close lid, press CONT to begin test" 330 340 PAUSE 350 OUTPUT 716; "RIN1X" ! Arm Unit 1 trigger, turn on output 360 OUTPUT 717; "RINIX" | Arm Unit 2 trigger, turn on output ! Loop for five Ib curves 370 FOR I=1 TO 5 380 PRINT "Generating sweep"; I 390 ! Trigger Unit to start sweep TRIGGER 716 400 STATUS 7,7;Stat ! Get IEEE-488 bus status 410 IF NOT BIT(Stat,10) THEN 400 ! Wait for Unit 2 SRQ on sweep done | Serial poll Unit 2 to clear SRQ 420 Stat=SPOLL(717) TRANSFER @D236 TO @Buf;END,WAIT ! Transfer from Unit 2 to computer 430 ENTER @Buf USING "%,W";N ! Get count info 440 450 ! Loop for all 101 readings FOR J=1 TO 101 ENTER @Buf USING "%, B, B, B, B, B, B, B, B, B, Sr, Shi, Smid, Slo, Mr, Mhi, Mmid, Mlo 460 470 1 Mask off range bits Mr=BINAND(Mr,15) IF BIT(Mhi,7) THEN Mhi=BINEOR(Mhi,-256) ! Sign extend measure high byte 480 490 IF BIT(Shi,7) THEN Shi=BINEOR(Shi,-256) ! Sign extend source high byte 500 Reading(I,J,2)=(65536*Mhi+256*Mmid+Mlo)*1.E-14*10^Mr ! Convert measure

510 Reading(I,J,1)=(65536*Shi+256*Smid+Slo)*1.E-5*10^Sr! Convert source value 520 NEXT J ! Loop back for next reading 530 ! Loop back for next Ib value NEXT I 540 OUTPUT 716; "NØX" | Turn off Unit 1 output OUTPUT 717; "NØX" ! Turn off Unit 2 output 550 PRINT "Press CONT to display graph" 560 570 PRINT "Press CONT while in graph to return to BASIC" 580 PAUSE 590 Ymin=MAXREAL Find minimum and maximum Ic value 600 Ymax=-MAXREAL 610 FOR I=1 TO 5 FOR J=1 TO 101 620 630 IF Reading(I,J,2)<Ymin THEN Ymin=Reading(I,J,2) IF Reading(I,J,2)>Ymax THEN Ymax=Reading(I,J,2) 640 650 NEXT J 660 NEXT I 670 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 680 ! Initialize graphics GINIT PLOTTER IS CRT, "INTERNAL" ! Define plot to CRT 690 700 GRAPHICS ON ! Turn on graphics 710 MOVE 10,95 ! Title graph 720 LABEL "BINARY TRANSFER COMMON EMITTER TEST" 730 ! Label X axis MOVE 70,10 740 LABEL "Vce" ! Label Y axis 750 MOVE 0,53 LABEL "Ic" 760 ! Define soft clip limits 770 VIEWPORT 30,120,20,85 780 WINDOW Vstart, Vstop, Ymin, Ymax ! Scale graph | Compute Y axis increment 790 Y1=(Ymax-Ymin)/10 X1=(Vstop-Vstart)/10 800 810 GRID 2*X1,2*Y1,Vstart,Ymin ! Draw grid ! Add some tick marks 820 AXES X1,Y1,Vstart,Ymin 830 FOR I=1 TO 5 ! Loop for all five curves ! Loop for all 101 points per curve FOR J=1 TO 101 840 PLOT Reading(I,J,1), Reading(I,J,2) ! Plot point 850 ! Plot next point 860 NEXT J 870 PENUP 880 NEXT I ! Plot next curve ! Define character size 890 CSIZE 4 ! Center character 900 LORG 6 ! Turn off soft clipping 910 CLIP OFF FOR I=Vstart TO Vstop+.01*Vstep STEP X1 | Number X axis 920 MOVE I, Ymin-(Y1/4) 930 940 LABEL USING "#,K";I 950 NEXT I FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! Number Y axis 960 MOVE Vstart-(1.3*X1),I+(.3*Y1) 970 LABEL USING "#,MD.DDE";I 980 990 NEXT I 1000 PAUSE 1010 OUTPUT KBD;CHR\$(255);CHR\$(75); ! Turn off alpha display 1020 GRAPHICS OFF ! Turn off graphics display 1030 END

8.5 SELF-BIAS THRESHOLD TEST WITH PLOTTING AND BINARY TRANSFER

The following paragraphs discuss the self-bias threshold test with added $V_{\rm T}$ vs. $I_{\rm D}$ plotting and binary transfer for maximum speed.

8.5.1 Self-bias Threshold Test Configuration

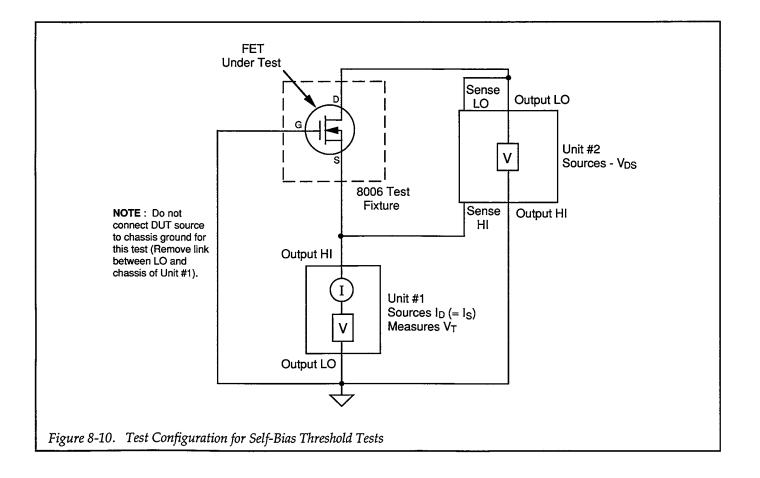
Figure 8-10 shows the general test configuration for the self-bias method of threshold voltage tests. Unit #1 sources the drain current, which is assumed to be the same as the source current, and it also measures the threshold voltage, V_T . Unit #2 sources V_{DS} . This arrangement allows very rapid threshold voltage measurement (milliseconds per reading) at very low currents, and it can be used with both enhancement-mode and depletion-mode FETs. Note that the high-impedance sensing circuits and the floating capabilities of the Models 236/237 are key characteristics that allow this special configuration to be used.

WARNING

When a Model 236/237 is programmed for remote sensing, hazardous voltage may be present on the SENSE and OUTPUT terminals when the unit is in operate regardless of the programmed voltage or current. To avoid a possible shock hazard, always turn off all power before connecting or disconnecting cables to the Source Measure Unit or the associated test fixture.

NOTE

Both V_{DS} and I_D must be programmed with reversed polarity because of the connection configuration used. For example, for an N-channel FET, both V_{DS} and I_D must be negative. These values will result in proper biasing of the DUT. Also, the sign of the measured V_T value will be reversed.



8.5.2 Self-bias Method Measurement Considerations

There is a limit as to the maximum voltage that can appear between the sense and source leads of each Source Measure Unit. For that reason, the maximum threshold voltage that can be measured with this method is defined as follows:

$$V_{MAX} = 12 - 10 \left(\frac{V_{DS}}{V_{FS}}\right)$$

Where V_{MAX} = maximum threshold voltage V_{DS} = Unit 2 V_{DS} value V_{FS} = full scale voltage range of Unit #2

For example, if V_{DS} has a value of 5V with the unit on the 11V measurement range, the maximum voltage is:

$$V_{MAX} = 12 - 10(5/11) = 7.45V$$

From this relationship, it can be seen that the voltage range of Unit #2 should be set as high as possible.

8.5.3 Program 25: Self-bias Threshold Voltage Tests with Plotting and Binary Data Transfer

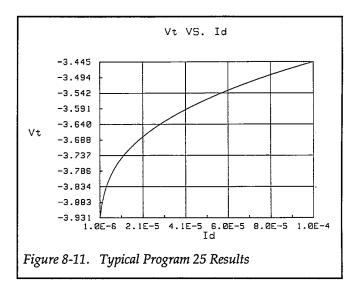
Use Program 25 below to perform the self-bias threshold voltage test.

- 1. With the power off, connect both Source Measure Units to the IEEE-488 bus of the computer.
- 2. Connect both units to the test fixture with suitable triax cables using Figure 8-10 as a guide (refer to Figure 8-7 for physical test connections. Note that remote sensing connections are used for Unit #2, and that both OUTPUT LO and SENSE LO of Unit #2 are connected to the drain of the device under test. With this configuration, it will be necessary to program negative V_{DS} and I_D values in order to properly bias the DUT.
- 3. Turn on both units, and allow them to warm up for at least two hours for rated accuracy. Verify that the primary address of Unit #1 is set to 16; the primary address of Unit #2 should be set to 17.
- 4. Turn on the computer, then boot up BASIC.

- 5. Enter the lines from Program 25 below into the computer.
- 6. Place the desired N-channel (enhancement-mode or depletion-mode) FET in the appropriate transistor socket. Install the correct jumpers (using Figure 8-10 as a guide), then close the test fixture lid.
- 7. RUN the program in the usual fashion. The computer will program Unit #1 to step through I_D current values between $-1\mu A$ and $-100\mu A$ at $-1\mu A$ increments, using a Omsec user delay for maximum speed and a fixed V_{DS} value of -10V.
- 8. After data are collected, the computer will display a graph of V_T vs. I_D , with both V_T and I_D sign adjusted for correct polarity.

8.5.4 Typical Program 25 Results

Figure 8-11 shows a typical plot generated by Program 25. The FET used for this example was a 2N4392 N-channel JFET.



8.5.5 Program 25 Description

Refer to the program listing below and the flowchart in Figure 8-12 for the following description of Program 25.

Initially, the data arrays and I/O paths are set up (lines 30-60), and then instruments are returned to default conditions (line 70). Next, Unit #1, which sources I_D and measures V_T , is programmed as follows (lines 100-220):

- Source I, sweep mode
- 10V compliance, 11V range
- Local sense
- Trigger on GET, continuous

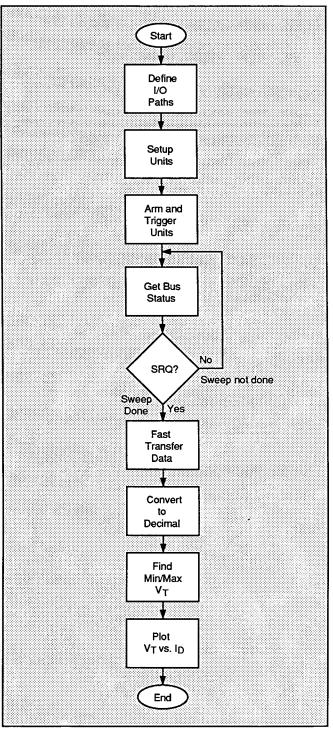


Figure 8-12. Program 25 Flowchart

- Source, measure data, no prefix or suffix, binary data
- SRQ on sweep done
- Terminator off, fastest integration rate, filter off
- Start I_D current: –1μA
- Stop I_D current: –100µA

- Step I_D current: -1µA
- Delay: 0msec

Next, Unit #2, which sources V_{DS} is then configured in the following manner (lines 240):

- Source V, dc mode
- Remote sensing
- 100mA compliance, 100mA range
- Trigger on GET, continuous
- –10V fixed V_{DS} value

After operator signal (lines 310 and 320), both Source Measure Units are armed and placed into operate (lines 330 and 340) and triggered (lines 350 and 360). The program then enters a loop to wait for Unit #1 to generate an SRQ (lines 370 and 370. After the SRQ, Unit #1 is serial polled to clear the SRQ (line 390), and both units are placed into standby (lines 400 and 410).

Unit #1 data is then transferred to the computer buffer (line 420), and the byte count is read from the buffer to update the buffer pointer (line 430). Next, the main input and conversion loop are set up (lines 440-510). Initially, all eight bytes of a reading are read from the buffer into BASIC variables (line 450), and the source and measure values are check to see if they are negative (lines 460 and 470). If so, the corresponding byte is sign extended to properly convert to a negative value. After this conversion, the measure resolution byte is masked to recover the resolution bits (line 480), and the source and measure values are converted to decimal and, at the same time, sign adjusted for correct polarity (lines 490 and 500).

After conversion, the maximum and minimum V_T values are determined (lines 520-570), and data is plotted as usual (lines 610-910).

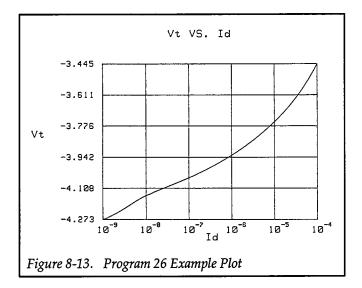
8.5.6 Modifying Program 25

As written, the program tests for threshold voltages at 100 values of of I_D between $-1\mu A$ and $-100\mu A$ at $-1\mu A$ increments (as pointed out previously, the programmed drain currents must be negative with an N-channel device because of the test configuration used). These values can be changed to the required values simply by modifying the corresponding variables in the program.

8.5.7 Self-bias Threshold Test Using Log Sweep

Often, the required sweep range is too large for a linear sweep. In such cases, a log sweep can be used. Program

26 is a modified version of Program 25 which will generate a plot of V_T vs. I_D using a range of I_D between 1nA and 100 μ A with 10 points per decade. Aside from the changes required to accommodate a log sweep, the other important changes include the use of line cycle integration as well as a 200msec delay period because of the low currents involved. Figure 8-13 shows an example plot generated by this program.



10 REM SELF BIAS THRESHOLD VOLTAGE TEST PROGRAM REV. 1.3 (Program 25) REM INCLUDES BINARY TRANSFER AND PLOTTING OF Vt VS. Id 20 ! First array subscript is 1 30 OPTION BASE 1 40 DIM Reading(100,2) | Dimension reading array ASSIGN @D236 TO 716 ! Assign I/O path to 236 50 ASSIGN @Buf TO BUFFER [3000] ! Assign I/O path to BUFFER 60 70 ! Clear both Units CLEAR 7 OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear screen 80 90 | Put Unit | in remote 100 REMOTE 716 OUTPUT 716; "F1,1X" ! Source I, sweep mode 110 OUTPUT 716;"L10,2X" 120 | 10V compliance, 11V range ! Local sense, suppress off 130 OUTPUT 716; "00Z0X" OUTPUT 716;"T1,0,0,0X" ! GET trigger,continuous ! Source,measure,binary data 140 150 OUTPUT 716;"G5,3,2X" ! SRQ on sweep done 160 OUTPUT 716; "M2,X" OUTPUT 716; "Y4S0P0X" ! Terminator off,fast rate,filter off 170 OUTPUT 716;"B0,0,0X" ! Program 0 bias value 175 ! Define -luA start current 180 Istart=-1.0E-6 190 ! Define -100uA stop current Istop=-1.00E-4 ! Define -luA step current 200 Istep=-1.0E-6 210 Dly=0 ! Define Ø sec Unit delay OUTPUT 716;"Q1,";Istart;",";Istop;",";Istep;",0,";Dly;"X" ! Pgm swp 220 230 ! Put Unit 2 in remote 240 REMOTE 717 OUTPUT 717; "F0,0X" 1 Source V, DC mode 250 OUTPUT 717;"01X" 260 ! Remote sensing 270 OUTPUT 717;"L100E-3,9X" ! 100mA compliance,100mA range OUTPUT 717; "T1,0,0,0X" | Get trigger, continuous 280 ! Define -10V Vds value 290 Vds=-10 OUTPUT 717 ;"B";Vds;",3,";Dly;"X" ! Program DC, 110V range,delay 300 310 PRINT "Close lid, press CONT to begin test" 320 PAUSE OUTPUT 716; "RINIX" ! Arm Unit 1 trigger, turn on output 330 ! Arm Unit 2 trigger, turn on output 340 OUTPUT 717; "RINIX" | Trigger Unit 2 350 TRIGGER 717 360 TRIGGER 716 | Trigger Unit 1 STATUS 7,7;Stat ! Get bus status 370 IF NOT BIT(Stat,10) THEN 370 | Wait for SRQ 380 ! Serial poll Unit 1 to clear SRQ 390 Stat=SPOLL(716) | Turn off Unit 1 output OUTPUT 716; "NØX" 400 OUTPUT 717;"N000X" ! Turn off Unit 2 output, local sense 410 TRANSFER @D236 TO @Buf;END,WAIT | Fast transfer data to computer 420 430 ENTER @Buf USING "%,W";N ! Input reading count ! Loop for all readings 440 FOR I=1 TO 100 ENTER @Buf USING "%, B, B, B, B, B, B, B, B, B, Sr, Shi, Smid, Slo, Mr, Mhi, Mmid, Mlo 450 IF BIT(Mhi,7) THEN Mhi≃BINEOR(Mhi,-256) ! Sign extend measure high byte 460 IF BIT(Shi,7) THEN Shi=BINEOR(Shi,-256) ! sign extend source high byte 470 ! Mask off range bits 480 Mr=BINAND(Mr,15) Reading(I,2)=-(65536*Mhi+256*Mmid+Mlo)*1.E-5*10^Mr ! Convert measure 490 Reading(I,1)=-(65536*Shi+256*Smid+Slo)*1.E-14*10^Sr ! Convert source 500

510 NEXT I 1 Loop back for next reading 520 Ymin=MAXREAL | Find minimum and maximum Vt 530 Ymax=~MAXREAL 540 FOR I=1 TO 100 IF Reading(I,2)<Ymin THEN Ymin=Reading(I,2) 550 560 IF Reading(I,2)>Ymax THEN Ymax=Reading(I,2) 570 NEXT I PRINT "Press CONT to display graph" 580 590 PRINT "Press CONT while in graph to return to BASIC" 600 PAUSE 610 OUTPUT KBD;CHR\$(255);CHR\$(75); ! Clear CRT 620 ! Initialize graphics GINIT 630 PLOTTER IS CRT, "INTERNAL" ! Define plot to CRT 640 GRAPHICS ON I Turn on graphics 650 MOVE 55,95 ! Title graph 660 LABEL "Vt VS. Id" 670 MOVE 70.10 ! Label X axis 680 LABEL "Id" 690 MOVE 0,53 ! Label Y axis 700 LABEL "Vt" 710 VIEWPORT 30,120,20,85 | Define soft clip limits 720 WINDOW -Istart,-Istop,Ymin,Ymax ! Scale graph X1=(Istart-Istop)/10 730 ! Compute X axis increment 740 ! Compute Y axis increment Y1=(Ymax-Ymin)/10 750 GRID X1*2,Y1*2,-Istart,Ymin ! Draw grid 76Ø AXES X1,Y1,-Istart,Ymin ! Add some tick marks 770 PLOT Reading(*) | Plot data 780 ! Define character size CSIZE 4 790 LORG 6 ! Center characters 800 CLIP OFF ! Turn off soft clipping 810 FOR I=-Istart TO -Istop+.01*(-Istep) STEP 2*X1 ! Number X axis 820 MOVE I, Ymin-(Y1/4) 830 LABEL USING "#,D.DESZ";I 840 NEXT I 850 FOR I=Ymin TO Ymax+.01*Y1 STEP Y1 ! number Y axis 860 MOVE -Istart-(1.3*X1),I+(.3*Y1) 870 LABEL USING "#,MDD.DDD";I 880 NEXT I 890 PAUSE 900 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Turn off alpha display 910 GRAPHICS OFF ! Turn off graphics display 920 END

REM LOG SWEEP SELF BIAS THRESHOLD VOLTAGE PROGRAM REV. 1.3 (Program 26) 10 20 REM INCLUDES BINARY TRANSFER AND PLOTTING OF Vt VS. Id 30 OPTION BASE 1 ! First array subscript is 1 40 DIM Reading(51,2) ! Dimension reading array 50 ASSIGN @D236 TO 716 ! Assign I/O path to 236 ASSIGN @Buf TO BUFFER [3000] | Assign I/O path to BUFFER 60 70 ! Clear both Units CLEAR 7 80 OUTPUT KBD; CHR\$(255); CHR\$(75); ! Clear screen 90 100 REMOTE 716 ! Put Unit 1 in remote 110 OUTPUT 716; "F1,1X" ! Source I, sweep mode 120 OUTPUT 716; "L10,2X" ! 10V compliance, 11V range 130 OUTPUT 716;"00Z0X" ! Local sense, suppress off 140 OUTPUT 716; "T1,0,0,0X" ! GET trigger,continuous 150 OUTPUT 716; "65,3,2X" ! Source,measure,binary data 160 ! SRQ on sweep done OUTPUT 716; "M2,X" 170 OUTPUT 716; "Y4S2PØX" ! Terminator off,line cycle,filter off ! Program 0 bias value 175 OUTPUT 716; "B0,0,0X" 180 ! Define -1nA start current Istart=-1.0E-9 ! Define -100uA stop current 190 Istop=-1.00E-4 200 Points=1 10 points per decade 210 Dly=200 ! Define 200msec Unit delay 220 OUTPUT 716; "Q2,"; Istart; ", "; Istop; ", "; Points; ", 0, "; Dly; "X" ! Pgm LOG swp 230 240 REMOTE 717 ! Put Unit 2 in remote 250 OUTPUT 717; "F0,0X" ! Source V, DC mode 260 OUTPUT 717; "01X" I Remote sensing 270 OUTPUT 717; "L100E-3,9X" ! 100mA compliance,100mA range 280 OUTPUT 717; "T1,0,0,0X" | Get trigger, continuous 290 Vds=-10 ! Define -10V Vds value 300 OUTPUT 717 ;"B";Vds;",3,";Dly;"X" ! Program DC, 110V range,delay 310 PRINT "Close lid, press CONT to begin test" 320 PAUSE 330 OUTPUT 716; "R1N1X" ! Arm Unit 1 trigger, turn on output 340 OUTPUT 717; "RINIX" I Arm Unit 2 trigger, turn on output 350 TRIGGER 717 ! Trigger Unit 2 TRIGGER 716 360 ! Trigger Unit 1 370 STATUS 7,7;Stat | Get bus status 380 IF NOT BIT(Stat,10) THEN 370 | Wait for SRQ 390 Stat=SPOLL(716) ! Serial poll Unit 1 to clear SRQ OUTPUT 716; "NØX" 400 ! Turn off Unit 1 output 410 ! Turn off Unit 2 output, local sense OUTPUT 717; "N000X" 420 TRANSFER @D236 TO @Buf;END,WAIT ! Fast transfer data to computer 430 ENTER @Buf USING "%,W";N ! Input reading count 440 FOR I=1 TO 51 I Loop for all readings 450 ENTER @Buf USING "%, B, B, B, B, B, B, B, B, B"; Sr, Shi, Smid, Slo, Mr, Mhi, Mmid, Mlo 460 IF BIT(Mhi,7) THEN Mhi=BINEOR(Mhi,-256) ! Sign extend measure high byte IF BIT(Shi,7) THEN Shi=BINEOR(Shi,-256) ! sign extend source high byte 470 480 Mr=BINAND(Mr,15) ! Mask off range bits 490 Reading(I,2)=-(65536*Mhi+256*Mmid+Mlo)*1.E-5*10^Mr ! Convert measure 500 Reading(I,1)=-(65536*Shi+256*Smid+Slo)*1.E-14*10^Sr ! Convert source

510 NEXT I ! Loop back for next reading ! Find minimum and maximum Vt 520 Ymin=MAXREAL 530 Ymax=-MAXREAL FOR I=1 TO 51 540 550 IF Reading(I,2)<Ymin THEN Ymin=Reading(I,2) IF Reading(I,2)>Ymax THEN Ymax=Reading(I,2) 560 570 NEXT I 580 FOR I=1 TO 51 ! Find LOG of source data 590 Reading(I,1)=LGT(Reading(I,1)) 600 NEXT I ! Find LOG of min X axis value Xmin=LGT(ABS(Istart)) 610 Xmax=LGT(ABS(Istop)) ! Find LOG of max X axis value 620 630 PRINT "Press CONT to display graph" PRINT "Press CONT while in graph to return to BASIC" 640 650 PAUSE OUTPUT KBD; CHR\$(255); CHR\$(75); | Clear CRT 660 ! Initialize graphics 670 GINIT | Define plot to CRT 680 PLOTTER IS CRT, "INTERNAL" ! Turn on graphics 690 GRAPHICS ON 700 MOVE 55,95 ! Title graph LABEL "Vt VS. Id" 710 720 ! Label X axis MOVE 70,10 730 LABEL "Id" 740 ! Label Y axis MOVE 0,53 LABEL "Vt" 750 VIEWPORT 30,120,20,85 WINDOW Xmin,Xmax,Ymin,Ymax ! Define soft clip limits 760 ! Scale graph 770 780 X1=(Xmax-Xmin)/10 ! Compute X axis increment 790 Y1=(Ymax-Ymin)/10 ! Compute Y axis increment GRID X1*2, Y1*2, Xmin, Ymin ! Draw grid 800 810 PLOT Reading(*) | Plot data ! Center characters 820 LORG 6 CLIP OFF ! Turn off soft clipping 830 FOR I=Xmin TO Xmax+.01*(X1) STEP 2*X1 ! Number X axis 840 850 CSIZE 4.5 MOVE I, Ymin-(Y1/3) 860 870 LABEL "10" CSIZE 3 880 890 MOVE I+.5*X1,Ymin-(Y1/8) LABEL USING "#,K";I 900 NEXT I 910 920 CSIZE 4 FOR I=Ymin TO Ymax+.01*Y1 STEP 2*Y1 ! number Y axis 930 940 MOVE Xmin-(1.3*X1), I+(.3*Y1) LABEL USING "#,MDD.DDD";I 950 960 NEXT I 970 PAUSE OUTPUT KBD;CHR\$(255);CHR\$(75); ! Turn off alpha display 980 990 GRAPHICS OFF ! Turn off graphics display 1000 END

APPENDIX A Converting Applications Programs to QuickBASIC for IBM-PC Computers

INTRODUCTION

This appendix contains information on converting the applications programs in this manual to Microsoft QuickBASIC for use with IBM-PC AT and compatible computers.. Example programs are also included to demonstrate the process.

Computer Hardware Requirements

The following computer hardware is recommended:

- IBM-PC AT or compatible computer.
- EGA graphics adapter and monitor.
- IOtech Personal488, CEC PC-488, or National Instruments PC-II or PC-IIA IEEE-488 interface for the computer.

Computer Software Requirements

The following software is necessary:

- MS-DOS or PC-DOS version 3.30 or later.
- Microsoft QuickBASIC BASIC compiler, version 4.0 or later.
- Capital Equipment Corp. CEC-GRAPH graphics software, version 1.7 or later.
- IOtech Driver488 IEEE-488 bus driver, Rev. 2.3 or later.

Hardware/Software Installation

Make sure the IEEE-488 interface and Driver488 software driver are installed per manufacturer's recommendations. The board base I/O address, DMA and interrupt status, and board clock frequency must agree with the corresponding driver software settings.

Compiling and Linking Procedure

Follow the general procedure below to make an executable program from a program source listing.

- 1. Copy the CEC-GRAPH GRAPHQB.OBJ and GRPKG.OBJ files to your QuickBASIC working diskette or subdirectory.
- 2. Enter the QuickBASIC editor, and type in the desired program.
- 3. After checking for errors, save the source listing under a convenient filename, then exit the editor.
- 4. Compile the program by typing in the following:

BC Filename <Enter>

Here, Filename is the name of the file assigned in step 3. Fix any errors that occur, and recompile if necessary.

5. Link the files to make an executable by typing in the following:

LINK Filename GRAPHQB GRPKG <Enter>

Be sure to specify the BCOM library at the .LIB prompt if you wish to make a stand-alone executable. Note that you should not include GRAPHQB and GRPKG in the name list for programs that do not include plotting routines.

6. After linking, the program is ready to run. From the DOS prompt, simply type in the name of the program.

Running in the QuickBASIC Environment

Instead of separately compiling and linking, you can also run a program while in the QuickBASIC environment. To do so, you must add a DECLARE SUB statement for each CEC-GRAPH CALL used in the program, for example:

DECLARE SUB GRAPHXY DECLARE SUB SCREENMODE Declarations should be added at the front of each program as appropriate.

In addition, you must also load the GRAPHQB.LIB module when entering the editor as follows:

QB /L GRAPHQB <Enter>

You can then type in or load your program as usual.

Press shift F5 while in the editor to run a program.

Example Programs

The sample listings on the following pages are the translated versions of six example programs throughout this manual. The programs and reference areas of the manual are:

Program A-1, Diode Characterization: paragraph 2.6. Program A-2, I_{CEO} Measurement: paragraph 3.7. Program A-3, Common-emitter Test: paragraph 3.4. Program A-4, Common-source Test: paragraph 4.4. Program A-5, Self-bias Threshold Test: paragraph 8.5. Program A-6, Gummel Plot: paragraph 3.5.

Example Plots

Figure A-1 through Figure A-6 show the example plots from the QuickBASIC example programs in this appendix. Figure A-1 was generated using an HPGL plotter, while Figure A-2 through Figure A-6 are printer graphics dumps generated with the aid of the DOS GRAPHICS command. In order to use GRAPHICS.COM, you should modify the corresponding program for SCREENMODE 6 and SCREEN 2 in order to support CGA graphics.

```
' DIODE CHARACTERIZATION PROGRAM, QUICKBASIC VERSION REV. 1.3 (Program A-1)
OPEN "\DEV\IEEEOUT" FOR OUTPUT AS #1 ' Open IEEE-488 output path.
OPEN "\DEV\IEEEIN" FOR INPUT AS #2
                                          ' Open IEEE-488 input path.
IOCTL #1, "BREAK"
PRINT #1, "RESET"
                                          ' Reset interface.
                                           ' Warm start interface
PRINT #1, "CLEAR"
                                           ' Send device clear.
PRINT #1, "REMOTE 16"
                                            ' Put 236 in remote.
                                            ' Clear CRT.
CLS
OPTION BASE 1
DIM RX(101), RY(101)
                                           ' Dimension reading arrays.
PRINT #1, "OUTPUT 16;F1,1X"
                                          ' Source I, sweep mode.
PRINT #1, "OUTPUT 16;00T1,0,0,0X"
PRINT #1, "OUTPUT 16;L1,1X"

' Local sense, trigger on GET.
' 1V compliance, 1.1V range.
' Source, measure, no prefix, sweep data.

PRINT #1, "OUTPUT 16;G5,2,1X"
PRINT #1, "OUTPUT 16;M2,X"
                                          ' SRQ on sweep done.
PRINT #1, "OUTPUT 16;B0,0,0X"
PRINT #1, "OUTPUT 16;Z1X"
                                          ' Program O bias value.
                                            ' Enable suppress
Istart = 0: Istop = .0001: Istep = .000001 ' Define current parameters.
                                           ' Define 10msec delay.
Delay = 10
PRINT #1, "OUTPUT 16;Q1,"; Istart; ","; Istop; ","; Istep; ",0,"; Delay; "X"
PRINT "Close lid, press any key to begin."
DO WHILE INKEY$ = "": LOOP
                                            ' Wait for keypress.
PRINT #1, "OUTPUT 16;R1N1X"
PRINT #1, "TRIGGER 16"
                                          ' Arm sweep, turn on 236 output.
                                            ' Trigger sweep.
WaitForSRQ: PRINT #1, "STATUS"
                                            ' Get bus status.
                                           ' Input status string.
INPUT #2, ST$
IF MID(ST, 11, 2) = "SO" THEN GOTO WaitForSRQ ' Wait for SRQ.
PRINT #1, "SPOLL 16"
                                            ' Serial poll 236 to clear SRQ.
INPUT #2, SB
PRINT #1, "OUTPUT 16;NOX"
                                            ' Turn off 236 output.
FOR I = 1 TO 101
                                           ' Loop for all 101 readings.
PRINT #1, "ENTER 16"
                                            ' Address 236 to talk.
INPUT #2, RX(I), RY(I)
                                          ' Input current and voltage readings.
                                          ' Loop back for next reading.
NEXT I
                                            ' Close I/O files.
CLOSE 1: CLOSE 2
PRINT "Press key to display graph."
PRINT "Press key while in graph to end program."
DO WHILE INKEY$ = "": LOOP
                                           ' Wait for keypress.
DO WHILE INKEYS = "": LOOP' Wait for Ititle$ = "DIODE TEST PROGRAM PLOT"' Plot data
CALL SCREENMODE(16)
SCREEN 9
CALL GRAPHXY(SEG RX(1), SEG RY(1), 101, 1, "If", 1, "Vf", title$, 1, 0, 2)
DO WHILE INKEYS = "": LOOP
END
```

'BIPOLAR TRANSISTOR LEAKAGE TEST, QUICKBASIC VERSION. REV. 1.3 (Program A-2) OPEN "\DEV\IEEEOUT" FOR OUTPUT AS #1 ' Open IEEE-488 output path. OPEN "\DEV\IEEEIN" FOR INPUT AS #2 ' Open IEEE-488 input path. IOCTL #1, "BREAK" ' Reset interface. PRINT #1, "RESET" ' Warm start interface PRINT #1, "CLEAR" ' Send device clear. PRINT #1, "REMOTE 16" ' Put unit in remote. CLS ' Clear CRT. OPTION BASE 1 DIM RX(101), RY(101) ' Dimension reading arrays. DIM RX(101), RY(101)' Dimension reading arrays.PRINT #1, "OUTPUT 16;F0,1X"' Source V, sweep mode.PRINT #1, "OUTPUT 16;00T1,0,0,0X"' Local sense, trigger on GET.PRINT #1, "OUTPUT 16;L1E-3,0X"' ImA compliance,autorange measure. PRINT #1, "OUTPUT 16;G5,2,1X" PRINT #1, "OUTPUT 16;M2,X" PRINT #1, "OUTPUT 16;S2X" ' Source, measure, no prefix, sweep. ' SRQ on sweep done. ' Line cycle integration. ' Program O bias value. PRINT #1, "OUTPUT 16;B0,0,0X" PRINT #1, "OUTPUT 16;Z1X" ' Enable suppress. Vstart = 0: Vstop = 10: Vstep = .1 ' Define voltage sweep parameters. ' Define 100msec delay. Delay = 100PRINT #1, "OUTPUT 16;Q1,"; Vstart; ","; Vstop; ","; Vstep; ",0,"; Delay; "X" PRINT "Close lid, press any key to begin." DO WHILE INKEYS = "": LOOP PRINT #1, "OUTPUT 16;R1N1X" PRINT #1, "TRIGGER 16" ' Wait for keypress. ' Arm sweep, turn on 236 output. ' Trigger sweep. WaitForSRQ: PRINT #1, "STATUS" ' Get bus status. ' Input status string. INPUT #2, ST\$ IF MID\$(ST\$, 11, 2) = "SO" THEN GOTO WaitForSRQ ' Wait for SRQ. PRINT #1, "SPOLL 16" ' Serial poll 236 to clear SRQ. INPUT #2, SB PRINT #1, "OUTPUT 16;NOX" ' Turn off 236 output. FOR I = 1 TO 101 ' Loop for all 101 readings. PRINT #1, "ENTER 16" ' Address 236 to talk. INPUT #2, RX(I), RY(I) ' Input voltage and current readings. ' Loop back for next reading. NEXT I CLOSE 1: CLOSE 2 ' Close I/O files. PRINT "Press key to display graph." PRINT "Press key while in graph to end program." DO WHILE INKEY\$ = "": LOOP ' Wait for keypress. title\$ = "Iceo vs. Vceo": xaxis\$ = "Vceo": yaxis\$ = "Iceo"' Plot data X% = 1: Y% = 1: SYMBOL% = 0: NUM% = 101: PEN.NUM% = 2: LIN% = 1: MODE% = 16 CALL GRID(1) CALL SCREENMODE(MODE%) SCREEN 9 CALL GRAPHXY(SEG RX(1), SEG RY(1), NUM%, X%, xaxis\$, Y%, yaxis\$, title\$, LIN%, SYMBOL %, PEN.NUM%) DO WHILE INKEYS = "": LOOP END

'COMMON-EMITTER TEST PROGRAM, QUICKBASIC VERSION. REV. 1.3 (Program A-3) OPEN "\DEV\IEEEOUT" FOR OUTPUT AS #1 ' Open IEEE-488 output path. OPEN "\DEV\IEEEIN" FOR INPUT AS #2 ' Open IEEE-488 input path. IOCTL #1, "BREAK" ' Reset interface. PRINT #1, "RESET" ' Warm start interface PRINT #1, "CLEAR" ' Send device clear. PRINT #1, "REMOTE 16,17" ' Put units in remote. CLS ' Clear CRT. OPTION BASE 1 DIM R(5, 101, 2), RX(101), RY(101) ' Dimension reading arrays. PRINT #1, "OUTPUT 16;F1,1X" ' Source I, sweep mode. ' Source 1, succe 1 ' 1V compliance, 1.1V range. ' Local sense PRINT #1, "OUTPUT 16;L1,1X" PRINT #1, "OUTPUT 16;00X"' Local sensePRINT #1, "OUTPUT 16;T1,1,2,0X"' Output trigger on end of delay.PRINT #1, "OUTPUT 16;B0,0,0X"' Program 0 bias value Istart = .00001: Istop = .00005: Istep = .00001 ' Define sweep parameters. ' 100msec delay. Delay = 100PRINT #1, "OUTPUT 16;Q1,"; Istart; ","; Istop; ","; Istep; ",O,"; Delay; "X" PRINT #1, "OUTPUT 17;F0,1X" ' Source V, sweep mode. PRINT #1, "OUTPUT 17;00X" PRINT #1, "OUTPUT 17;L100E-3,0X" ' Local sensing. ' 100mA compliance, autorange measure. PRINT #1, "OUTPUT 17;G5,2,1X" ' Source, measure, no prefix. ' Trigger on external. ' SRQ on sweep done. ' Program O bias value ' Enable suppress PRINT #1, "OUTPUT 17;T3,0,0,0X" PRINT #1, "OUTPUT 17;M2,X" PRINT #1, "OUTPUT 17;B0,0,0X" PRINT #1, "OUTPUT 17;Z1X" Vstart = 0: Vstop = 10: Vstep = .1 ' Define sweep parameters. PRINT #1, "OUTPUT 17;Q1,"; Vstart; ","; Vstop; ","; Vstep; ",0,"; Delay; "X" PRINT "Close lid, press any key to begin" DO WHILE INKEY\$ = "": LOOP PRINT #1, "OUTPUT 16;R1N1X" PRINT #1, "OUTPUT 17;R1N1X" ' Arm Unit 1, turn on output. ' Arm Unit 2, turn on output. FOR I = 1 TO 5 ' Loop for all 5 sweeps. PRINT "Generating sweep"; I PRINT #1, "TRIGGER 16" ' Trigger Unit 1. WaitForSRQ: PRINT #1, "STATUS" ' Get bus status. INPUT #2, ST\$ IF MID\$(ST\$, 11, 2) = "SO" THEN GOTO WaitForSRQ ' Wait for SRQ. PRINT #1, "SPOLL 17" ' Serial poll Unit 2 to clear SRQ. INPUT #2, SB FOR J = 1 TO 101 ' Loop for all 101 readings. PRINT #1, "ENTER 17" ' Address Unit 2 to talk. INPUT #2, R(I, J, 1), R(I, J, 2) ' Get Vce and Ic data from Unit 2. NEXT J ' Loop back for next reading. ' Loop back for next sweep. NEXT I PRINT #1, "OUTPUT 16;NOX" PRINT #1, "OUTPUT 17;NOX" ' Turn off Unit 1 output. ' Turn off Unit 2 output. CLOSE 1: CLOSE 2 ' Close I/O files. PRINT "Press any key to display graph." PRINT "Press any key while in graph to end program." DO WHILE INKEY\$ = "": LOOP

```
Y_{min} = 1E+32: Y_{max} = -1E+32
                                         ' Find maximum and minimum Ic.
FOR I = 1 TO 5
FOR J = 1 TO 101
IF R(I, J, 2) < Ymin THEN Ymin = R(I, J, 2)
IF R(I, J, 2) > Ymax THEN Ymax = R(I, J, 2)
NEXT J, I
title$ = "COMMON-EMITTER CHARACTERISTICS" ' Plot data.
xaxis$ = "Vce": yaxis$ = "Ic"
X% = 1: Y% = 1: SYMBOL% = 0: NUM% = 101: PEN.NUM% = 2: LIN% = 1: mode% = 16
CALL SCREENMODE(mode%)
SCREEN 9
Xmin = 0!: Xmax = 10!
CALL SCALE(Xmin, Ymin, Xmax, Ymax)
FOR I = 1 TO 5
                                         ' Loop for all five curves.
                                          .
FOR J = 1 TO 101
RX(J) = R(I, J, 1): RY(J) = R(I, J, 2) ' Transfer readings to plot arrays.
NEXT J
                                         ' Loop back for next data point.
IF I = 2 THEN X\% = 0: Y\% = 0
                                         ' No axes after first curve.
CALL GRAPHXY(SEG RX(1), SEG RY(1), NUM%, X%, xaxis$, Y%, yaxis$, title$, LIN%, SYMBOL
%, PEN.NUM%)
NEXT I
                                         ' Loop back for next curve.
DO WHILE INKEY$ = "": LOOP
END
```

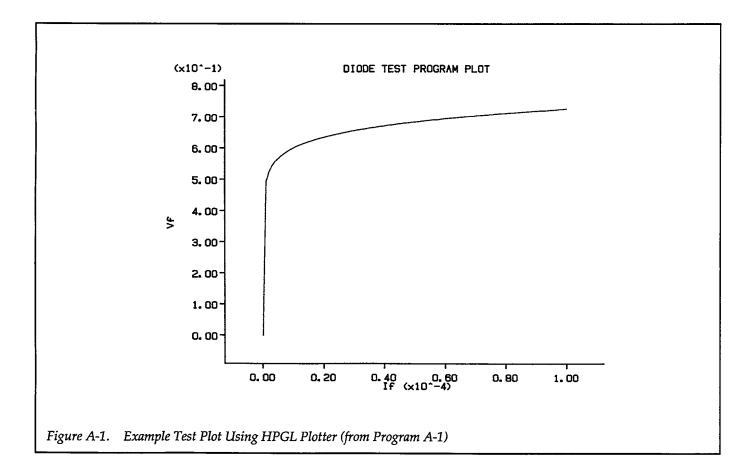
```
'COMMON-SOURCE TEST PROGRAM, QUICKBASIC VERSION. REV. 1.3 (Program A-4)
OPEN "\DEV\IEEEOUT" FOR OUTPUT AS #1
                                      ' Open IEEE-488 output path.
OPEN "\DEV\IEEEIN" FOR INPUT AS #2
                                       ' Open IEEE-488 input path.
IOCTL #1, "BREAK"
                                       ' Reset interface.
PRINT #1, "RESET"
PRINT #1, "CLEAR"
                                       ' Warm start interface
                                       ' Send device clear.
PRINT #1, "REMOTE 16,17"
                                       ' Put units in remote.
CLS
                                       ' Clear CRT.
OPTION BASE 1
DIM R(5, 101, 2), RX(101), RY(101) 'Dimension reading arrays.
PRINT #1, "OUTPUT 16;F0,1X"
PRINT #1, "OUTPUT 16;L1E-3,7X"
PRINT #1, "OUTPUT 16;OOT1,1,2,0X"
PRINT #1, "OUTPUT 16;F0,1X"
                                      ' Source V, sweep mode.
                                      ' 1mA compliance,1mA range.
                                      ' Local sense, out trig end of delay.
PRINT #1, "OUTPUT 16;B0,0,0X"
                                      ' Program O bias.
Vgstart = -2: Vgstop = 0: Vgstep = .5 ' Define sweep parameters.
Delay = 10
                                       ' lOmsec delay.
PRINT #1, "OUTPUT 16;Q1,"; Vgstart; ","; Vgstop; ","; Vgstep; ",0,"; Delay; "X"
PRINT #1, "OUTPUT 17;F0,1X"
                                       ' Source V, sweep mode.
PRINT #1, "OUTPUT 17;00X"
                                       ' Local sensing.
PRINT #1, "OUTPUT 17;L100E-3,0X"
                                       ' 100mA compliance, autorange measure.
PRINT #1, "OUTPUT 17;G5,2,1X"
                                      ' Source, measure, no prefix.
PRINT #1, "OUTPUT 17;M2,T3,0,0,0X"
                                     ' SRQ, trigger on external.
PRINT #1, "OUTPUT 17; B0, 0, 0X"
                                      ' Program O bias.
PRINT #1, "OUTPUT 17; Z1X"
                                       ' Enable suppress
Vdstart = 0: Vdstop = 10: Vdstep = .1 ' Define sweep parameters.
PRINT #1, "OUTPUT 17;Q1,"; Vdstart; ","; Vdstop; ","; Vdstep; ",0,"; Delay; "X"
PRINT "Close lid, press any key to begin"
DO WHILE INKEYS = "": LOOP
PRINT #1, "OUTPUT 16;R1N1X"
PRINT #1, "OUTPUT 17;R1N1X"
                                      ' Arm Unit 1, turn on output.
                                       ' Arm Unit 2, turn on output.
                                       ' Loop for all 5 sweeps.
FOR I = 1 TO 5
PRINT "Generating sweep"; I
PRINT #1, "TRIGGER 16"
                                       ' Trigger Unit 1.
WaitForSRQ: PRINT #1, "STATUS"
                                      ' Get bus status.
INPUT #2, ST$
IF MID$(ST$, 11, 2) = "SO" THEN GOTO WaitForSRQ ' Wait for SRQ.
PRINT #1, "SPOLL 17"
                                       ' Serial poll Unit 2 to clear SRQ.
INPUT #2, SB
                                       ' Loop for all 101 readings.
FOR J = 1 TO 101
PRINT #1, "ENTER 17"
                                       ' Address Unit 2 to talk.
INPUT #2, R(I, J, 1), R(I, J, 2)
                                      ' Get Vce and Ic data from Unit 2.
NEXT J
                                       ' Loop back for next reading.
NEXT I
                                       ' Loop back for next sweep.
PRINT #1, "OUTPUT 16;NOX"
                                       ' Turn off Unit 1 output.
PRINT #1, "OUTPUT 17;NOX"
                                       ' Turn off Unit 2 output.
                                       ' Close I/O files.
CLOSE 1: CLOSE 2
PRINT "Press any key to display graph."
PRINT "Press any key while in graph to end program."
DO WHILE INKEY$ = "": LOOP
Ymin = 1E+32: Ymax = -1E+32 'Find maximum and minimum Id.
FOR I = 1 TO 5
```

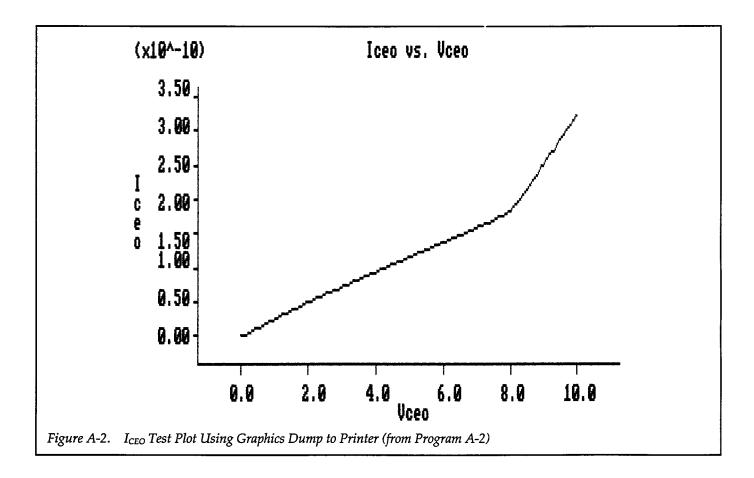
```
FOR J = 1 TO 101
IF R(I, J, 2) < Ymin THEN Ymin = R(I, J, 2)
IF R(I, J, 2) > Ymax THEN Ymax = R(I, J, 2)
NEXT J, I
Xmin = 0!: Xmax = 10!
CALL SCALE(Xmin, Ymin, Xmax, Ymax)
title$ = "COMMON-SOURCE CHARACTERISTICS" ' Plot data.
xaxis$ = "Vds": yaxis$ = "Id"
X% = 1: Y% = 1: SYMBOL% = 0: NUM% = 101: PEN.NUM% = 2: LIN% = 1: MODE% = 16
CALL SCREENMODE(MODE%)
SCREEN 9
FOR I = 1 TO 5
                                         ' Loop for all five curves.
FOR J = 1 TO 101
RX(J) = R(I, J, 1): RY(J) = R(I, J, 2) ' Transfer readings to plot arrays.
NEXT J
                                        ' Loop back for next data point.
IF I = 2 THEN X\% = 0: Y\% = 0
                                        ' Axes on first curve only.
CALL GRAPHXY(SEG RX(1), SEG RY(1), NUM%, X%, xaxis$, Y%, yaxis$, title$, LIN%, SYMBOL
%, PEN.NUM%)
NEXT I
                                         ' Loop back for next curve.
DO WHILE INKEY$ = "": LOOP
END
```

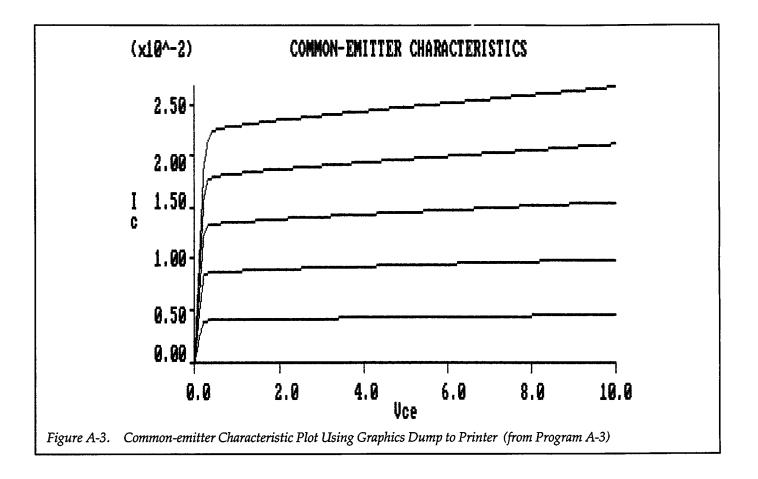
```
'LOG SWEEP SELF BIAS THRESHOLD VOLTAGE, QUICKBASIC VER. REV. 1.3 (Pgm. A-5)
OPEN "\DEV\IEEEOUT" FOR OUTPUT AS #1
                                       ' Open IEEE-488 output path.
OPEN "\DEV\IEEEIN" FOR INPUT AS #2
                                        ' Open IEEE-488 input path.
IOCTL #1, "BREAK"
                                       ' Reset interface.
PRINT #1, "RESET"
                                       ' Warm start interface
PRINT #1, "CLEAR"
                                       ' Send device clear.
PRINT #1, "REMOTE 16,17"
                                       ' Put units in remote.
CLS
                                       ' Clear CRT.
OPTION BASE 1
DIM RX(51), RY(51)
                                       ' Dimension reading arrays.
PRINT #1, "OUTPUT 16;F1,1X"
                                       ' Source I, sweep mode.
PRINT #1, "OUTPUT 16;L10,2X"
                                       ' 10V compliance, 11V range.
PRINT #1, "OUTPUT 16;00T1,0,0,0X"
                                       ' Local sense, out trig end of delay.
PRINT #1, "OUTPUT 16;B0,0,0X"
PRINT #1, "OUTPUT 16;G5,2,1X"
                                       ' Program O bias value.
                                       ' Source, measure, no prefix, sweep data.
PRINT #1, "OUTPUT 16;S2POX"
                                       ' Line cycle integration, filter off.
PRINT #1, "OUTPUT 16;B0,0,0X"
                                       ' Program O bias value.
PRINT #1, "OUTPUT 16;M2,OZOX"
                                      ' SRQ on sweep done, suppress off.
Istart = -1E-09: Istop = -.0001: Points = 1' Define sweep parameters.
Delay = 200
                                       ' Define 200msec delay.
PRINT #1, "OUTPUT 16;Q2,"; Istart; ","; Istop; ","; Points; ",0,"; Delay; "X"
PRINT #1, "OUTPUT 17;F0,0X"
                                       ' Source V, DC mode.
PRINT #1, "OUTPUT 17;01X"
                                       ' Remote sensing.
PRINT #1, "OUTPUT 17;L100E-3,9X"
PRINT #1, "OUTPUT 17;T1,0,0,0X"
                                       ' 100mA compliance, 100mA range.
                                       ' Trigger on GET.
                                       ' Define -10V Vds value.
Vds = -10
PRINT #1,"OUTPUT 17;B"; Vds; ",3,"; Delay; "X" ' Program DC, 110V range,delay
PRINT "Close lid, press any key to begin"
DO WHILE INKEY$ = "": LOOP
PRINT #1, "OUTPUT 16;R1N1X"
                                       ' Arm Unit 1, turn on output.
PRINT #1, "OUTPUT 17;R1N1X"
                                       ' Arm Unit 2, turn on output.
PRINT #1, "TRIGGER 17"
                                       ' Trigger Unit 2.
PRINT #1, "TRIGGER 16"
                                       ' Trigger Unit 1.
WaitForSRQ: PRINT #1, "STATUS"
                                       ' Get bus status.
INPUT #2, ST$
IF MID$(ST$, 11, 2) = "SO" THEN GOTO WaitForSRQ ' Wait for SRQ.
PRINT #1, "SPOLL 16"
                                       ' Serial poll Unit 1 to clear SRQ.
INPUT #2, SB
FOR I = 1 TO 51
                                       ' Loop for all 51 readings.
PRINT #1, "ENTER 16"
                                       ' Address Unit 1 to talk.
                                       ' Get -Id and -Vt data from Unit 1.
INPUT #2, RX(I), RY(I)
RX(I) = ABS(RX(I)); RY(I) = -RY(I)
                                       ' Sign adjust Id and Vt.
NEXT I
                                        ' Loop back for next reading.
PRINT #1, "OUTPUT 16;NOX"
                                        ' Turn off Unit 1 output.
PRINT #1, "OUTPUT 17;NOOOX"
                                       ' Turn off Unit 2 output, local sense.
CLOSE 1: CLOSE 2
                                        ' Close I/O files.
PRINT "Press any key to display graph."
PRINT "Press any key while in graph to end program."
DO WHILE INKEYS = "": LOOP
title$ = "Vt vs. Id"
                                       ' Plot data.
xaxis$ = "Id": yaxis$ = "Vt"
```

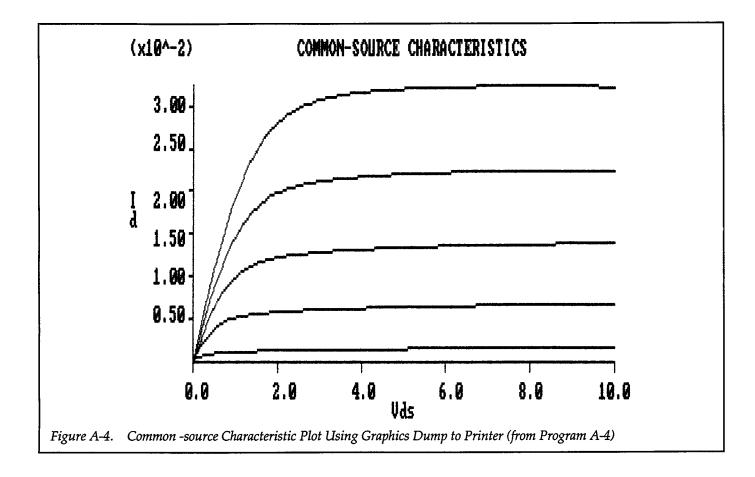
'GUMMEL PLOT TEST PROGRAM, QUICKBASIC VERSION REV. 1.3 (Program A-6) OPEN "\DEV\IEEEOUT" FOR OUTPUT AS #1 ' Open IEEE-488 output path. OPEN "\DEV\IEEEIN" FOR INPUT AS #2 ' Open IEEE-488 input path. IOCTL #1, "BREAK" ' Reset interface. PRINT #1, "RESET" ' Warm start interface PRINT #1, "CLEAR" ' Send device clear. PRINT #1, "REMOTE 16,17" ' Put units in remote. CLS ' Clear CRT. **OPTION BASE 1** DIM R(71, 3), RX(71), RY(71) ' Dimension reading arrays. PRINT #1, "OUTPUT 16;F0,1X" ' Source V, sweep mode. PRINT #1, "OUTPUT 16;L1E-3,OX" ' 1mA compliance, autorange measure. PRINT #1, "OUTPUT 16;00T3,4,2,0X" ' Local sense, ext trig end of delay. PRINT #1, "OUTPUT 16;G5,2,1X" ' Source, measure, no prefix, sweep data. PRINT #1, "OUTPUT 16;S2ZOX" ' Line cycle integration, suppress off. PRINT #1, "OUTPUT 16;B0,0,0X" ' Program O bias value. ' Define sweep parameters. Vstart = .7: Vstop = 0!: Vstep = -.01' 10msec delay. Delay = 10PRINT #1, "OUTPUT 16;Q1,"; Vstart; ","; Vstop; ","; Vstep; ",0,"; Delay; "X" PRINT #1, "OUTPUT 17;F0,1X" ' Source V, sweep mode. PRINT #1, "OUTPUT 17;00X" ' Local sensing. PRINT #1, "OUTPUT 17;L100E-3,OX" ' 100mA compliance, autorange measure. PRINT #1, "OUTPUT 17;G4,2,1X" ' Measure, no prefix. PRINT #1, "OUTPUT 17;T3,1,4,0X" ' Trigger on external. PRINT #1, "OUTPUT 17;B0,0,0X" ' Program O bias value. PRINT #1, "OUTPUT 17;S2ZOX" ' Line cycle integration, suppress off. ' Define 10V constant Vce. Vce = 10PRINT #1, "OUTPUT 17;Q0,"; Vce; ",0,"; Delay; ",71X" ' Program sweep. PRINT "Close lid, press any key to begin" DO WHILE INKEY\$ = "": LOOP PRINT #1, "OUTPUT 16;R1N1X" ' Arm Unit 1, turn on output. PRINT #1, "OUTPUT 17;R1N1X" ' Arm Unit 2, turn on output. PRINT #1, "OUTPUT 16;HOX" ' Trigger Unit 1. FOR I = 71 TO 1 STEP -1' Loop for all 71 readings. ' Address Unit 1 to talk. PRINT #1, "ENTER 16" INPUT #2, R(I, 1), R(I, 2) ' Input Vbe and Ib from Unit 1. PRINT #1, "ENTER 17" ' Address Unit 2 to talk. INPUT #2, R(I, 3) ' Input Ic from Unit 2. IF R(I, 2) < 1E-14 THEN R(I, 2) = 1E-14' Set Ib noise floor. IF R(I, 3) < 1E-14 THEN R(I, 3) = 1E-14 'Set Ic noise floor. ' Loop for next readings. NEXT I PRINT #1, "OUTPUT 16;NOX" ' Put Unit 1 in standby. PRINT #1, "OUTPUT 17;NOX" ' Put Unit 2 in standby. ' Close I/O files. CLOSE 1: CLOSE 2 PRINT "Press any key to display graph." PRINT "Press any key while in graph to end program." DO WHILE INKEYS = "": LOOP $Y_{min} = 1E+32$: $Y_{max} = -1E+32$ ' Find maximum Ic and minimum Ib. FOR I = 1 TO 71 IF R(I, 2) < Ymin THEN Ymin = R(I, 2)IF R(I, 3) > Ymax THEN Ymax = R(I, 3)

```
NEXT I
Xmin = Vstop: Xmax = Vstart
CALL LOGAXIS(0, 1)
                                         ' Log on Y axis only.
CALL SCALE(Xmin, Ymin, Xmax, Ymax)
                                         ' Scale graph.
title$ = "Ib, Ic vs. Vbe"
                                         ' Plot data.
xaxis$ = "Vbe": yaxis$ = "Ib & Ic"
X% = 1: Y% = 1: SYMBOL% = 0: NUM% = 71: PEN.NUM% = 2: LIN% = 1: MODE% = 16
CALL SCREENMODE(MODE%)
SCREEN 9
FOR I = 2 TO 3
                                         ' Loop for Ib and Ic curves.
FOR J = 1 TO 71
RX(J) = R(J, 1): RY(J) = R(J, I)
                                         ' Transfer readings to plot arrays.
NEXT J
                                         ' Loop back for next data point.
IF I = 3 THEN X\% = 0: Y\% = 0
                                         ' Axes on first curve only.
CALL GRAPHXY(SEG RX(1), SEG RY(1), NUM%, X%, xaxis$, Y%, yaxis$, title$, LIN%, SYMBOL
%, PEN.NUM%)
NEXT I
                                         ' Loop back for next curve.
DO WHILE INKEY$ = "": LOOP
END
```

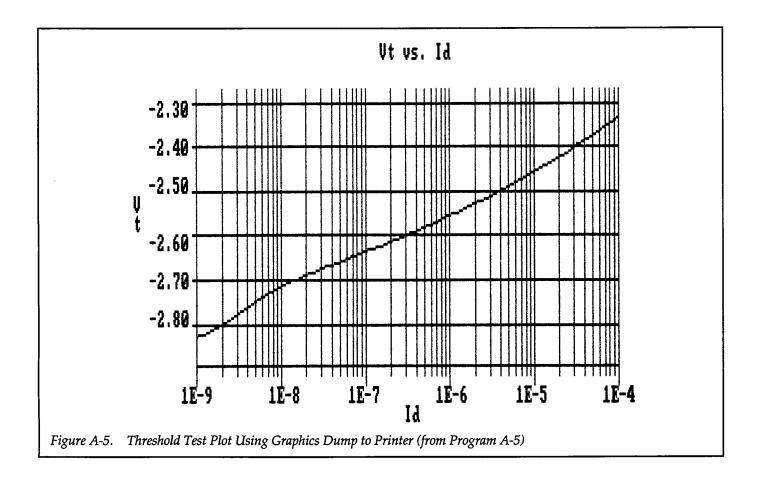


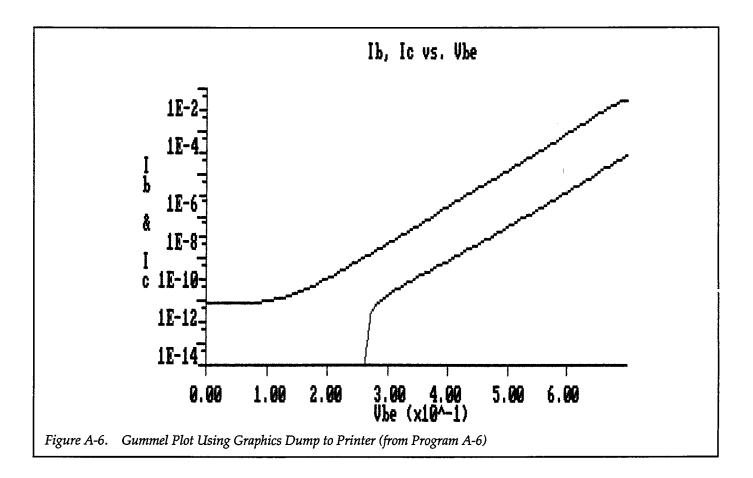






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